

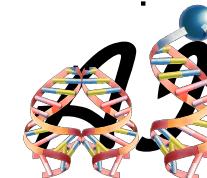


Genetic Programming and Lindenmayer Systems

Christian Jacob

*Department of Computer Science
University of Calgary*

CPSC 601.73 — Winter 2003



Genetic Algorithms (GA)

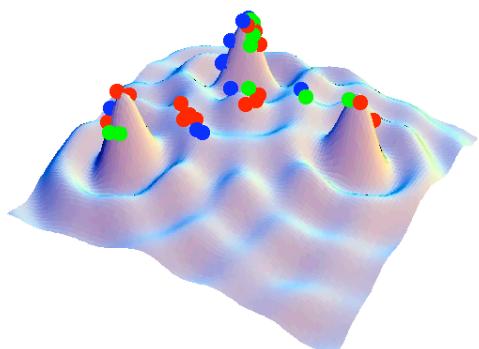
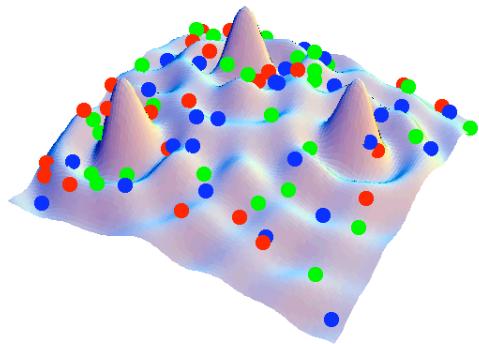
John H. Holland

(1975)

David Goldberg

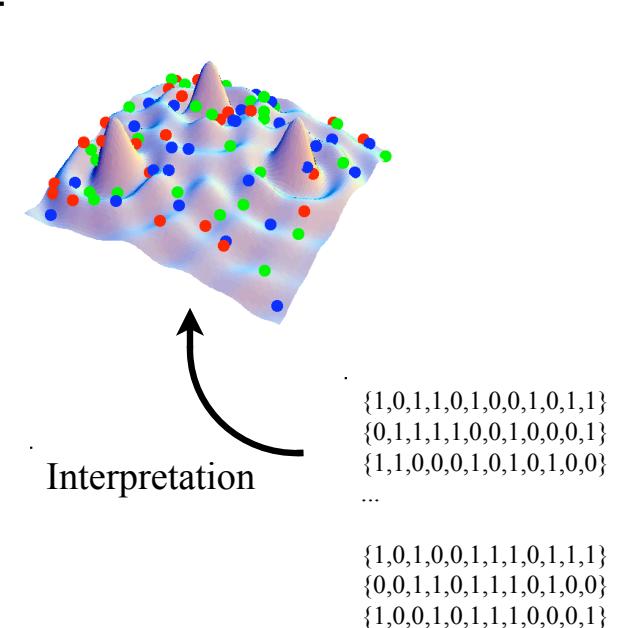
(1989)

Evolutionary Optimization

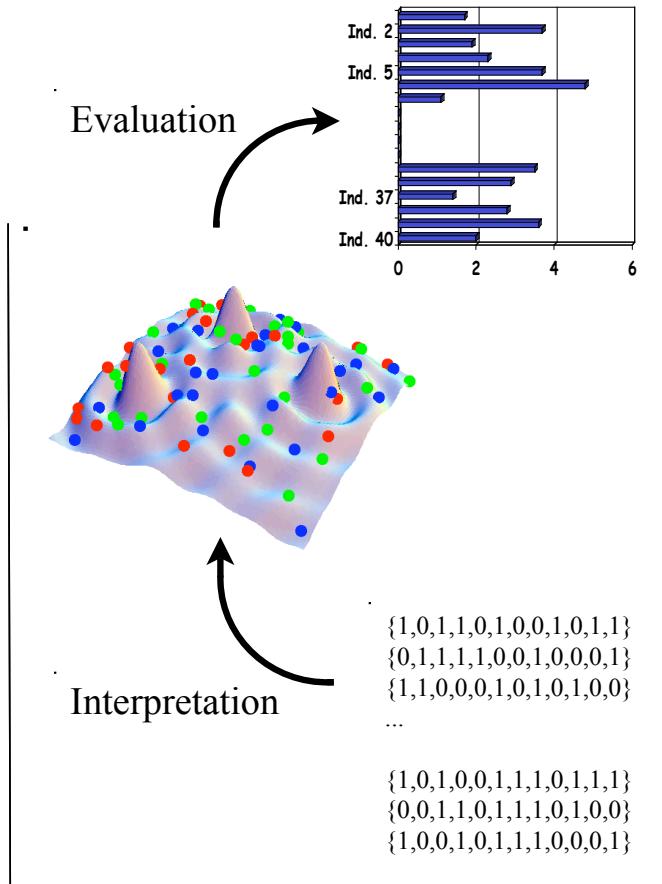


- **Knowledge Reservoir**
Set of possible solutions
 - *Gleaning a reservoir of knowledge from interactions with the environment.*
- **Selection**
Fitness-dependent number of offspring
 - *The sieve of selection culls out incorrect / unuseful “knowledge”.*
- **Variation**
Variations of individual solutions
 - *The learning system invents new variants of its old ideas that are tested against environmental demands.*

How Genetic Algorithms Work

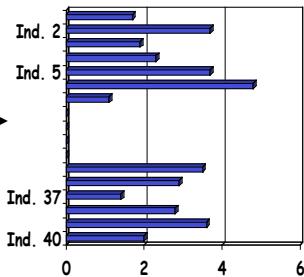


How Genetic Algorithms Work

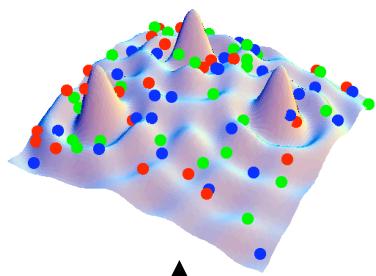


How Genetic Algorithms Work

Evaluation



Interpretation



{1,0,1,1,0,1,0,0,1,0,1,1}
{0,1,1,1,1,0,0,1,0,0,0,1}
{1,1,0,0,0,1,0,1,0,1,0,0}

...

{1,0,1,0,0,1,1,1,0,1,1,1}
{0,0,1,1,0,1,1,1,0,1,0,0}
{1,0,0,1,0,1,1,1,0,0,0,1}

Selection

{0,0,1,1,0,1,1,1,0,1,0,0} {1,1,0,0,0,1,0,1,0,1,0,0}

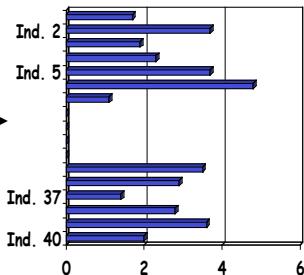
{1,0,1,1,0,1,0,0,1,0,1,1}
{0,1,1,1,1,0,0,1,0,0,0,1}
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...

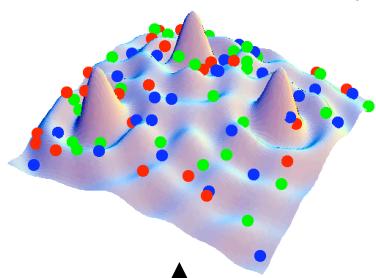
{1,0,1,0,0,1,1,1,0,1,1,1}
{0,0,1,1,0,1,1,1,0,1,0,0}
{1,0,0,1,0,1,1,1,0,0,0,1}

How Genetic Algorithms Work

Evaluation



Interpretation



{1,0,1,1,0,1,0,0,1,0,1,1}

{0,1,1,1,1,0,0,1,0,0,0,1}

{1,1,0,0,0,1,0,1,0,1,0,0}

...

{1,0,1,0,0,1,1,1,0,1,1,1}

{0,0,1,1,0,1,1,1,0,1,0,0}

{1,0,0,1,0,1,1,1,0,0,0,1}

{0,**0**,1,1,0,**1**,1,1,0,1,**0**,0}

Mutation

{0,**1**,1,1,0,**0**,1,1,0,1,**1**,0}

{1,1,**0**,0,0,1,0,1,0,**1**,0,0}

{1,0,1,1,0,1,0,0,1,0,1,1}

{0,1,1,1,1,0,0,1,0,0,0,1}

{1,1,0,0,0,1,0,1,0,1,0,0}

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{0,0,1,1,0,1,1,1,0,1,0,0}

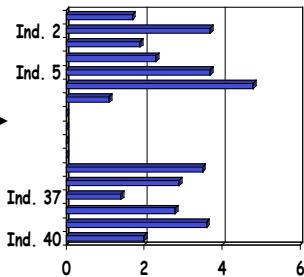
{1,0,0,1,0,1,1,1,0,0,0,1}

Selection

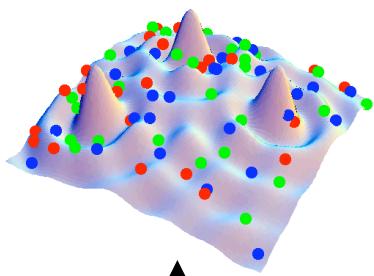


How Genetic Algorithms Work

Evaluation



Interpretation



{1,0,1,1,0,1,0,0,1,0,1,1}

{0,1,1,1,1,0,0,1,0,0,0,1}

{1,1,0,0,0,1,0,1,0,1,0,0}

...

{1,0,1,0,0,1,1,1,0,1,1,1}

{0,0,1,1,0,1,1,1,0,1,0,0}

{1,0,0,1,0,1,1,1,0,0,0,1}

{0,0,1,1,0,1,1,1,0,1,0,0} {1,1,0,0,0,1,0,1,0,1,0,0}

Mutation

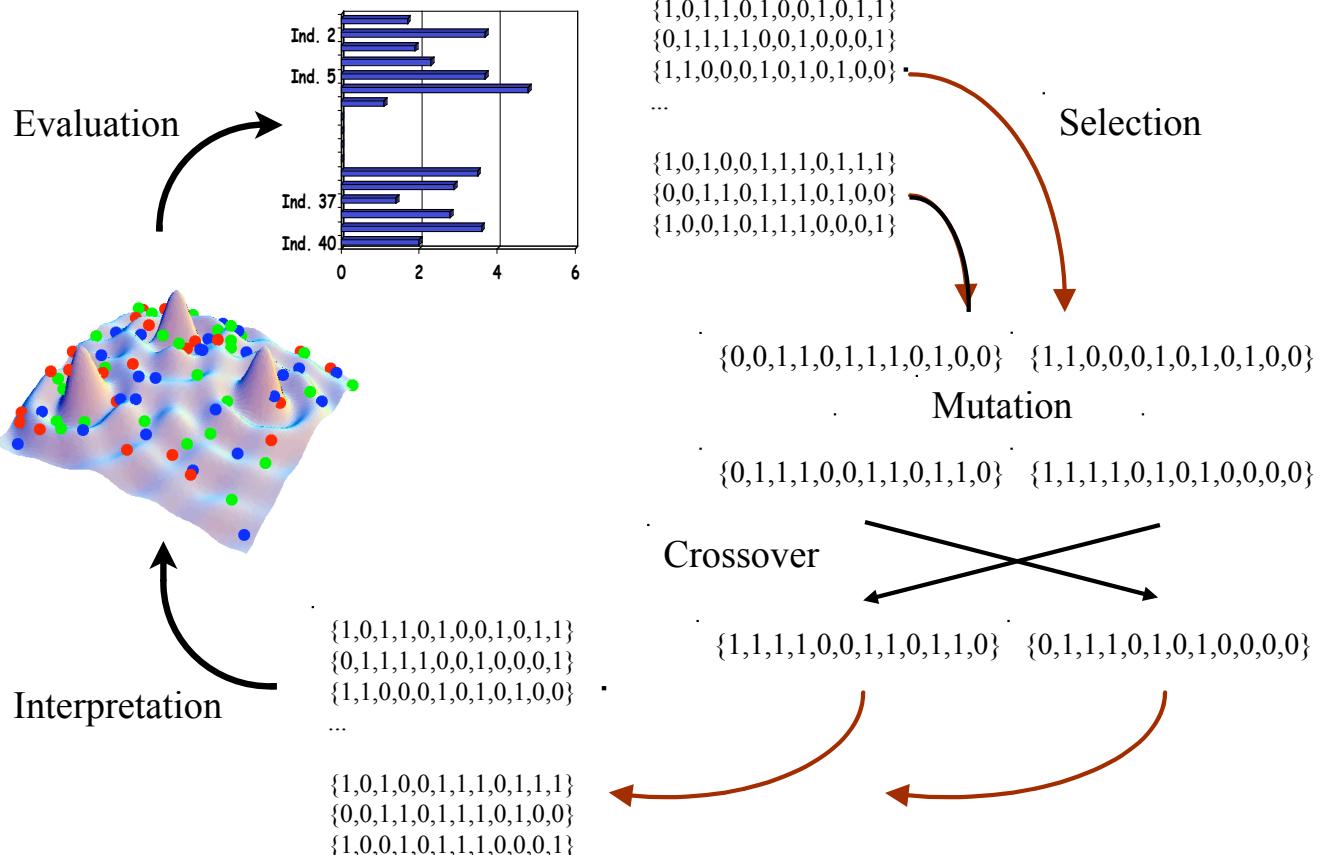
{0,1,1,1,0, 0,1,1,0,1,1,0} {1,1,1,1, 0,1,0,1,0,0,0,0}

Crossover



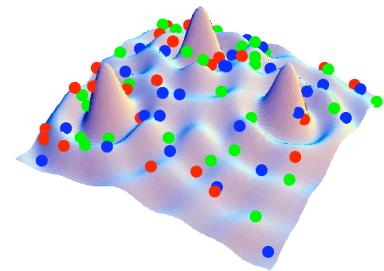
{1,1,1,1,0,0,1,1,0,1,1,0} {0,1,1,1,0,1,0,1,0,0,0,0}

How Genetic Algorithms Work

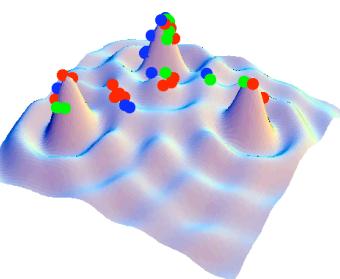
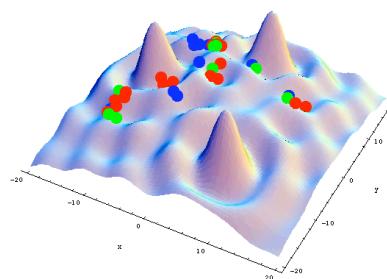


Evolution with Varying Objective Function

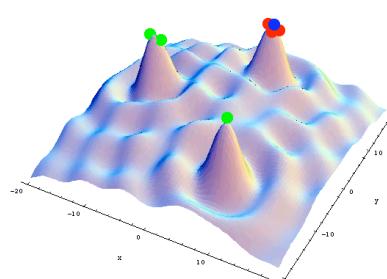
Generation 0



Generation 11



Generation 10



Generation 30

Evolution with Varying Objective Function

Generation 0

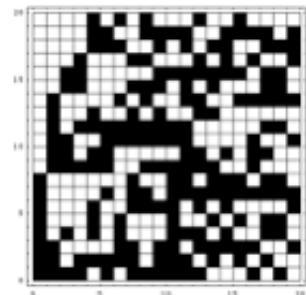
Generation 10

Evolution with Varying Objective Function

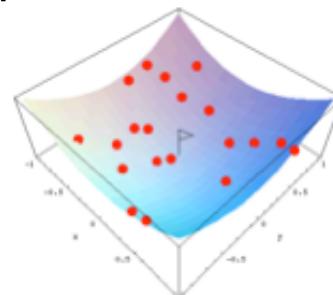
Generation 11

Generation 30

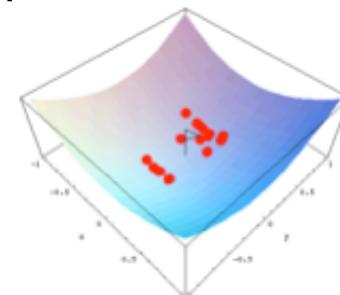
Comparison of Genetic Operators (Genotypes)



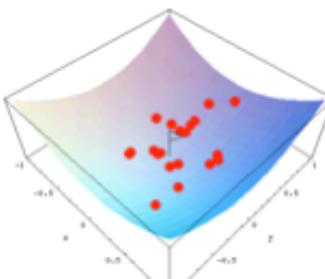
Initial Population



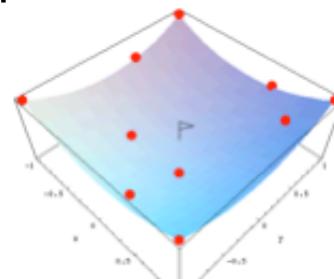
Mutation



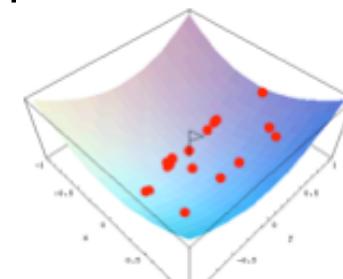
Recombination



Inversion

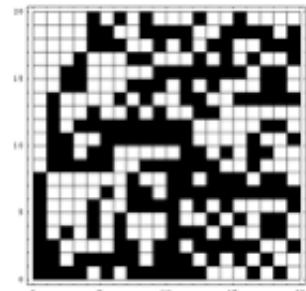


Deletion

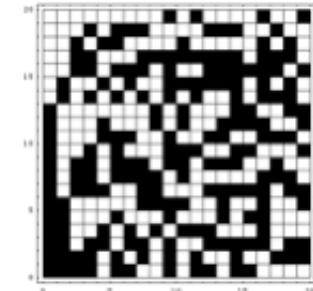


Duplication

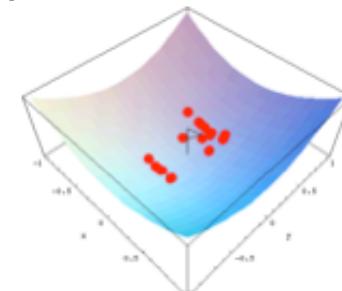
Comparison of Genetic Operators (Genotypes)



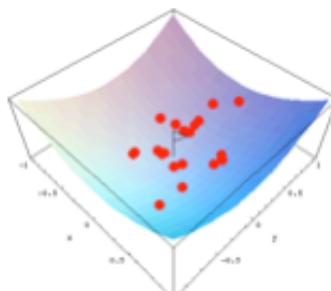
Initial Population



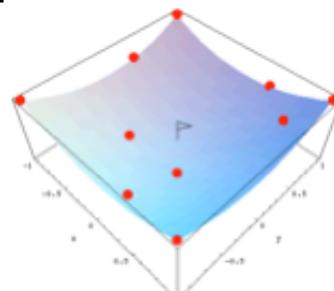
Mutation



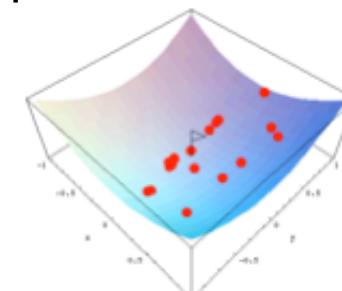
Recombination



Inversion

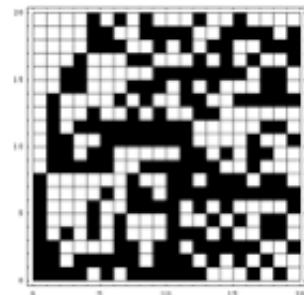


Deletion

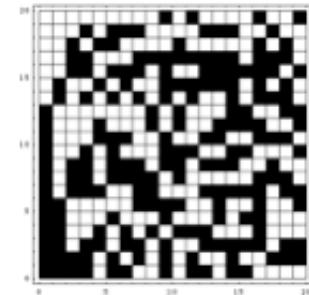


Duplication

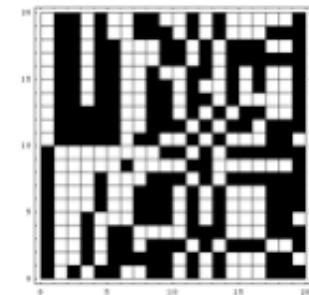
Comparison of Genetic Operators (Genotypes)



