

# Lecture #3: Nondeterministic Finite Automata

## Key Concepts

**Definition 1.** A *nondeterministic finite automaton* is a 5-tuple  $(Q, \Sigma, \delta, q_0, F)$ , where

- $Q$  is a finite, nonempty, set of **states**;
- $\Sigma$  is an **alphabet** such that  $Q \cap \Sigma = \emptyset$ ;
- $\delta : Q \times \Sigma_\lambda \rightarrow \mathcal{P}(Q)$  is a **transition function**;
- $q_0 \in Q$  is the **start state**; and
- $F \subseteq Q$  is the set of **accept states**.

Here,  $\Sigma_\lambda = \Sigma \cup \{\lambda\}$  and  $\delta$  is a **total** function from  $Q \times \Sigma_\lambda$  to  $\mathcal{P}(Q)$ .

**Definition 2.** Let  $M = (Q, \Sigma, \delta, q_0, F)$  be a nondeterministic finite automaton. Then, for  $q \in Q$ ,  $Cl_\lambda(q)$  is the **set of states** that reachable from  $q$  by following **zero or more**  $\lambda$ -transitions.

$Cl_\lambda(q)$  is sometimes called the  **$\lambda$ -closure** of the state  $q$ .

**Definition 3.** Let  $M = (Q, \Sigma, \delta, q_0, F)$ . The **extended transition function** of  $M$  is the total function

$$\delta^* : Q \times \Sigma^* \rightarrow \mathcal{P}(Q)$$

such that, for  $q \in Q$  and  $\omega \in \Sigma^*$ ,

$$\delta^*(q, \omega) = \begin{cases} Cl_\lambda(q) & \text{if } \omega = \lambda, \\ \bigcup_{r \in \delta^*(q, \mu)} \left( \bigcup_{s \in \delta(r, \sigma)} Cl_\lambda(s) \right) & \text{if } \omega = \mu \cdot \sigma \text{ for } \mu \in \Sigma^* \text{ and } \sigma \in \Sigma. \end{cases}$$

**Definition 4.** Let  $M = (Q, \Sigma, \delta, q_0, F)$  be a nondeterministic finite automaton. Then, for every string  $\omega \in \Sigma^*$ ,  $M$  **accepts**  $\omega$  if

$$\delta^*(q_0, \omega) \cap F \neq \emptyset$$

and  $M$  **rejects**  $\omega$  otherwise.

**Definition 5.** Let  $M = (Q, \Sigma, \delta, q_0, F)$ . Then the **language** of  $M$ ,  $L(M)$ , is the set of strings  $\omega \in \Sigma^*$  such that  $M$  accepts  $\omega$ .

The lecture also presented a proof of the following.

**Claim 6.** For every alphabet  $\Sigma$  and for every language  $L \subseteq \Sigma^*$ , the following are equivalent:

- (a)  $L$  is a **regular language**. That is,  $L$  is the language of a **deterministic finite automaton**.
- (b)  $L$  is the language of a **nondeterministic finite automaton**.

*Sketch of Proof.* To prove that (a)  $\Rightarrow$  (b), one should consider an arbitrarily chosen alphabet  $\Sigma$  and language  $L \subseteq \Sigma^*$ . If  $L$  is a regular language then there exists a **deterministic finite automaton**

$$M = (Q, \Sigma, \delta, q_0, F)$$

such that  $L = L(M)$ . One can define a **nondeterministic finite automaton**

$$\widehat{M} = (Q, \Sigma, \widehat{\delta}, q_0, F)$$

— with the same set  $Q$  of states, start state  $q_0$ , set of accepting states  $F$  and alphabet  $\Sigma$  — such that  $L(\widehat{M}) = L(M) = L$ , by defining the transition function  $\widehat{\delta} : Q \times \Sigma_\lambda \rightarrow \mathcal{P}(Q)$  as follows: For every state  $q \in Q$  and for all  $\sigma \in \Sigma_\lambda$ ,

$$\widehat{\delta}(q, \sigma) = \begin{cases} \{\delta(q, \sigma)\} & \text{if } \sigma \in \Sigma, \\ \emptyset & \text{if } \sigma = \lambda. \end{cases}$$

Then the state diagrams for  $M$  and  $\widehat{M}$ .

To prove that (b)  $\Rightarrow$  (a), one should consider an arbitrarily chosen alphabet  $\Sigma$  and language  $L \subseteq \Sigma^*$ , once again — and suppose that  $L$  is the language of a **nondeterministic finite automaton**

$$M = (Q, \Sigma, \delta, q_0, F).$$

One can proceed by designing a **deterministic finite automaton**

$$\widehat{M} = (\widehat{Q}, \Sigma, \widehat{\delta}, \widehat{q}_0, \widehat{F})$$

— with the same alphabet  $\Sigma$  but generally, with a different set  $\widehat{Q}$  of states, accept state and set of final states — using the design process from earlier lectures: When processing symbols in a string,  $\widehat{M}$  should remember *the set of states in  $Q$  that can be reached when the same symbols have been processed by  $M$*  — so that states in  $\widehat{M}$  correspond to *sets of states* in  $M$ .

Details of the construction of  $\widehat{M}$  from  $M$ , and a proof of the correctness of this construction, are given in a supplement for this lecture.  $\square$

A **simulation** is something that can be presented to relate the power of two models of computation. In order to show that the machines described by a **second** model of computation are (in some sense) at least as powerful or efficient as the machines described by a **first** model of computation, we generally do the following:

- (a) Consider an arbitrary machine  $M$ , of the type described by the **first** model of computation.
- (b) Use  $M$  to define another machine  $\widehat{M}$ , of the type described by the **second** model of computation.
- (c) Prove that  $\widehat{M}$  solves the same problem as  $M$ .

The above claim was (arguably) proved by giving two simulations. Simulations will be used again, later on in this course.