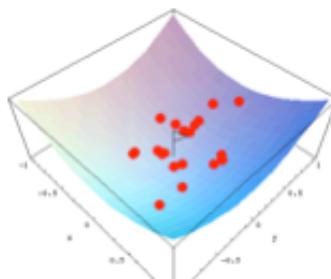
Initial Population



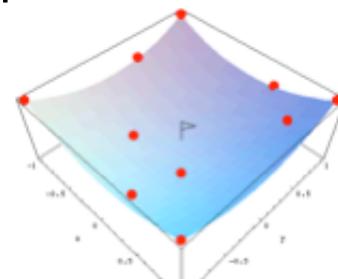
Mutation



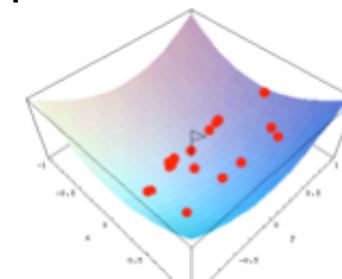
Recombination



Inversion

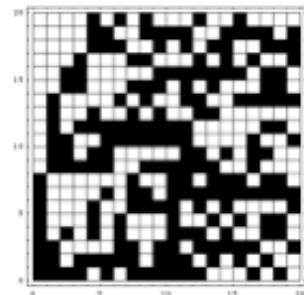


Deletion

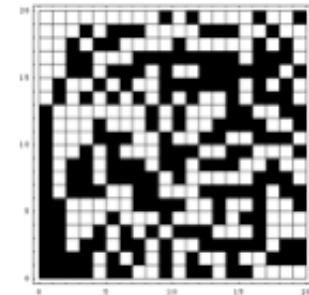


Duplication

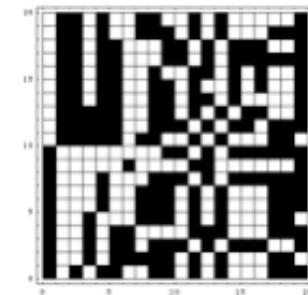
Comparison of Genetic Operators (Genotypes)



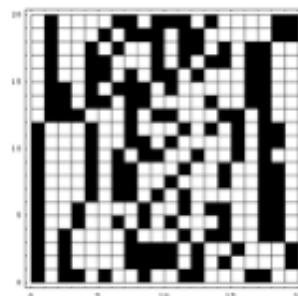
Initial Population



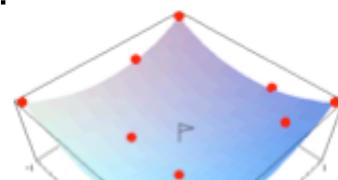
Mutation



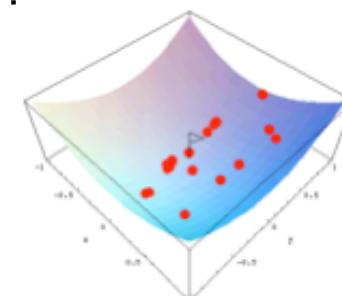
Recombination



Inversion

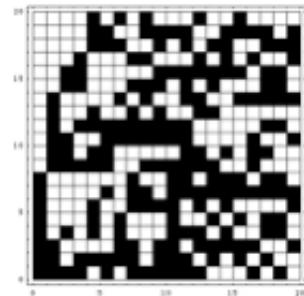


Deletion

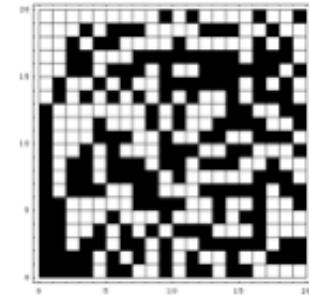


Duplication

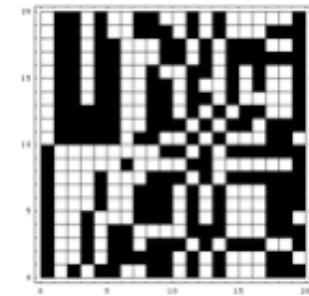
Comparison of Genetic Operators (Genotypes)



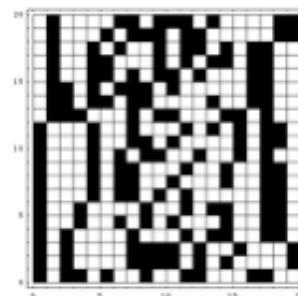
Initial Population



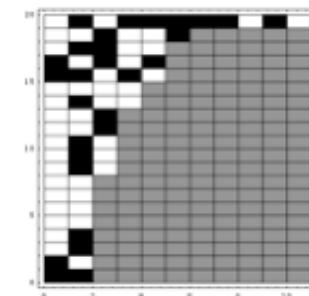
Mutation



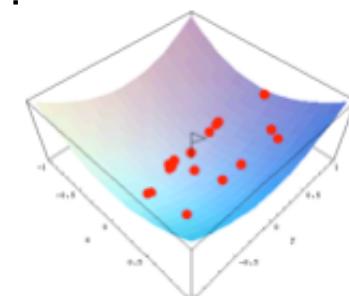
Recombination



Inversion

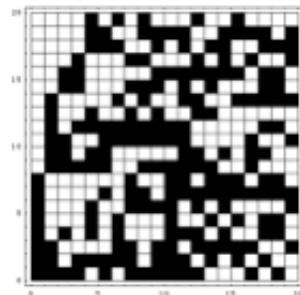


Deletion

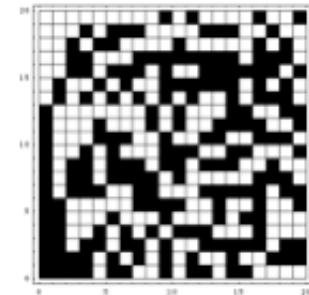


Duplication

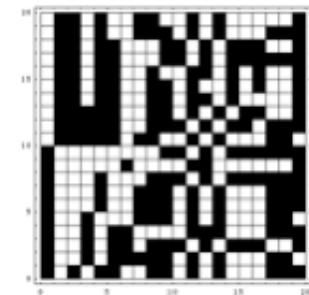
Comparison of Genetic Operators (Genotypes)



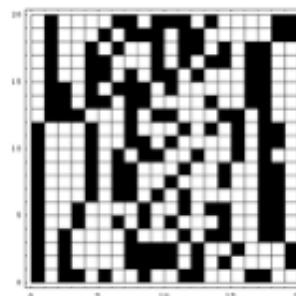
Initial Population



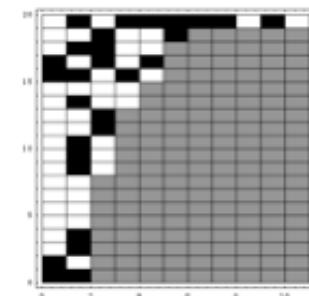
Mutation



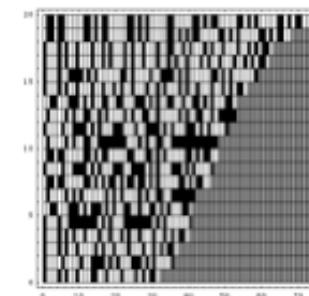
Recombination



Inversion

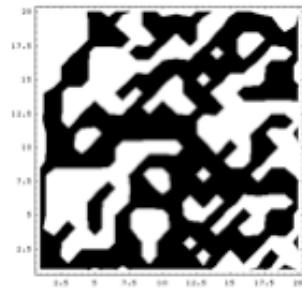


Deletion

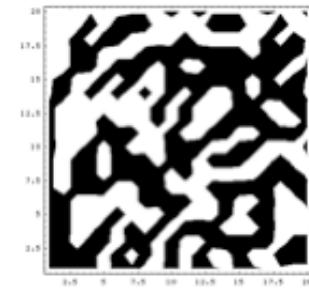


Duplication

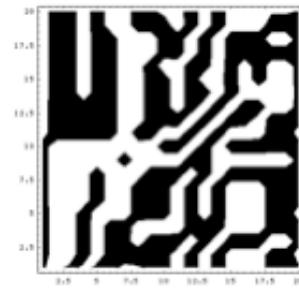
Comparison of Genetic Operators (Genotypes)



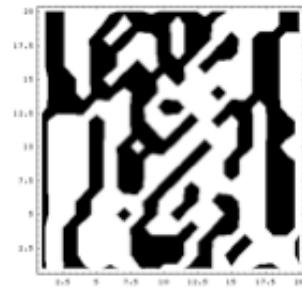
Initial Population



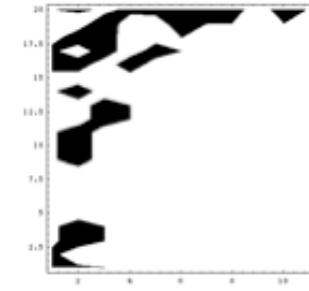
Mutation



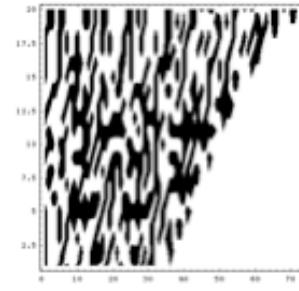
Recombination



Inversion

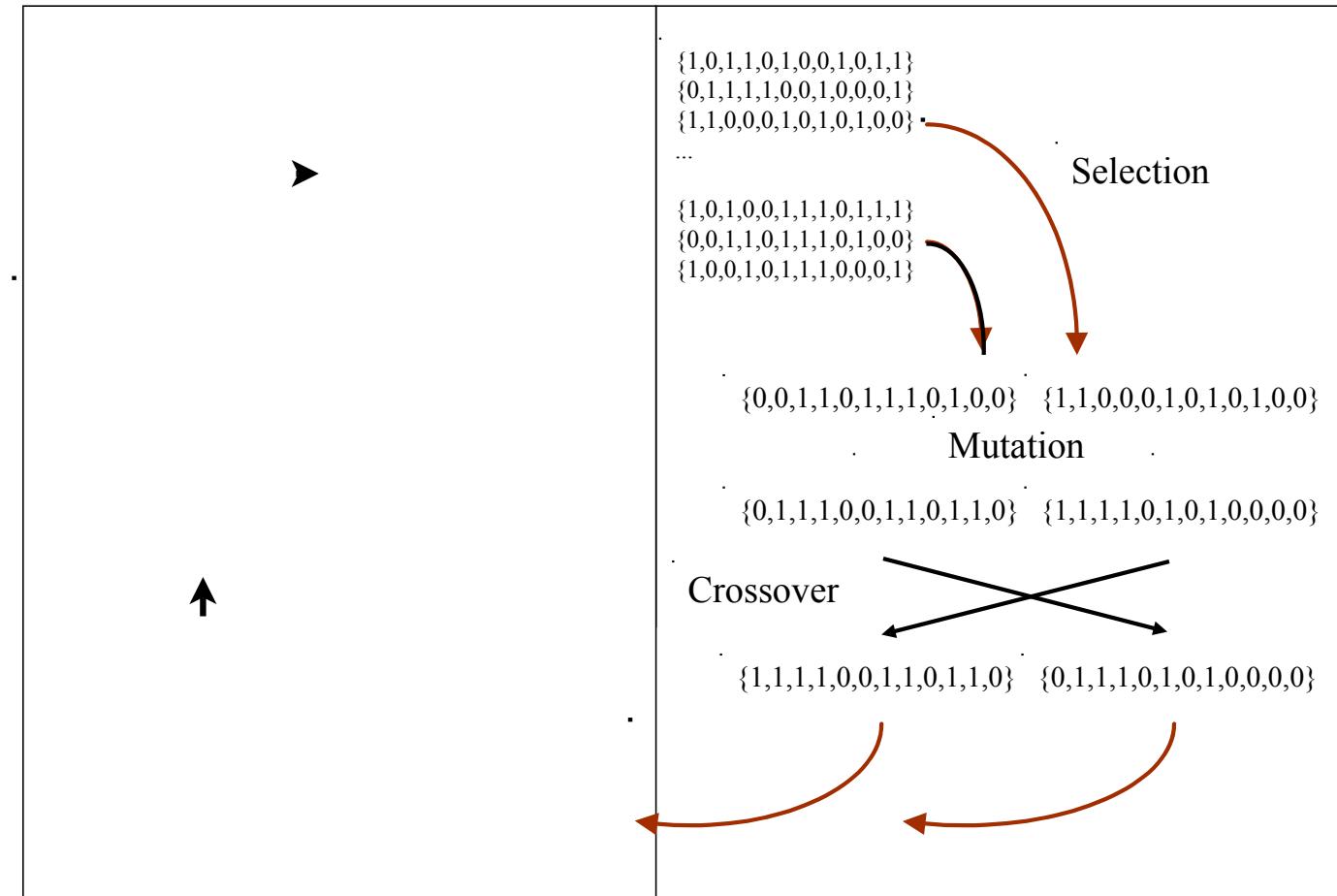


Deletion



Duplication

Phenotypic vs. Genotypic Structures



GA Dualism – Dualism in Nature

Genotype

```
{1,0,1,1,0,1,0,0,1,0,1,1}  
{0,1,1,1,1,0,0,1,0,0,0,1}  
{0,0,1,1,0,101,1,0,1,0,0}
```

...

```
{1,1,0,0,0,1,0,1,0,1,0,0}
```

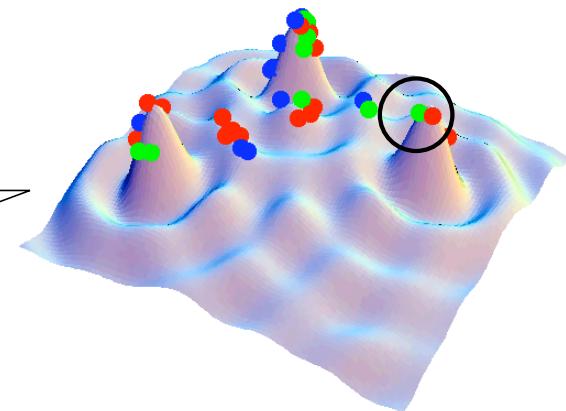
...

```
{1,0,1,0,0,1,1,1,0,1,1,1}  
{0,0,1,1,0,1,1,1,0,1,0,0}  
{1,0,0,1,0,1,1,1,0,0,0,1}
```

Phenotype

Decoding

Interpretation

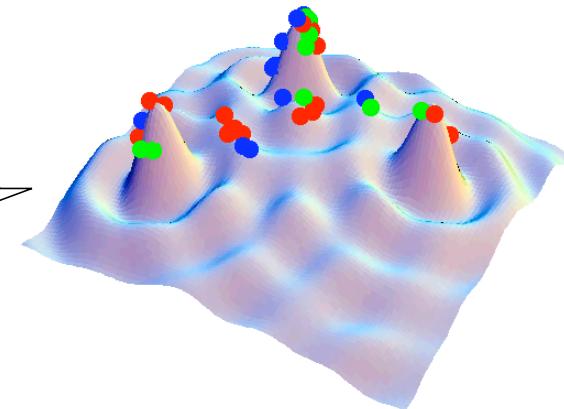


GA Dualism – Dualism in Nature

Genotype



Phenotype



Decoding



Interpretation

GA Dualism – Dualism in Nature

Genotype



Phenotype



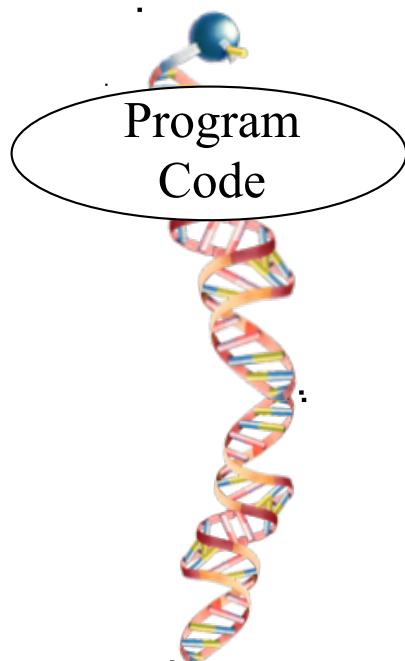
Transcription
Translation



Development
Morphogenesis

GA Dualism – Dualism in Nature

Genotype



Phenotype

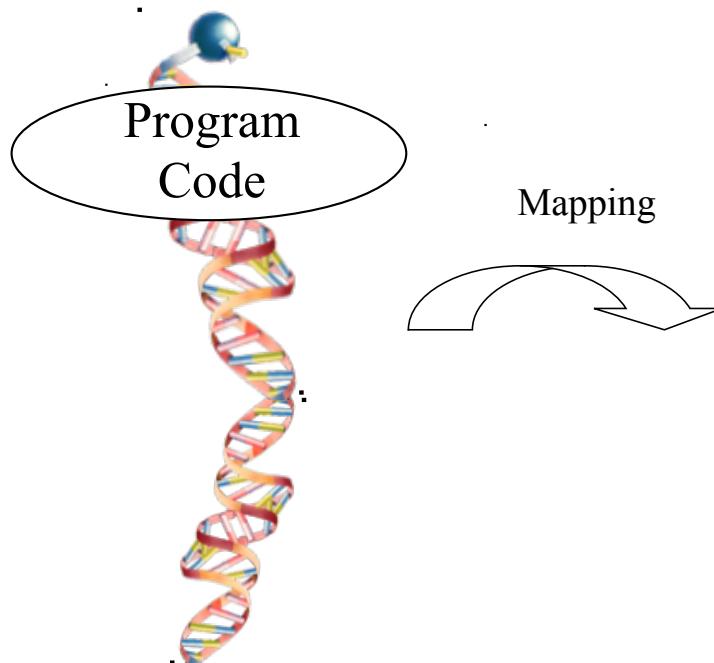


Transcription
Translation

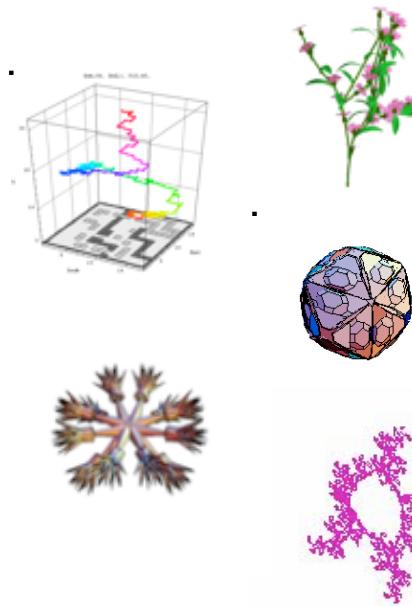
Development
Morphogenesis

GA Dualism – Dualism in Nature

Genotypes



Phenotypes



Genetic Programming (GP)

John Koza
(1992)

Programming of Computers
by Means of Natural Selection

Genetic Computer Programming

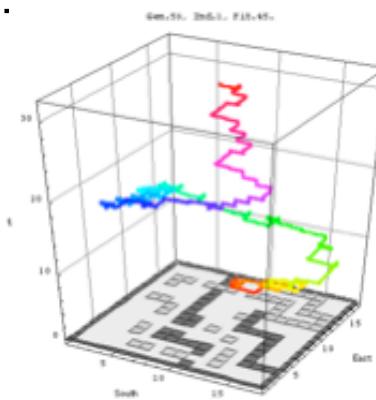
or

*How to Program a Computer
without
Explicitly Telling It What to Do*

Ant Tracker

*Breeding
of Simple
Control Programs*

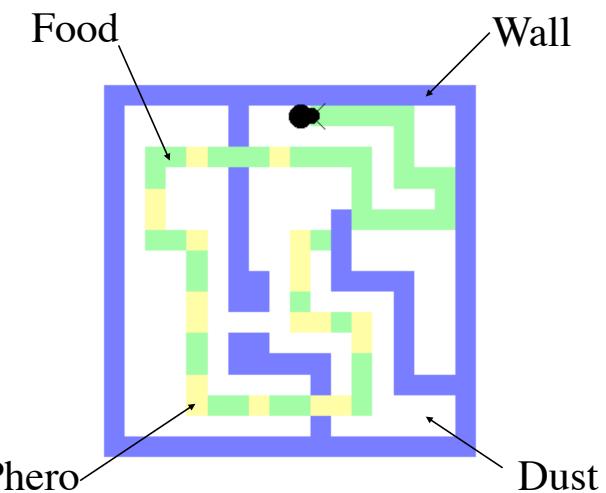
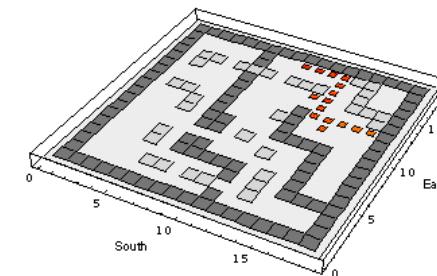
A Classic GP Example



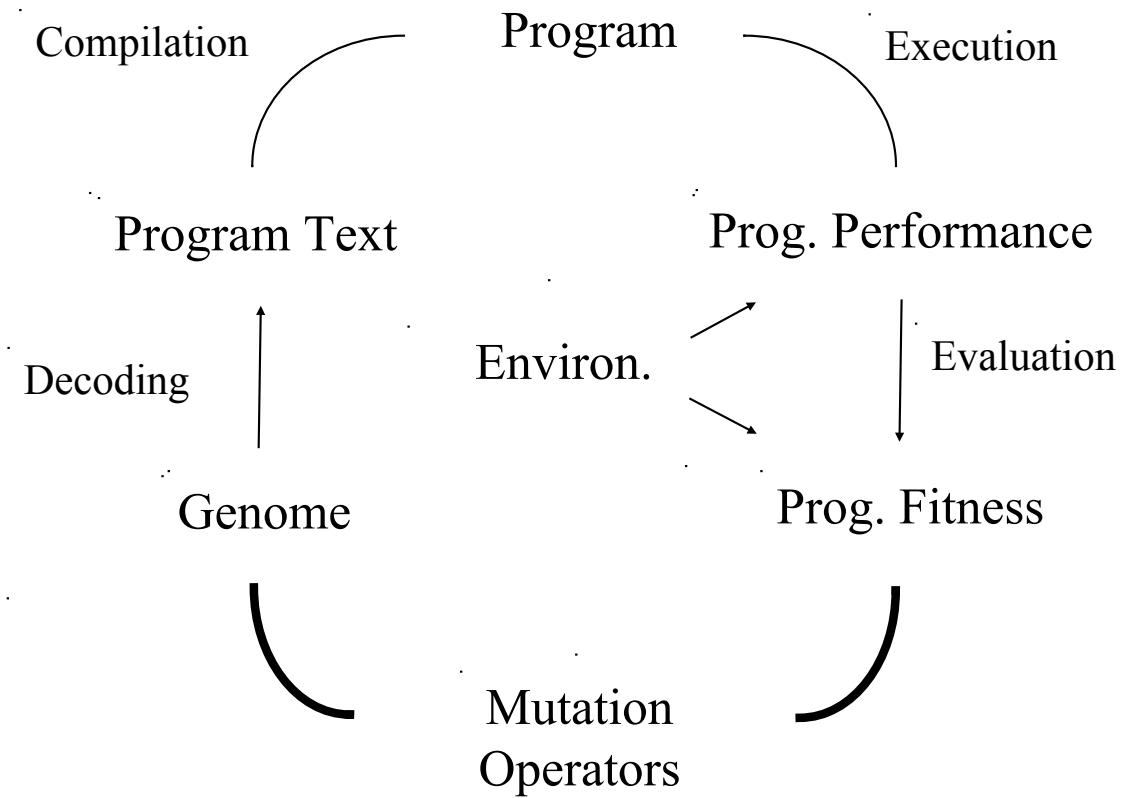
AntTracker: Collecting Food in a Maze

Command building blocks:

- advance
- turnLeft
- turnRight
- nop
- ifSensor[*food*][A, B]
ifSensor[*phero*][A, B]
ifSensor[*dust*][A, B]
ifSensor[*wall*][A, B]

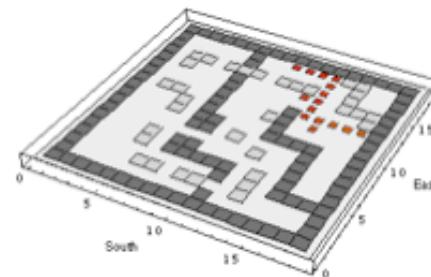


How Genetic Programming Works



AntTracker Evolution

- Fitness criterion:
Number of collected food pieces
- 50 individuals per population
- 100 generations (max.)
- < 400 action steps
- GP operators:
 - Mutation
 - Crossover
 - Permutation
 - Deletion
 - Duplication
 - En-/decapsulation

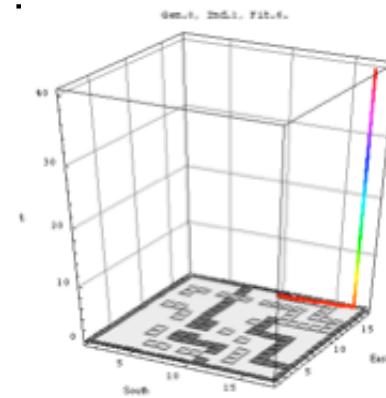
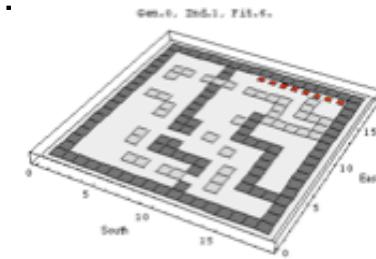


AntTracker: Generation 0

06

Fitness

```
AntTracker[  
    seq[advance]  
]
```

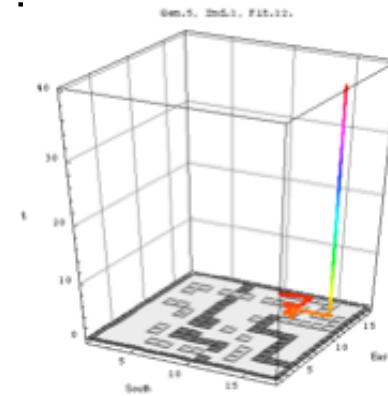
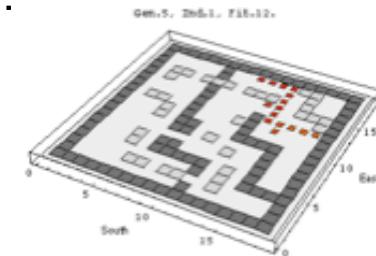


AntTracker: Generation 5

12

Fitness

```
AntTracker[  
    seq[seq[advance],  
        ifSensor[dust][  
            seq[seq[stop]],  
            seq[advance]],  
        seq[  
            ifSensor[dust][  
                seq[turnLeft, again],  
                seq[nop]],  
            seq[seq[advance]],  
            ifSensor[wall][  
                seq[seq[stop],  
                seq[nop],  
                ifSensor[phero][  
                    seq[turnLeft],  
                    seq[stop]]],  
                seq[turnRight]]],  
            seq[nop]]]]
```

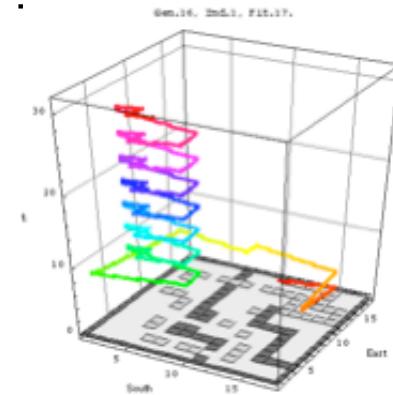
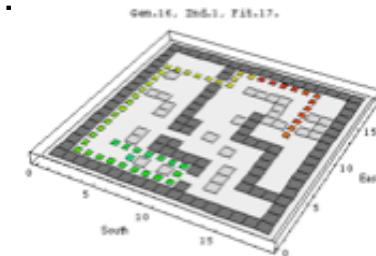


AntTracker: Generation 16

17

Fitness

```
AntTracker[  
    seq[seq[advance],  
        ifSensor[wall][  
            seq[seq[stop], seq[nop],  
                ifSensor[phero][  
                    seq[turnLeft],  
                    seq[advance]]],  
            seq[turnRight]],  
        seq[ifSensor[dust][  
            seq[turnLeft, again],  
            seq[nop]],  
            seq[ifSensor[wall][  
                seq[seq[turnLeft, again],  
                    seq[nop],  
                    ifSensor[phero]  
                        [seq[stop]],  
                        seq[seq[advance]]],  
                seq[nop]]]]]
```

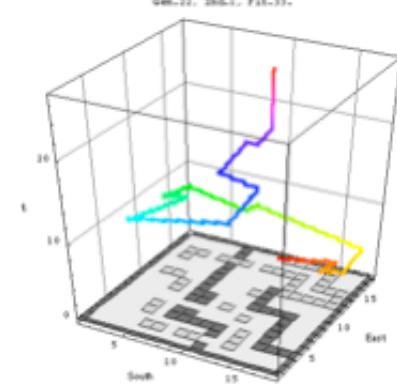
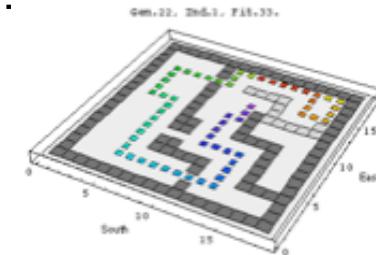


AntTracker: Generation 22

33

Fitness

```
AntTracker[  
    seq[  
        ifSensor[wall][  
            seq[turnLeft, again],  
        seq[turnRight]],  
        seq[  
            ifSensor[dust][seq[turnLeft,  
                again], seq[nop]],  
            seq[  
                ifSensor[wall][  
                    seq[seq[turnLeft, again],  
                    seq[nop],  
                    ifSensor[phero][seq[stop]]],  
                    seq[seq[advance]]],  
                    seq[nop]]]]]
```

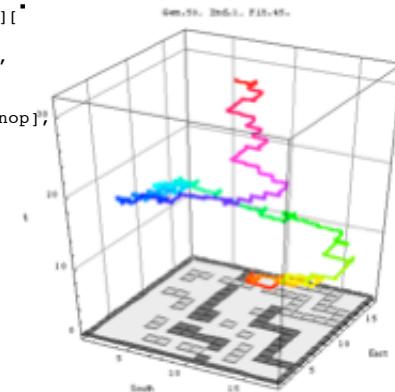
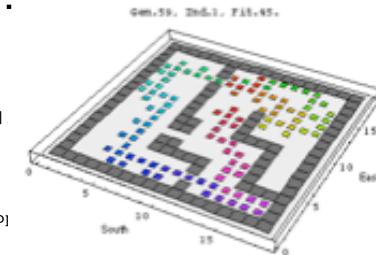


AntTracker: Generation 59

45

Fitness

```
AntTracker[ _____
  seq[
    ifSensor[wall][
      seq[turnLeft, turnLeft, again],
      seq[
        ifSensor[wall][seq[turnLeft, again]
          seq[turnRight]],
        seq[
          seq[
            ifSensor[wall][
              seq[seq[turnLeft, again], seq[nop]
                ifSensor[wall][seq[again],
                  seq[seq[nop], seq[nop]]],
                seq[seq[advance]]]]]]],
        seq[
          ifSensor[dust][seq[turnLeft, again]],
          seq[
            ifSensor[wall][seq[ifSensor[dust][
              seq[advance]]],
              seq[ifSensor[dust][seq[turnLeft,
                again]],
                seq[ifSensor[wall][
                  seq[seq[turnLeft, again], seq[nop],
                    ifSensor[dust][seq[stop],
                      seq[stop], seq[turnLeft]]],
                  seq[seq[advance]]]],
                  seq[nop]]]]]]]
```



Gen. 5

```

AntTracker[
    seq[seq[advance],
        ifSensor[dust][seq[seq[stop]], seq[advance]],
        seq[
            ifSensor[ust][seq[turnLeft, again], seq[nop]],
            nce,
            '1>[
                p], seq[nop],
                phero][seq[turnLeft], seq[stop]]
            seq[tu .Right]],
            seq[nop],
            seq[stop]]]
]

```

Gen. 1

```

AntTracker[
    seq[
        ifSensor[wall][
            seq[turnLeft, turnLeft, again],
            seq[
                ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                seq[
                    seq[
                        ifSensor[wall][
                            seq[seq[turnLeft, again], seq[nop],
                            ifSensor[wall][seq[again], seq[seq[nop seq[nop]]]],
                            seq[seq[advance]]]]],
                        seq[
                            ifSensor[dust][seq[turnLeft, again]],
                            seq[
                                ifSensor[wall][seq[ifSensor[dust][seq[adv. e]]],
                                seq[ifSensor[dust][seq[turnLeft, again]],
                                seq[ifSensor[wall][
                                    seq[seq[turnLeft, again], seq[nop],
                                    ifSensor[dust][seq[stop], seq[stop], seq[turnLeft]]],
                                    seq[seq[advance]]]],
                                    seq[nop]]]]]]]

```

Gen. 59

```

AntTracker[
    seq[seq[advance],
        ifSensor[wall][
            seq[seq[stop], seq[nop],
            sor[phero][seq[turnLeft], seq[advance]]],
            Right]],
            sor[dust][seq[turnLeft, again], seq[nop]],
            ensor[wall][
                se [eq[turnLeft, again], seq[nop],
                i sensor[phero][seq[stop]]],
                seq[seq[advance]]],
                seq[nop]]]
]

```

Gen. 16

```

AntTracker[
    seq[
        ifSensor[wall][
            seq[turnLeft, again], seq[turnRight]],
        seq[
            ifSensor[dust][seq[turnLeft, again], seq[nop]],
            seq[
                ifSensor[wall][
                    seq[seq[turnLeft, again], seq[nop],
                    ifSensor[phero][seq[stop]]],
                    seq[seq[advance]]],
                    seq[nop]]]
    ]
]

```

Gen. 1

```

AntTracker[
  seq[seq[advance],
    ifSensor[c
    seq[
      ifSensor
      AntTracker[
        seq[adv
      ]
      seq[tu
      seq[nop]
    ]
  ]
  Gen. 5. 2nd.1. Fit.12.
  
```

A 15x15 grid maze with a single path from the bottom-left corner (0,0) to the top-right corner (15,15). The path is highlighted in red. The grid has a border of 5 units on all sides.

Gen. 5

```

AntTracker[
  seq[seq[advan
  ifSensor[wal
  seq[seq[sto
    sor[p
    'Rig
    'or
    enso
    se
    seq[tu
    i
    sensor[
    seq[seq[adv
    seq[nop]]]
  ]
  Gen.16. 2nd.1. Fit.17.
  
```

A 15x15 grid maze with a complex path from the bottom-left corner (0,0) to the top-right corner (15,15). The path is highlighted with multiple colors (red, green, blue, yellow) and includes several loops and dead ends. The grid has a border of 5 units on all sides.

Gen. 16

```

AntTracker[
  seq[
    ifSensor[wall][
      seq[turnLeft, turnLeft, again],
      seq[
        ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
        seq[
          seq[seq[advance,
            ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
            seq[seq[advance,
              ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
              seq[seq[advance,
                ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                seq[seq[advance,
                  ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                  seq[seq[advance,
                    ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                    seq[seq[advance,
                      ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                      seq[seq[advance,
                        ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                        seq[seq[advance,
                          ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                          seq[seq[advance,
                            ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                            seq[seq[advance,
                              ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                              seq[seq[advance,
                                ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                seq[seq[advance,
                                  ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                  seq[seq[advance,
                                    ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                    seq[seq[advance,
                                      ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                      seq[seq[advance,
                                        ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                        seq[seq[advance,
                                          ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                          seq[seq[advance,
                                            ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                            seq[seq[advance,
                                              ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                              seq[seq[advance,
                                                ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                                seq[seq[advance,
                                                  ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                                  seq[seq[advance,
                                                    ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                                    seq[seq[advance,
                                                      ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                                      seq[seq[advance,
                                                        ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                                        seq[seq[advance,
                                                          ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                                          seq[seq[advance,
                                                            ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                                            seq[seq[advance,
                                                              ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                                              seq[seq[advance,
                                                                ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                                                seq[seq[advance,
                                                                  ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                                                  seq[seq[advance,
                                                                    ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                                                    seq[seq[advance,
                                                                      ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                                                      seq[seq[advance,
                                                                        ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                                                        seq[seq[advance,
                                                                          ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                                                          seq[seq[advance,
                                                                            ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                                                            seq[seq[advance,
                                                                              ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                                                              seq[seq[advance,
                                                                                ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                                                                seq[seq[advance,
                                                                                  ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                                                                  seq[seq[advance,
                                                                                    ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                                                                    seq[seq[advance,
                                                                                      ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                                                                      seq[seq[advance,
                                                                                        ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                                                                                        seq[seq[advance,
              
```

A 15x15 grid maze with a very complex path from the bottom-left corner (0,0) to the top-right corner (15,15). The path is highlighted with many different colors (red, green, blue, yellow, purple, etc.) and contains numerous loops and dead ends. The grid has a border of 5 units on all sides.

Gen. 59

```

AntTracker[
  seq[
    ifSensor
    seq[tur
    seq[
      ifSensor
      seq[
        ifSens
        seq[s
        ifSe
        seq[s
        seq[nop
      ]
    ]
    Gen.32. 2nd.1. Fit.33.
    
```

A 15x15 grid maze with a complex path from the bottom-left corner (0,0) to the top-right corner (15,15). The path is highlighted with many different colors (red, green, blue, yellow, purple, etc.) and contains numerous loops and dead ends. The grid has a border of 5 units on all sides.

Gen. 32

Reuse of Learnt Building Blocks (1)

Gen. 5

```

AntTracker[
    seq[seq[advance],
        ifSensor[dust][seq[seq[stop]], seq[advance]],
    seq[
        ifSensor[dust][seq[turnLeft, again], seq[nop]],
        seq[seq[advance],
            ifSensor[wall][
                seq[seq[stop], seq[nop],
                    ifSensor[phero][seq[turnLeft], seq[advance]],
                seq[turnRight]],
                seq[nop]]]
    ]
]

```

Gen. 1

```

AntTracker[
    seq[
        ifSensor[wall][
            seq[turnLeft, turnLeft, again],
        seq[
            ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
        seq[
            seq[
                ifSensor[wall][
                    seq[seq[turnLeft, again], seq[nop],
                        ifSensor[wall][seq[again], seq[seq[nop], seq[nop]]],
                    seq[seq[advance]]]]],
            seq[
                ifSensor[dust][seq[turnLeft, again]],
                seq[
                    ifSensor[wall][seq[ifSensor[dust][seq[advance]]],
                        seq[ifSensor[dust][seq[turnLeft, again]]],
                    seq[ifSensor[wall][
                        seq[seq[turnLeft, again], seq[nop],
                            ifSensor[dust][seq[stop], seq[stop], seq[turnLeft]],
                        seq[seq[advance]]]],
                        seq[nop]]]]]
        ]
]

```

Gen. 59

```

AntTracker[
    seq[seq[advance],
        ifSensor[wall][
            seq[seq[stop], seq[nop],
                ifSensor[phero][seq[turnLeft], seq[advance]],
            seq[turnRight]],
            seq[ifSensor[dust][seq[turnLeft, again], seq[nop]],
                seq[ifSensor[wall][
                    seq[seq[turnLeft, again], seq[nop],
                        ifSensor[phero][seq[stop]]],
                    seq[seq[advance]]]],
                    seq[nop]]]
]

```

Gen. 16

Gen. 22

```

AntTracker[
    seq[
        ifSensor[wall][
            seq[turnLeft, again], seq[turnRight]],
        seq[
            ifSensor[dust][seq[turnLeft, again], seq[nop]],
            seq[
                ifSensor[wall][
                    seq[seq[turnLeft, again], seq[nop],
                        ifSensor[phero][seq[stop]]],
                    seq[seq[advance]]]],
                seq[nop]]]
]

```

Reuse of Learnt Building Blocks (2)

Gen. 5

```

AntTracker[
    seq[seq[advance],
        ifSensor[dust][seq[seq[stop]], seq[advance]],
        seq[
            ifSensor[dust][seq[turnLeft, again], seq[nop]],
            seq[seq[advance],
                ifSensor[wall][
                    seq[seq[stop], seq[nop],
                        ifSensor[phero][seq[turnLeft], seq[stop]],
                        seq[turnRight]],
                    seq[nop]]]
    ],
    seq[nop]
]

```

Gen. 1

```

AntTracker[
    seq[
        ifSensor[wall][
            seq[turnLeft, turnLeft, again],
            seq[
                ifSensor[wall][seq[turnLeft, again], seq[turnRight]],
                seq[
                    seq[
                        ifSensor[wall][
                            seq[seq[turnLeft, again], seq[nop],
                                ifSensor[wall][seq[again], seq[seq[nop], seq[nop]]],
                                seq[seq[advance]]]]],
                    seq[
                        ifSensor[dust][seq[turnLeft, again]],
                        seq[
                            ifSensor[wall][seq[ifSensor[dust][seq[advance]]],
                                seq[ifSensor[dust][seq[turnLeft, again]],
                                    seq[ifSensor[wall][
                                        seq[seq[turnLeft, again], seq[nop],
                                            ifSensor[dust][seq[stop], seq[stop], seq[turnLeft]],
                                            seq[seq[advance]]]],
                                        seq[nop]]]]]
                ],
                seq[nop]
            ]
        ]
    ]
]

```

Gen. 59

Gen. 16

```

AntTracker[
    seq[seq[advance],
        ifSensor[wall][
            seq[seq[stop], seq[nop],
                ifSensor[phero][seq[turnLeft], seq[advance]]],
            seq[turnRight]],
        seq[ifSensor[dust][seq[turnLeft, again], seq[nop]],
            seq[ifSensor[wall][
                seq[seq[turnLeft, again], seq[nop],
                    ifSensor[phero][seq[stop]]],
                seq[seq[advance]]]],
            seq[nop]]]
]

```

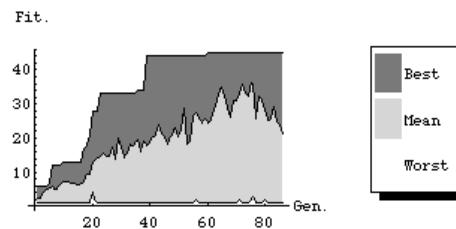
Gen. 22

```

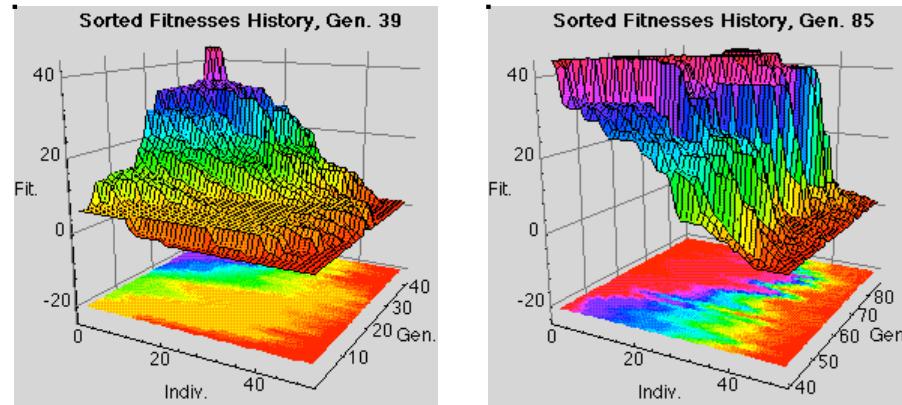
AntTracker[
    seq[
        ifSensor[wall][
            seq[turnLeft, again], seq[turnRight]],
        seq[
            ifSensor[dust][seq[turnLeft, again], seq[nop]],
            seq[
                ifSensor[wall][
                    seq[seq[turnLeft, again], seq[nop],
                        ifSensor[phero][seq[stop]]],
                    seq[seq[advance]]]],
                seq[nop]]
    ]
]

```

AntTracker: Evolution of Fitnesses

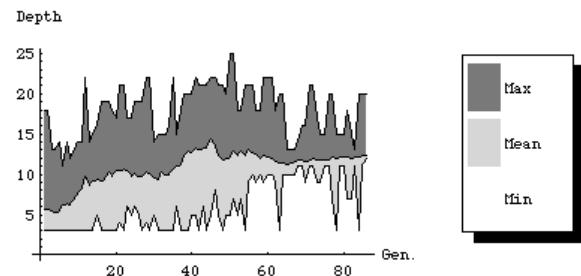


Fitness evolution of *AntTracker* program genomes

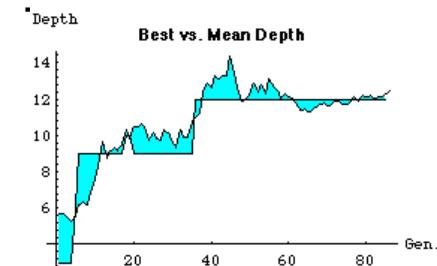


[Jacob 2001, Ch. 9]

AntTracker: Evolution of Program Depth



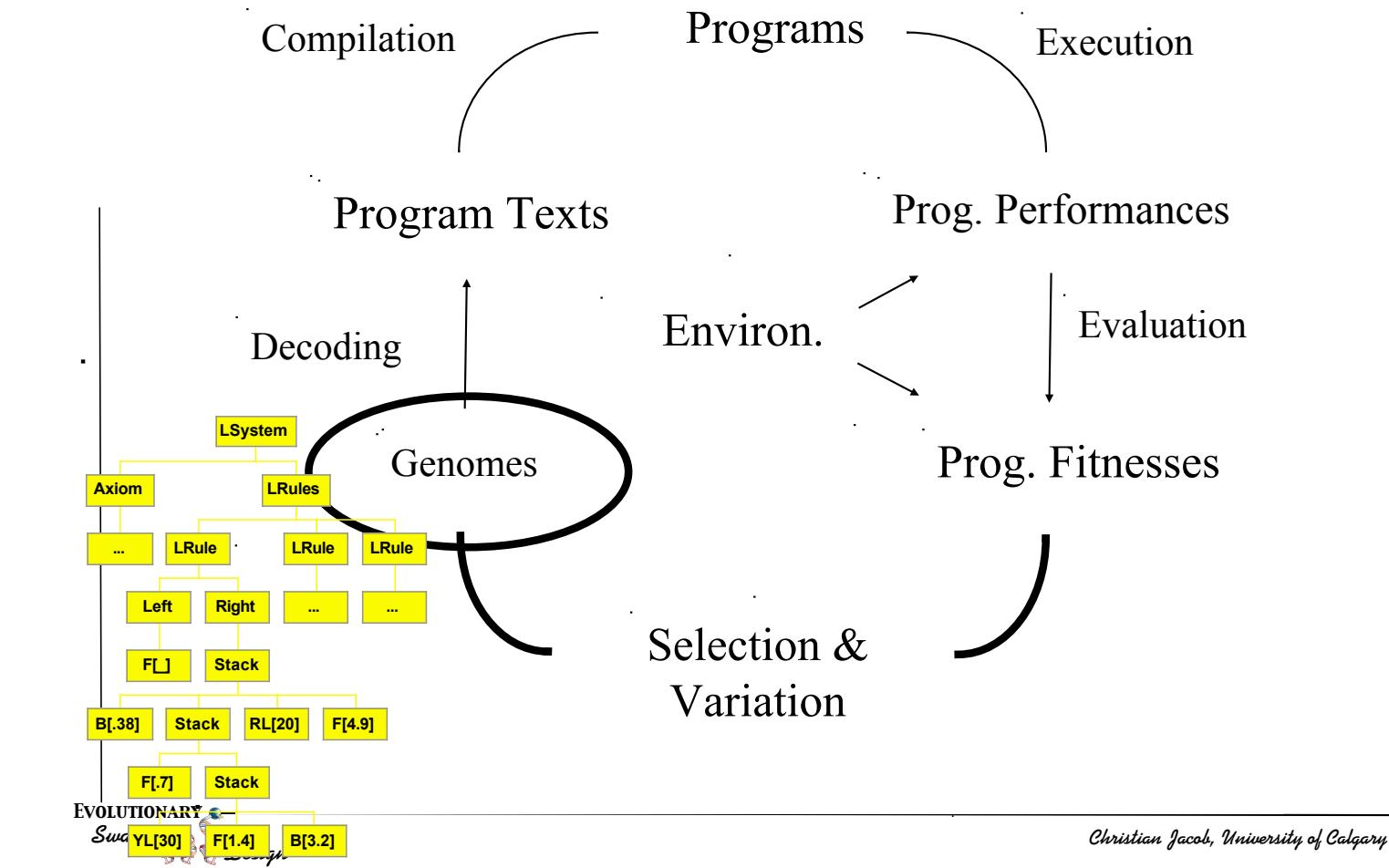
Evolution of program expression depth



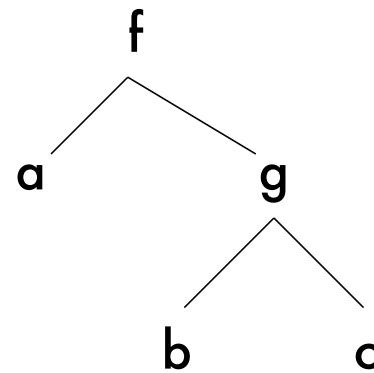
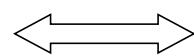
Depth of the best program per generation versus average program depth

[Jacob 2001, Ch. 9]

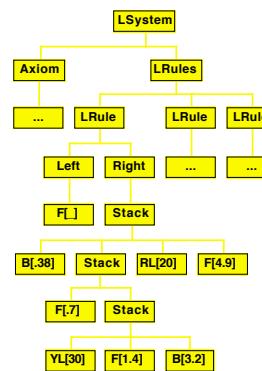
How to Generate a 'Gene Pool' of Programs



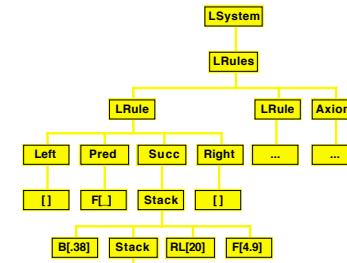
Formulas / Expressions as 'Tree Structures'

$$f(a, g(b, c))$$


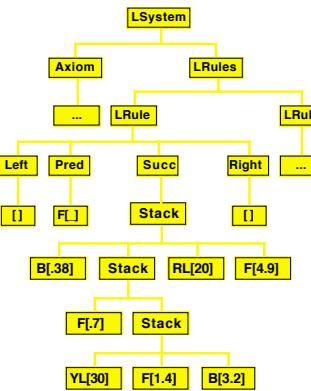
Population of Symbolic Expressions



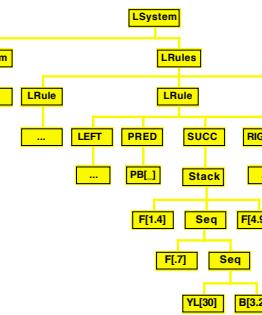
Program 1



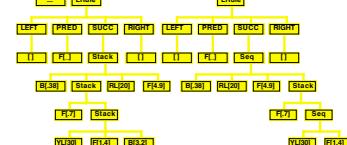
Program 2



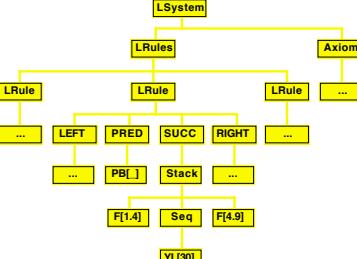
Program 3



Program 4

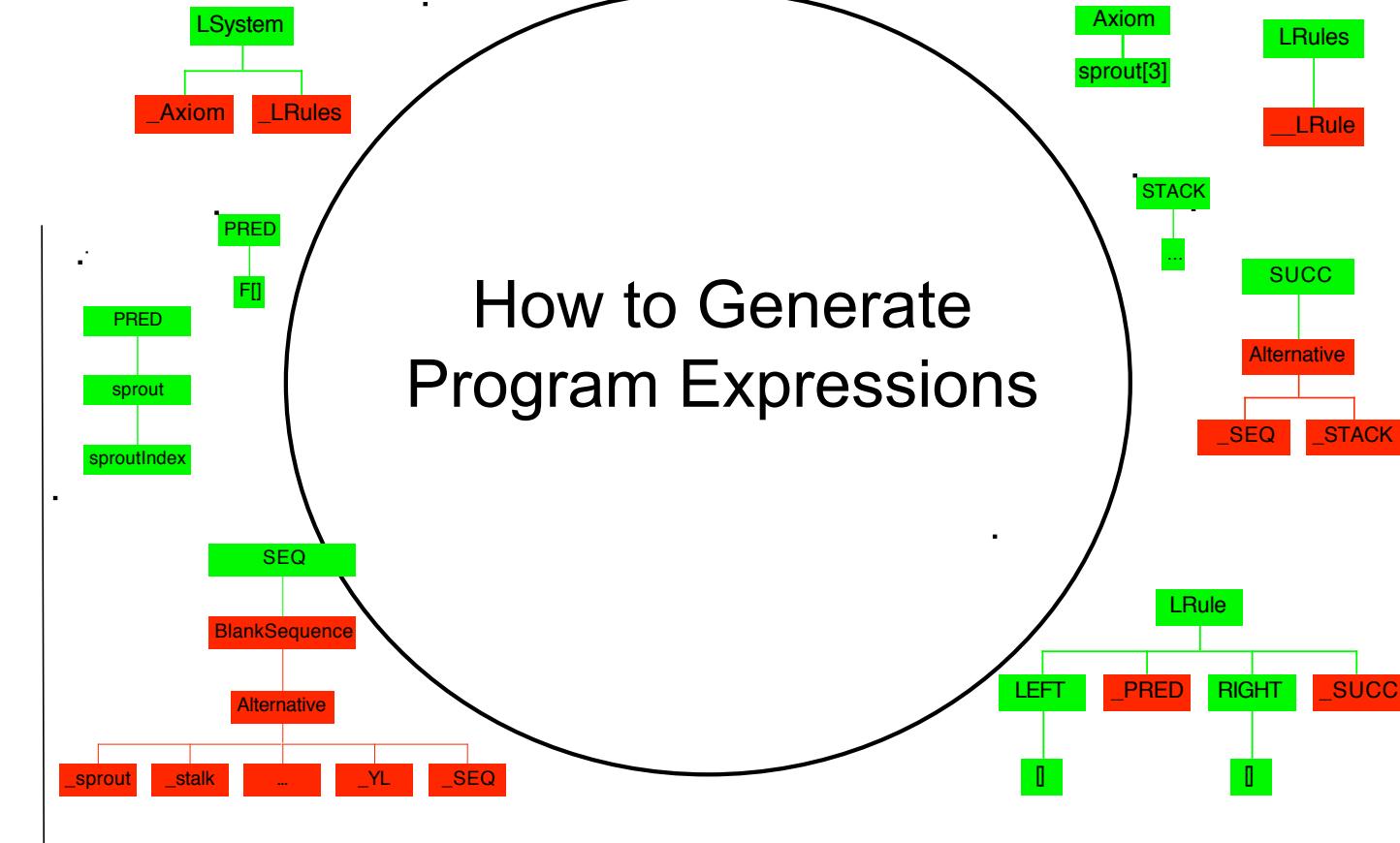


Program 5

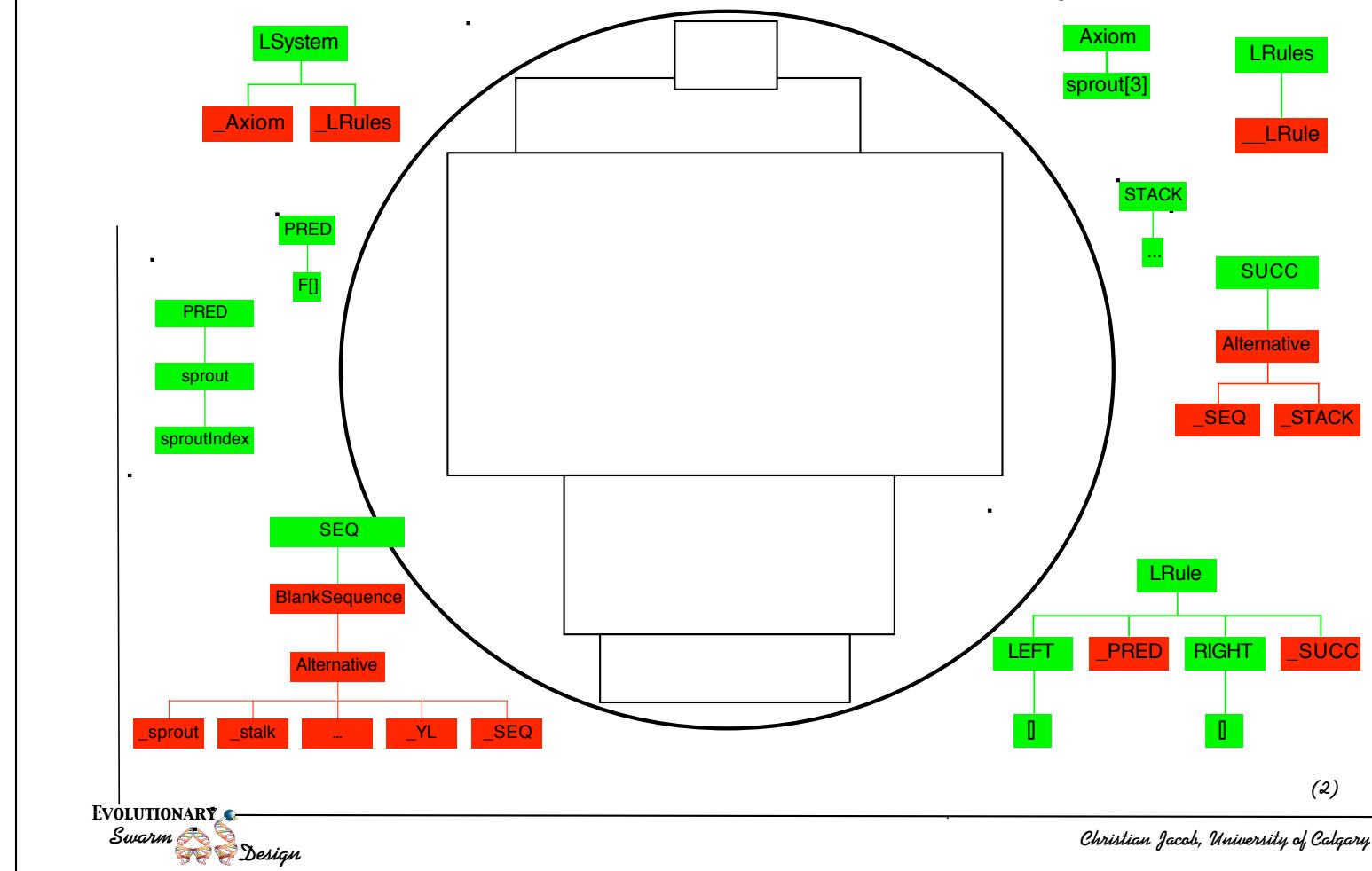


Program 6

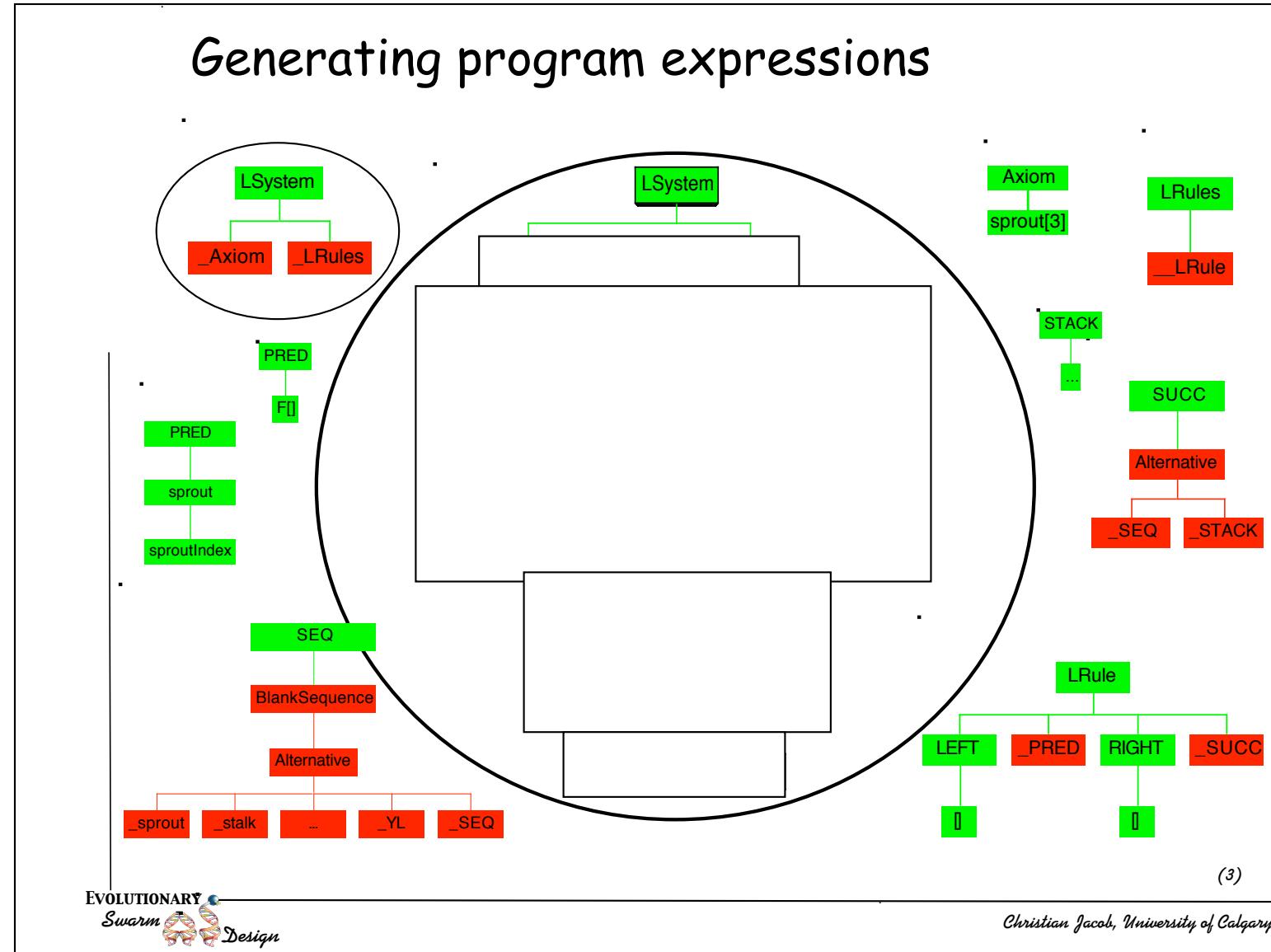
How to Generate Program Expressions



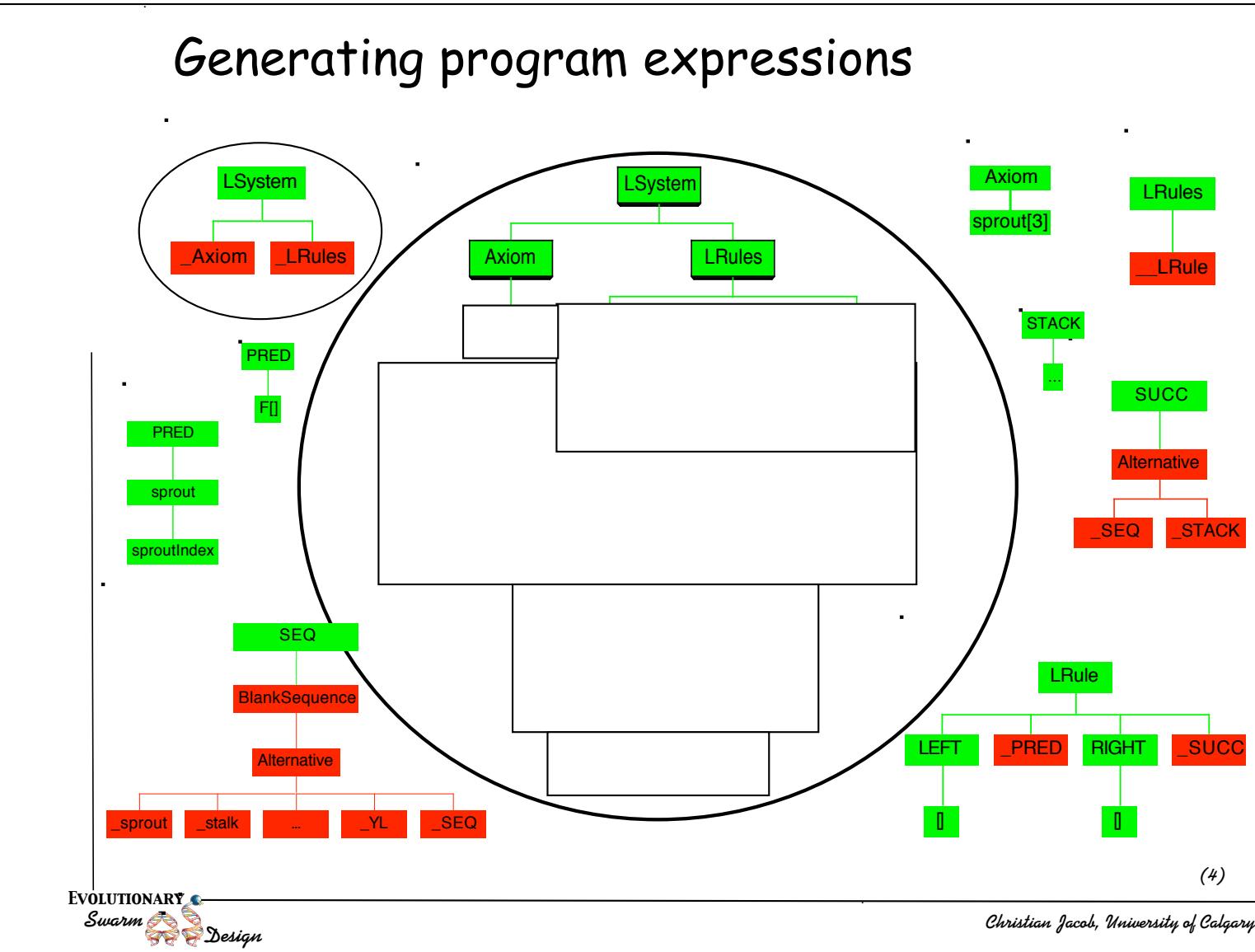
Generating program expressions



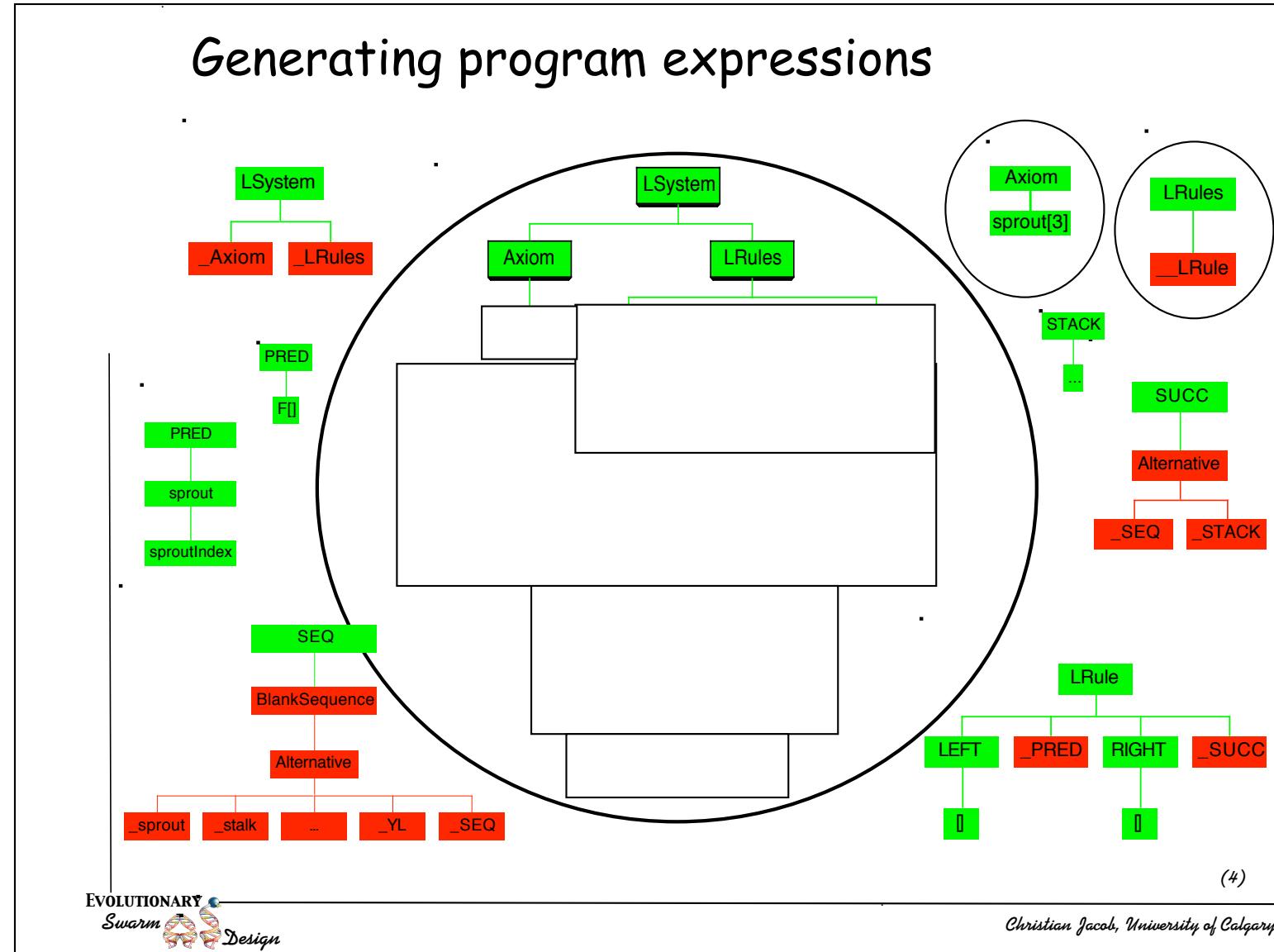
Generating program expressions



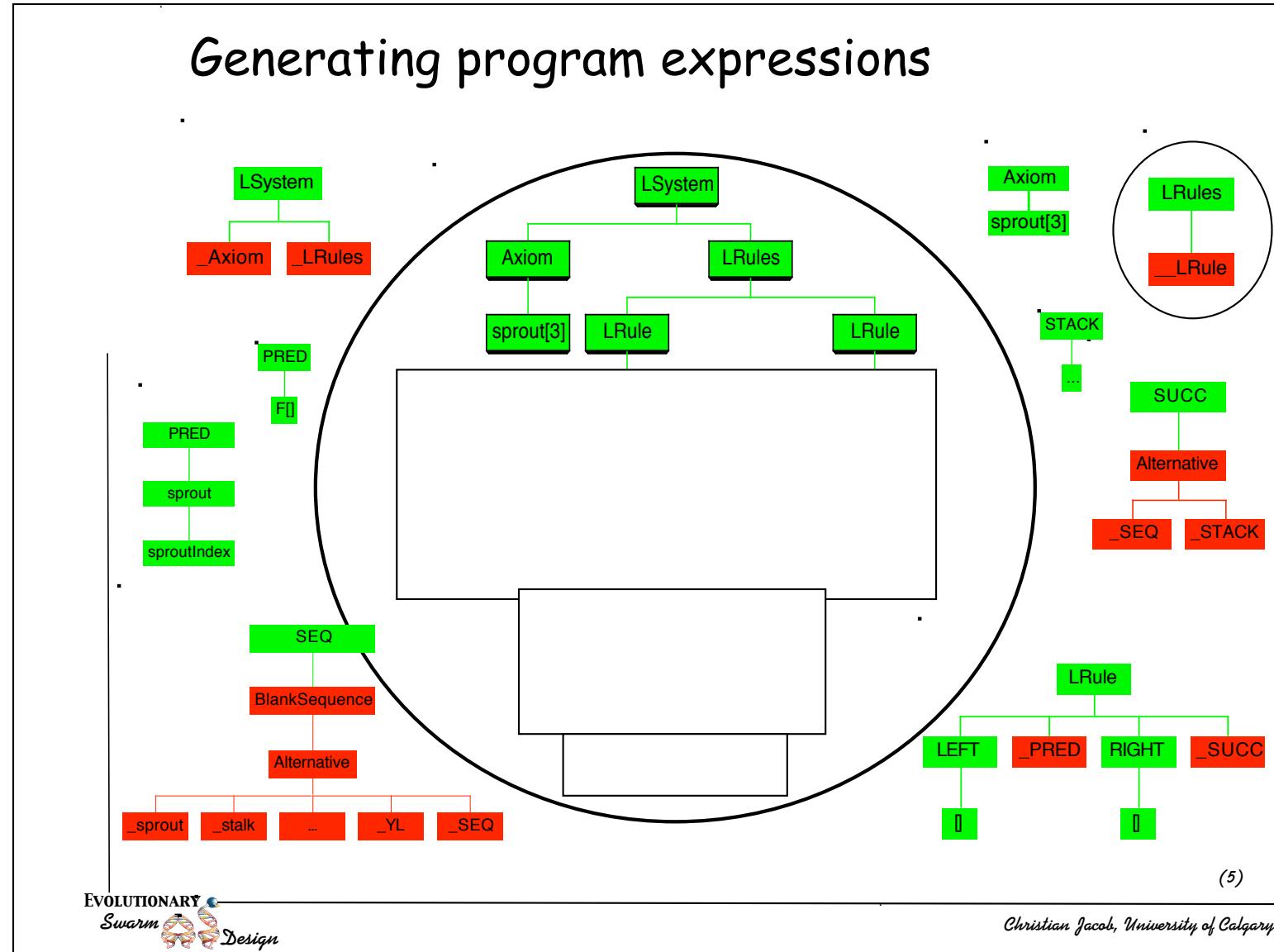
Generating program expressions



Generating program expressions

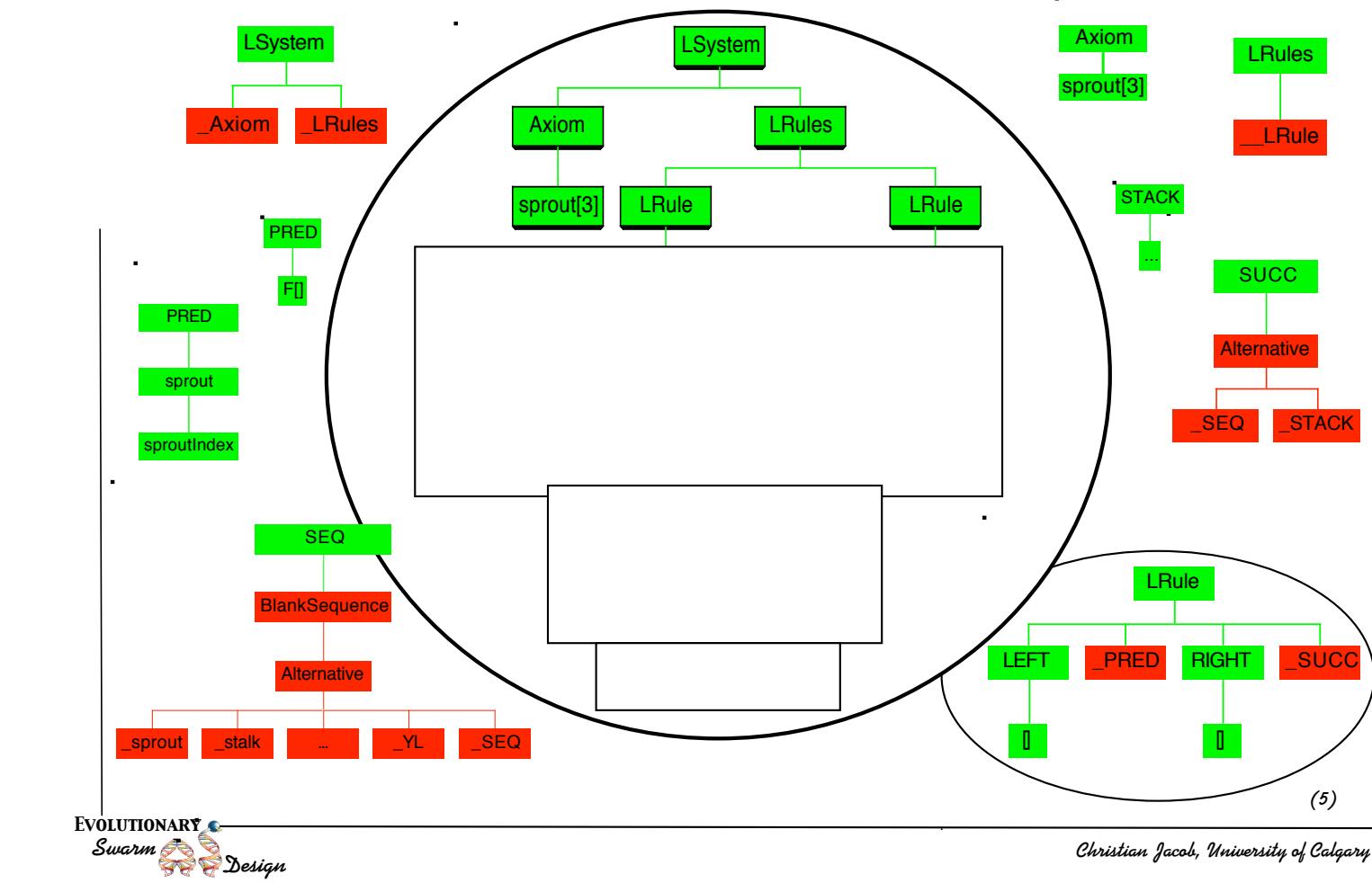


Generating program expressions

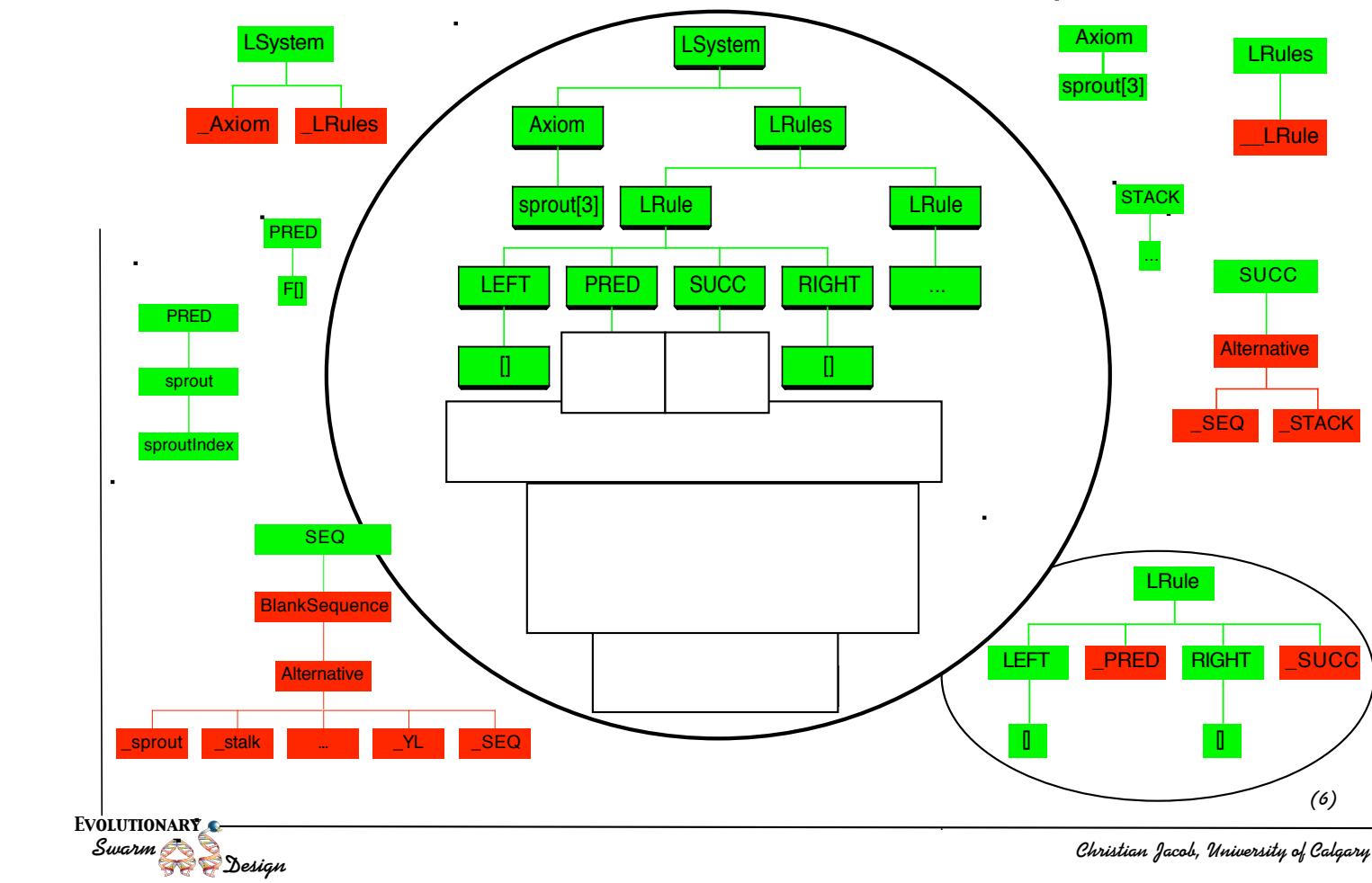


(5)

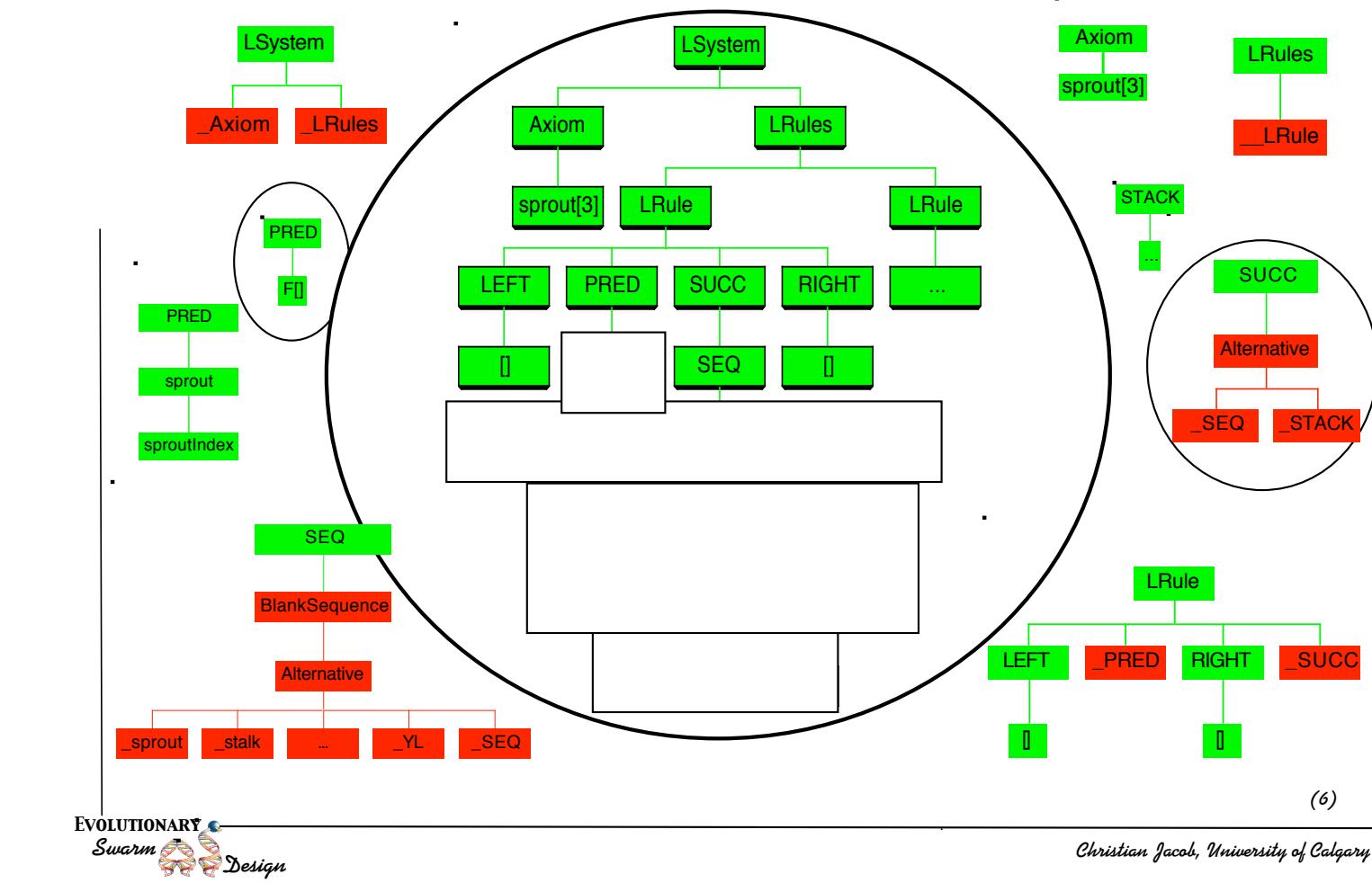
Generating program expressions



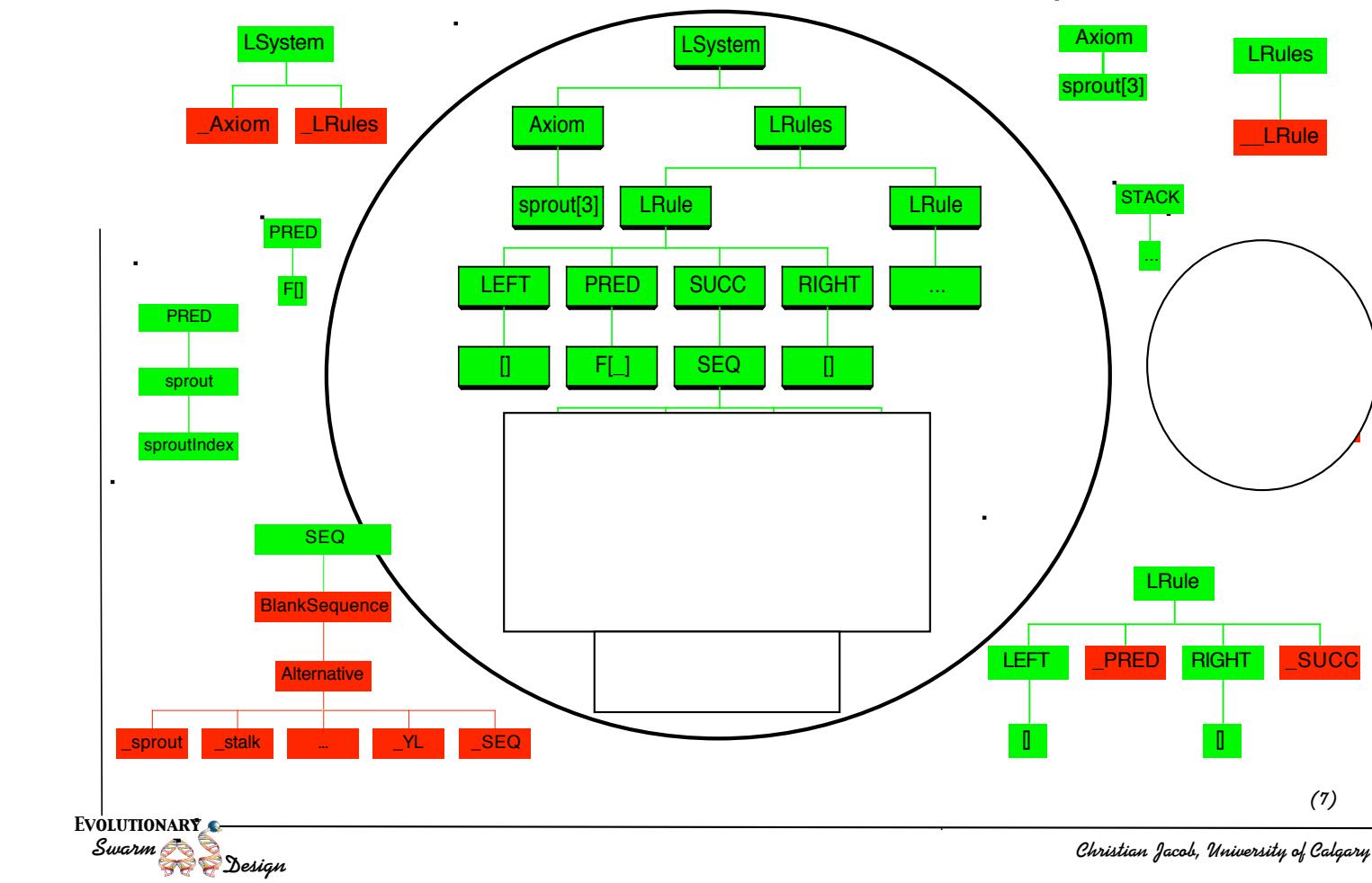
Generating program expressions



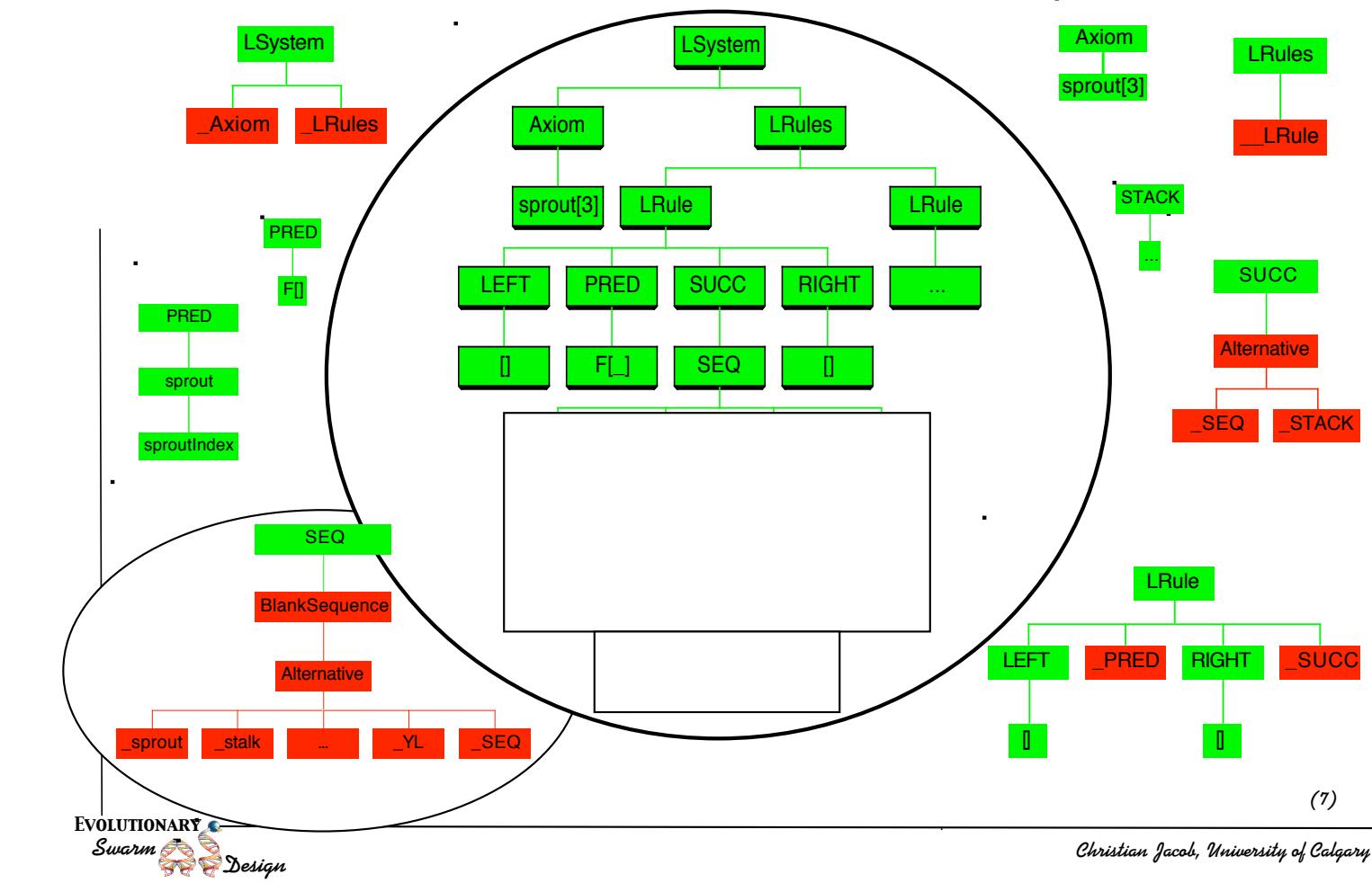
Generating program expressions



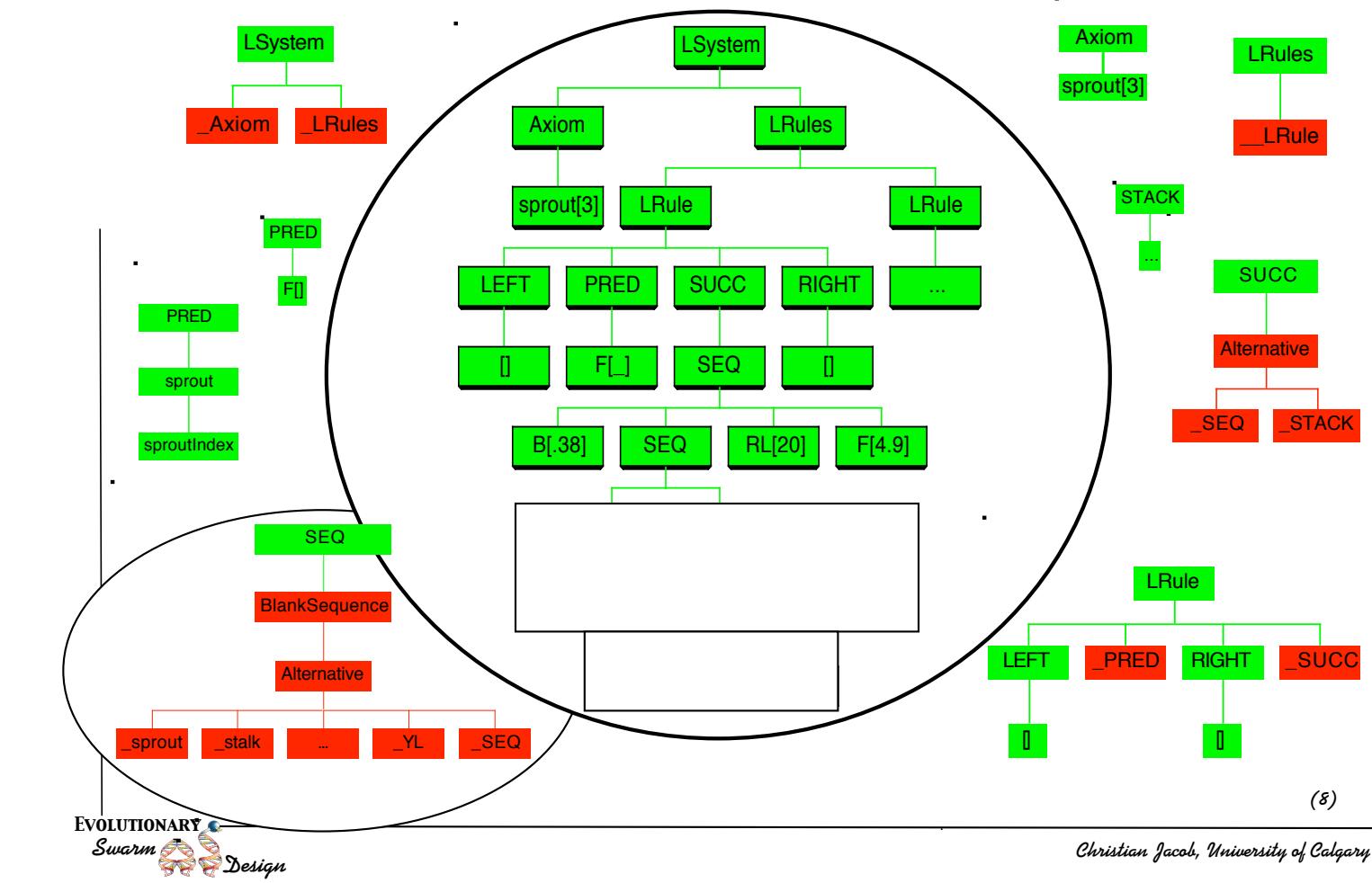
Generating program expressions



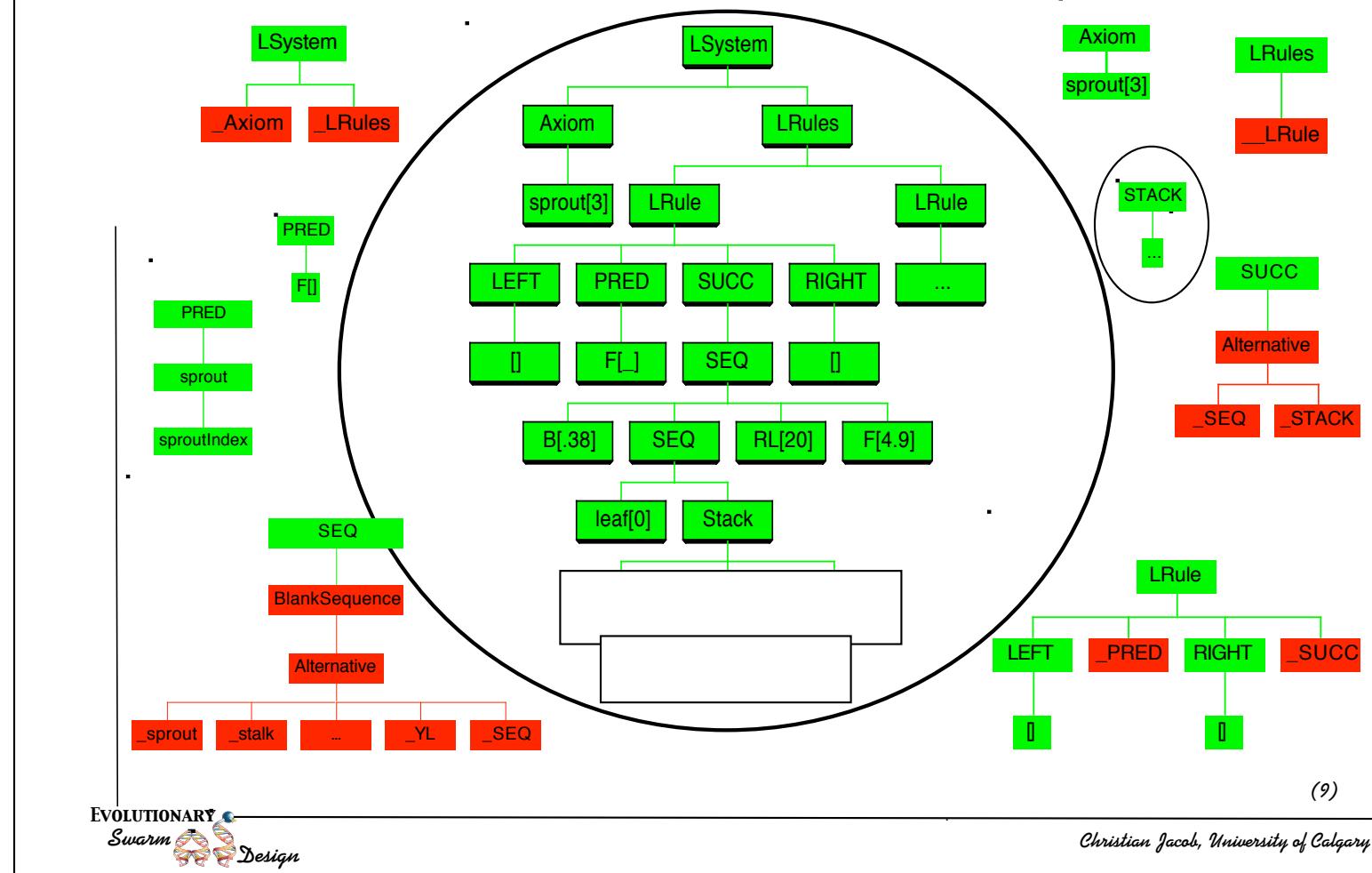
Generating program expressions



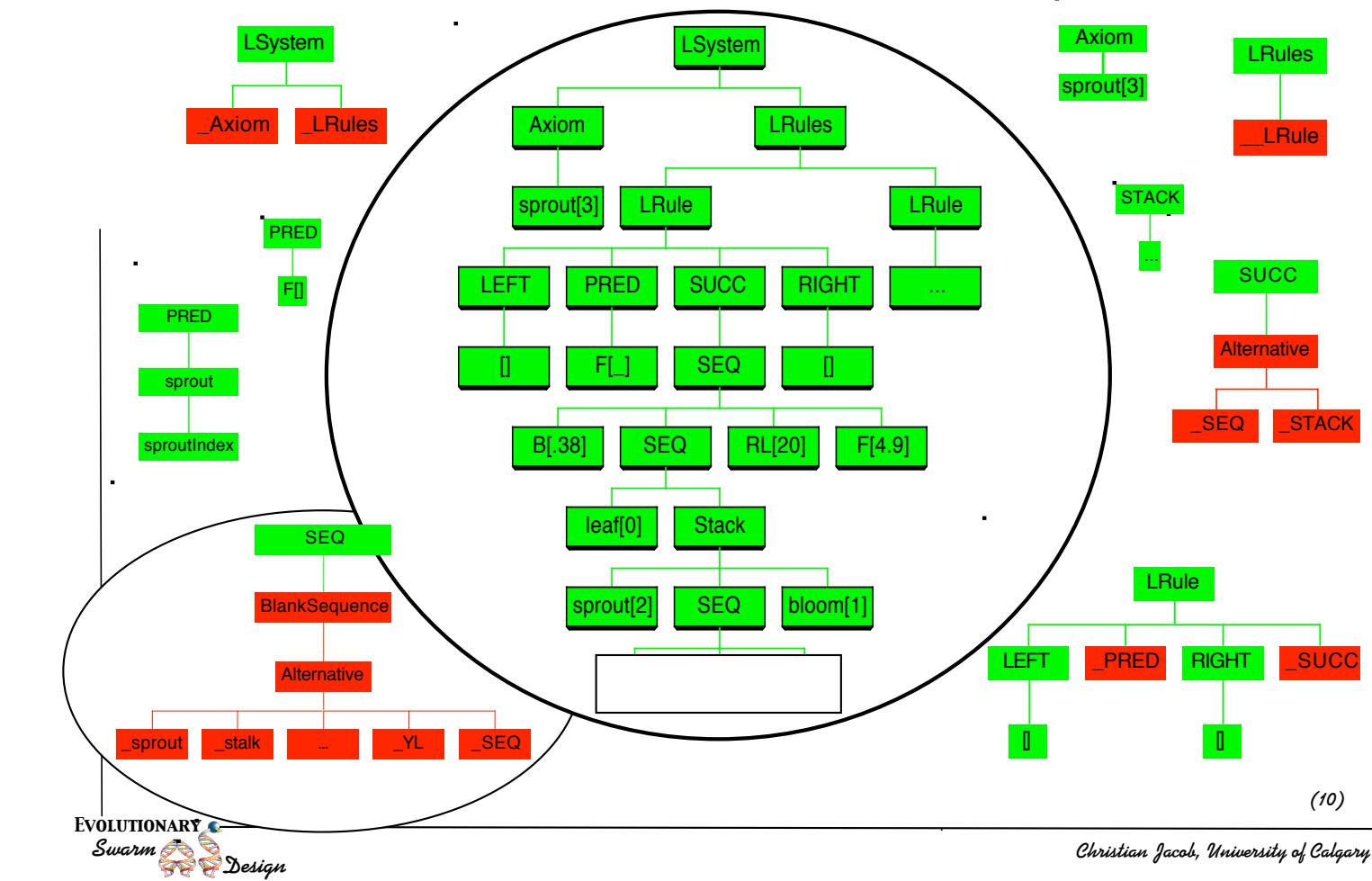
Generating program expressions



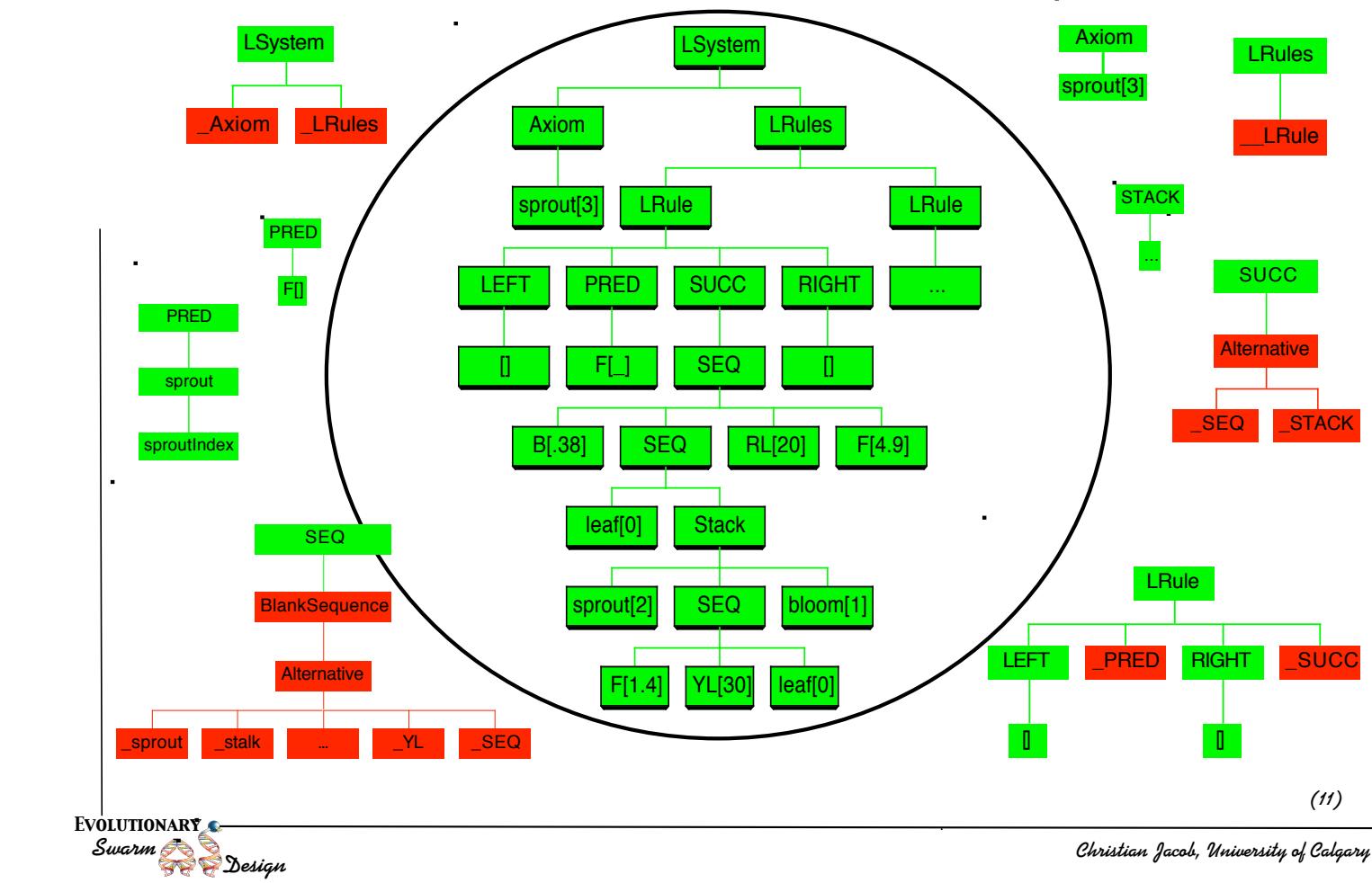
Generating program expressions



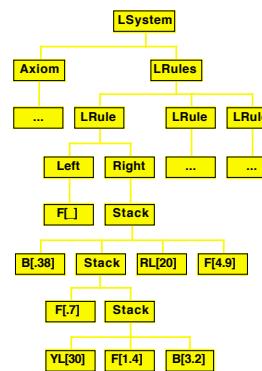
Generating program expressions



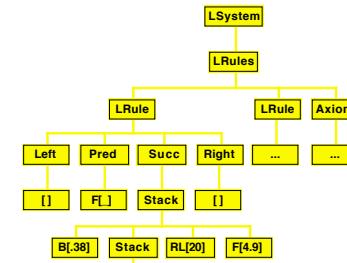
Generating program expressions



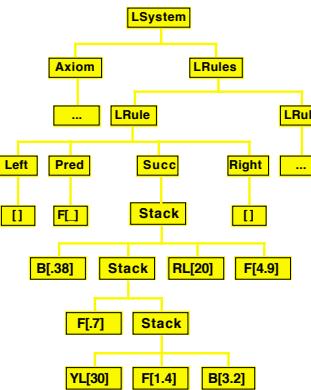
Population of Symbolic Expressions



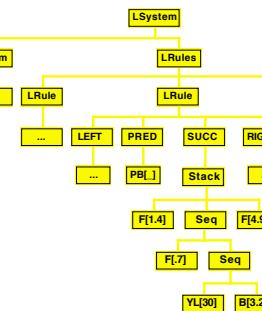
Program 1



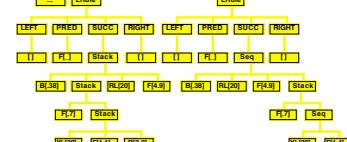
Program 2



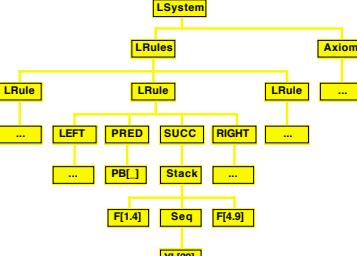
Program 3



Program 4

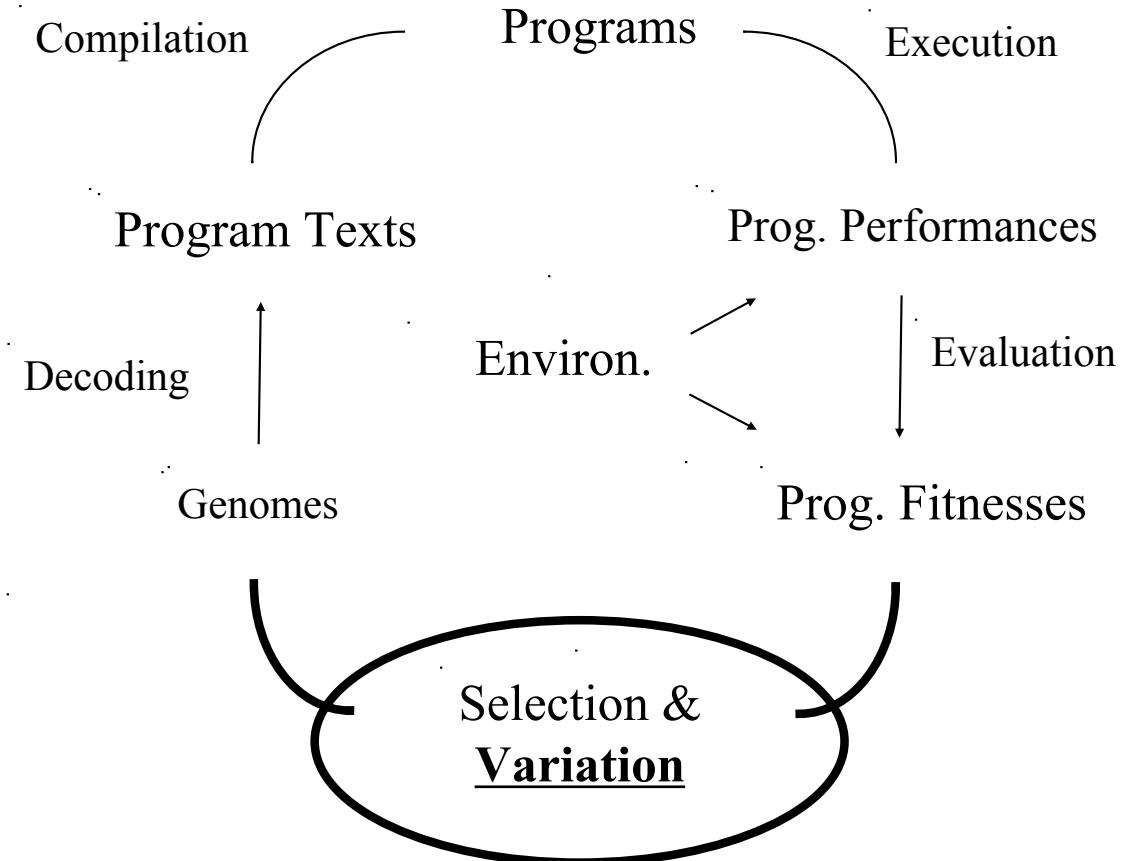


Program 5



Program 6

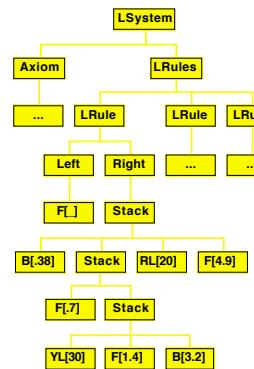
How to Diversify the Programs ...



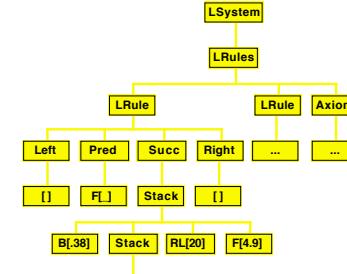
How to Diversify the Programs ...

- **Genetic Operators on Symbolic Expressions**
- Crossover
- Mutation
 - Point Mutation
 - Tree Mutation
- Permutation
- Hoisting
- Deletion, Shrinking
- Expansion
- Duplication
- Encapsulation / Decapsulation

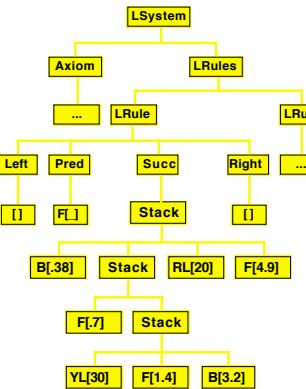
CROSSOVER on Symbolic Expressions



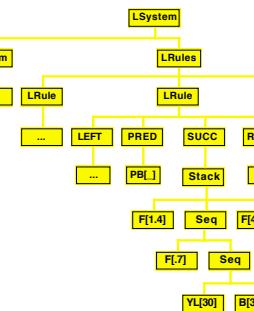
Program 1



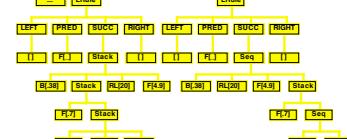
Program 2



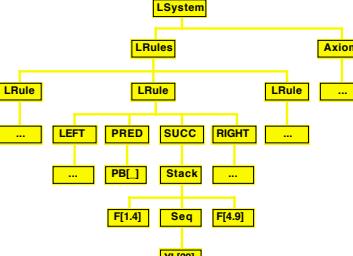
Program 3



Program 4

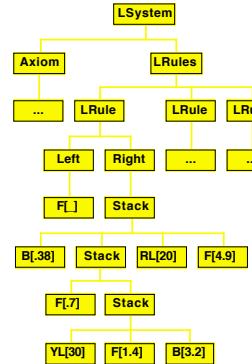


Program 5

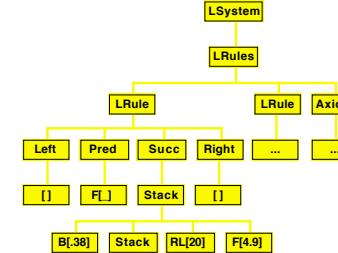


Program 6

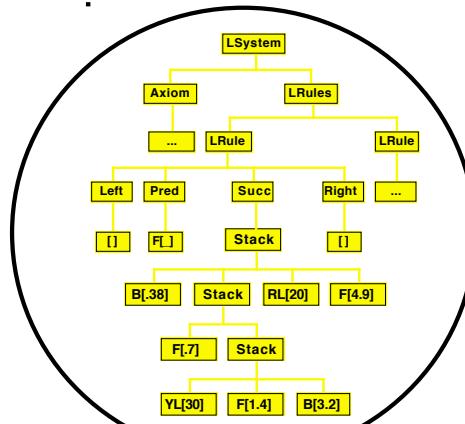
CROSSOVER on Symbolic Expressions



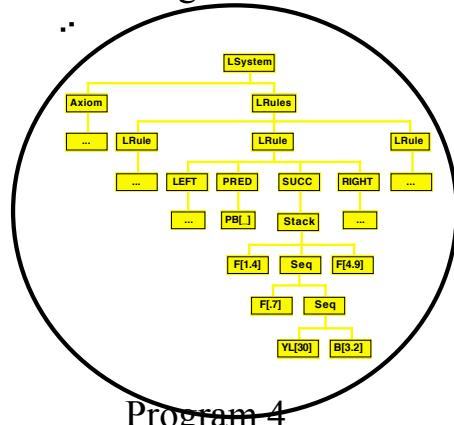
Program 1



Program 2

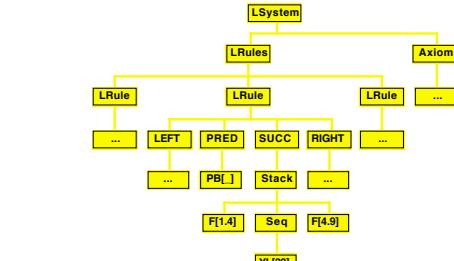


Program 3



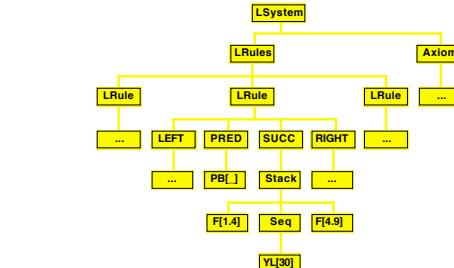
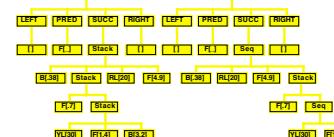
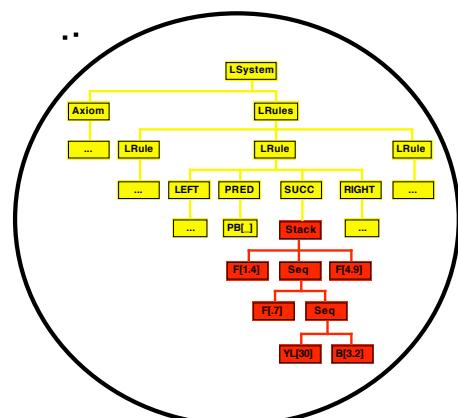
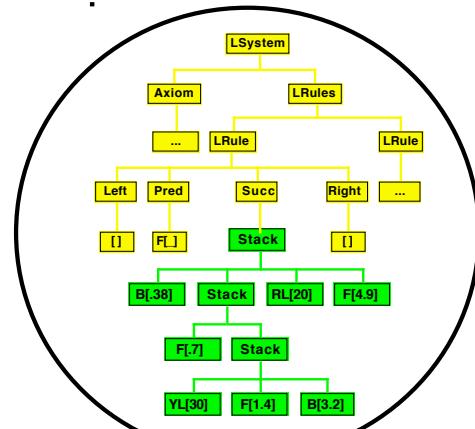
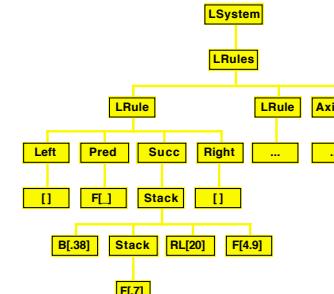
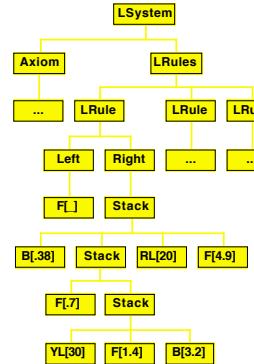
Program 4

Program 5

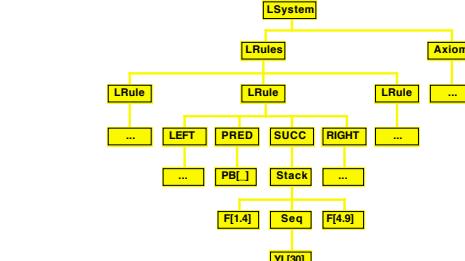
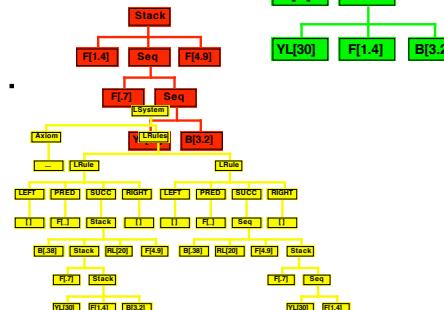
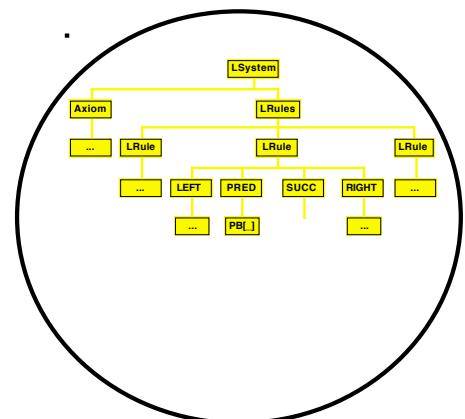
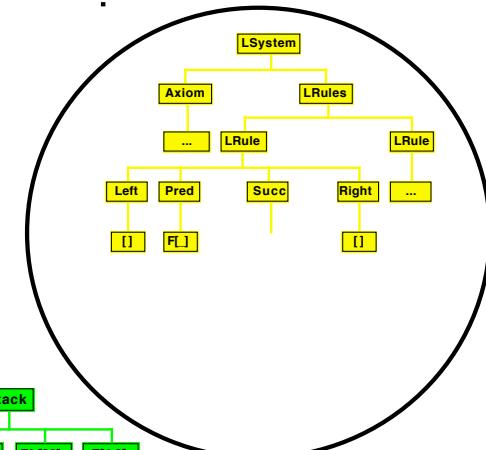
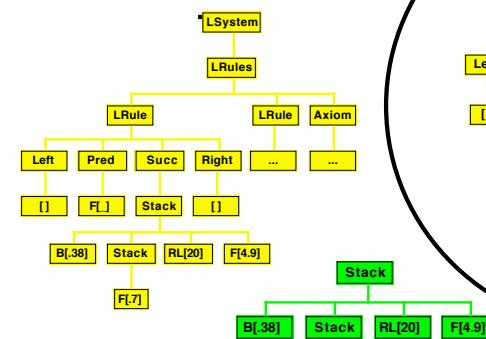
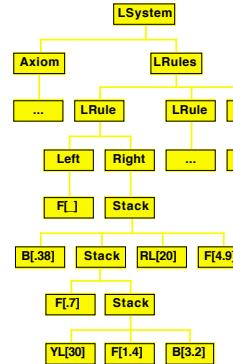


Program 6

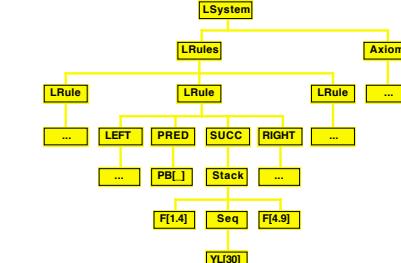
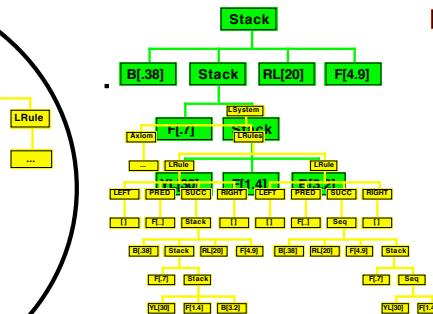
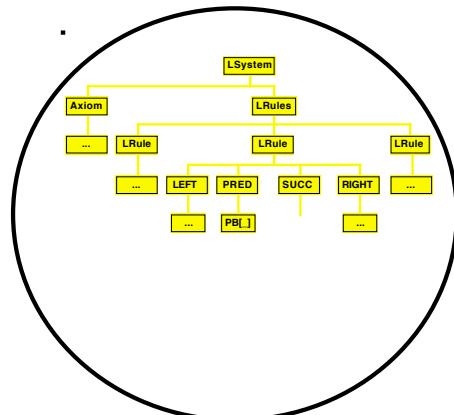
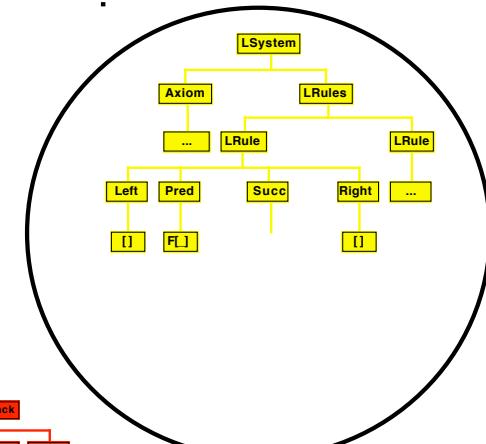
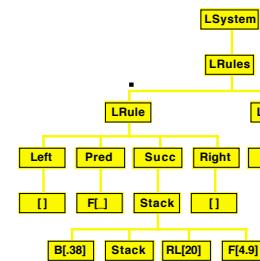
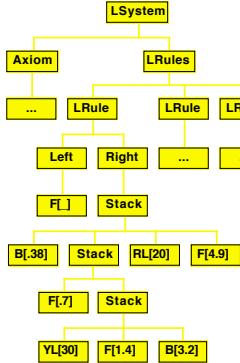
CROSSOVER on Symbolic Expressions



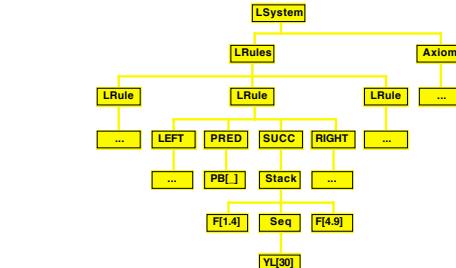
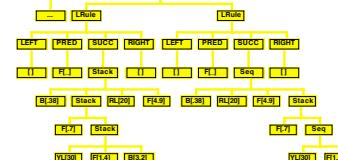
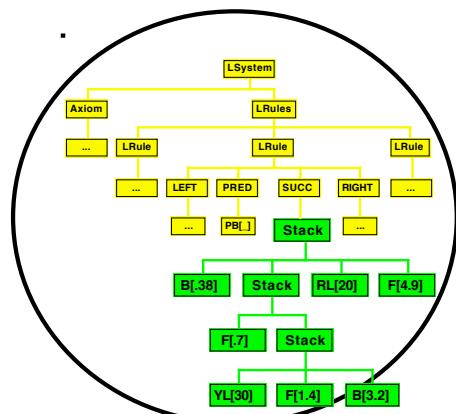
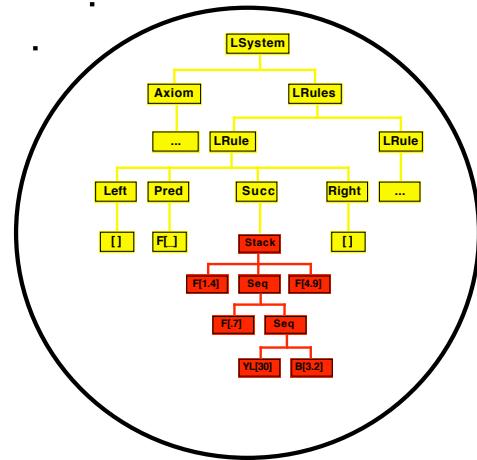
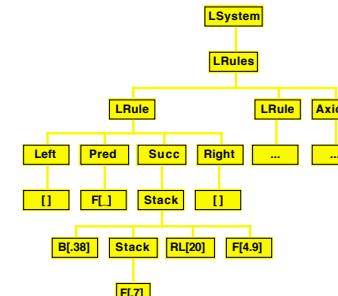
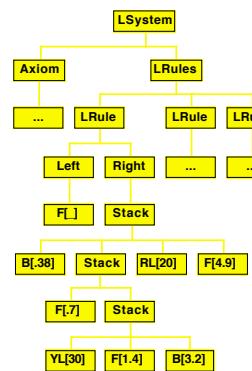
Crossover on Symbolic Expressions



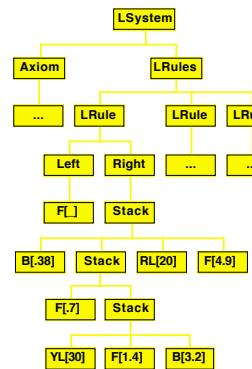
CROSSOVER on Symbolic Expressions



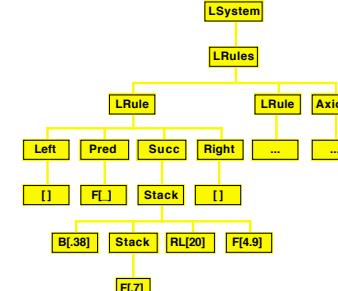
CROSSOVER on Symbolic Expressions



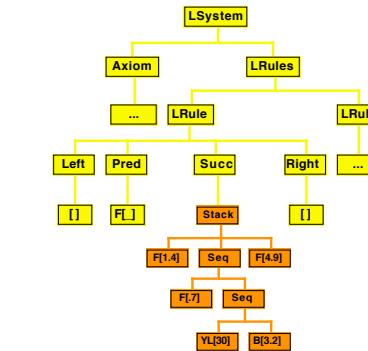
CROSSOVER on Symbolic Expressions



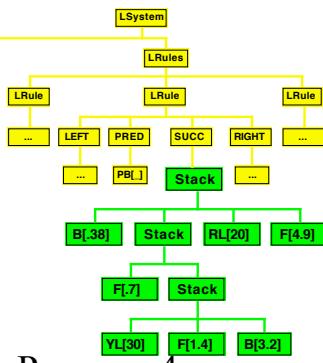
Program 1



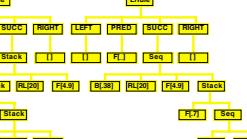
Program 2



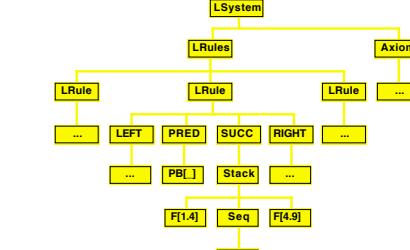
Program 3



Program 4



Program 5

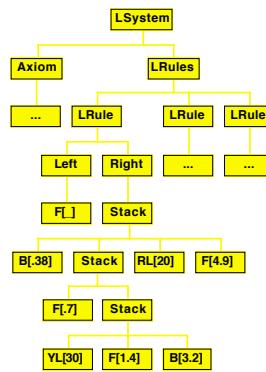


Program 6

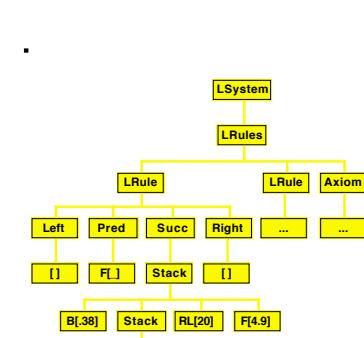
How to Diversify the Programs ... (2)

- **Genetic Operators on Symbolic Expressions**
- Crossover
- Mutation
 - Point Mutation
 - Tree Mutation
- Permutation
- Hoisting
- Deletion, Shrinking
- Expansion
- Duplication
- Encapsulation / Decapsulation

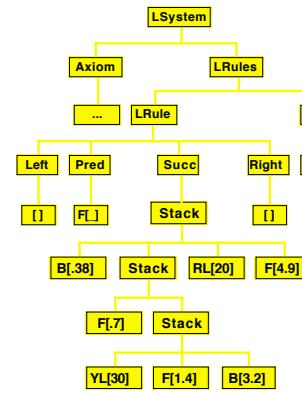
MUTATION on Symbolic Expressions



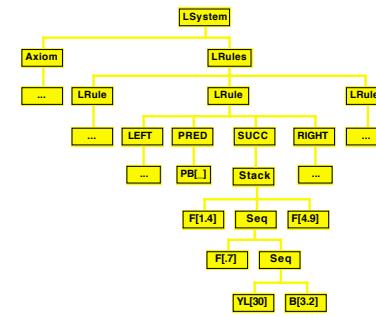
Program 1



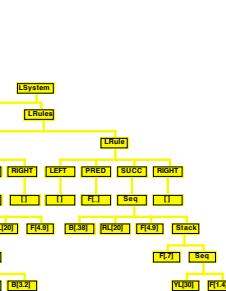
Program 2



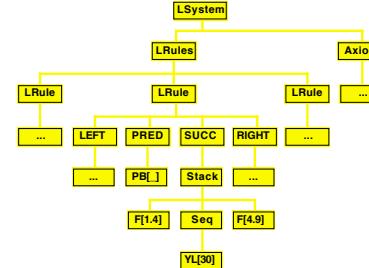
Program 3



Program 4

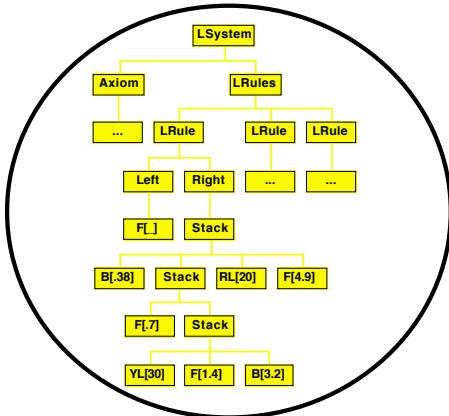


Program 5

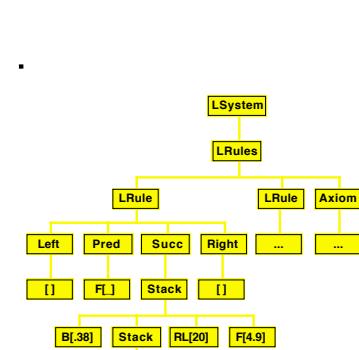


Program 6

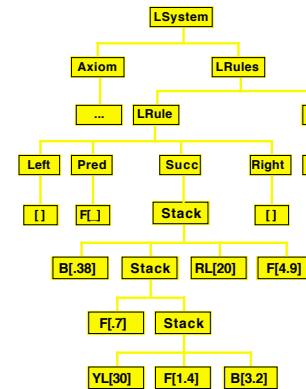
MUTATION on Symbolic Expressions



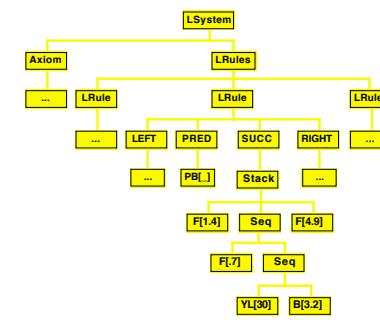
Program 1



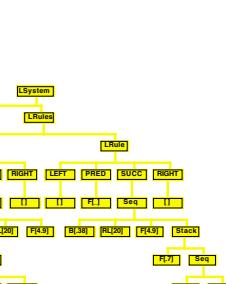
Program 2



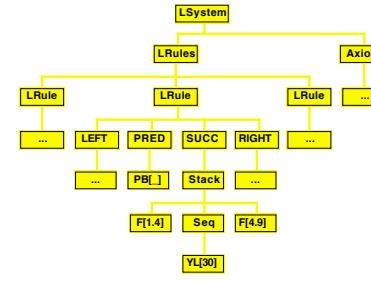
Program 3



Program 4

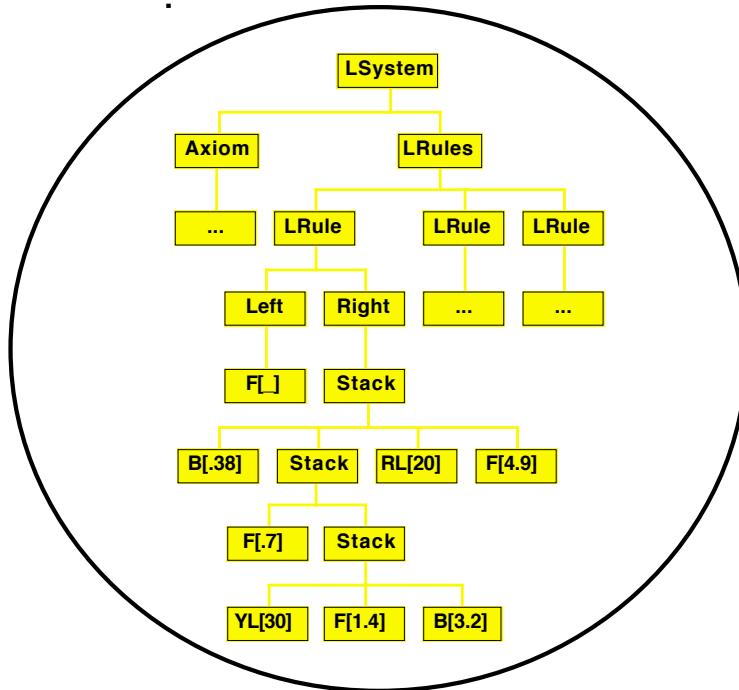


Program 5



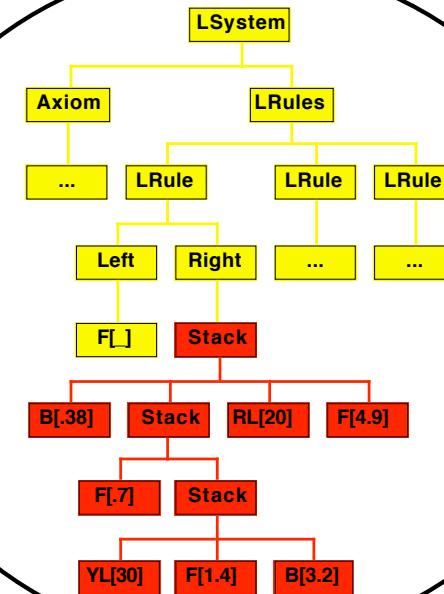
Program 6

MUTATION on a Symbolic Expression

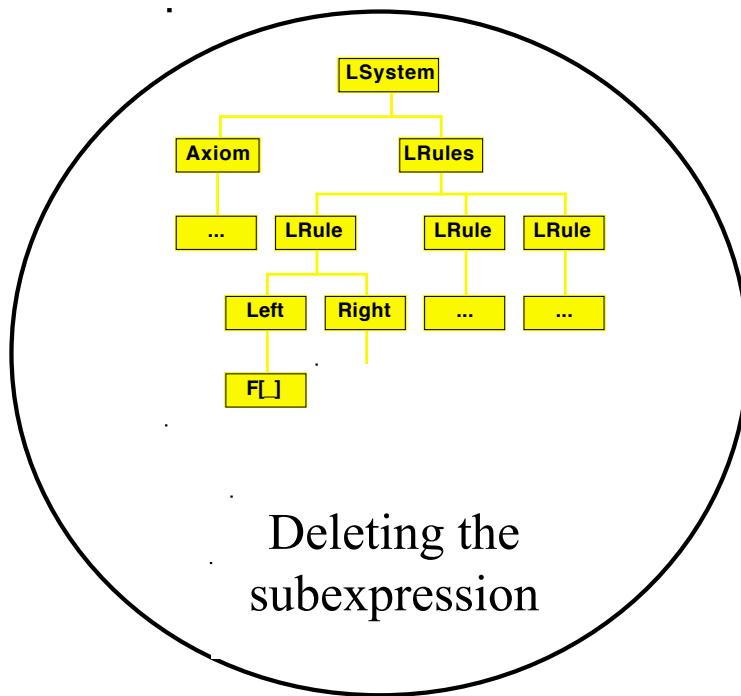


MUTATION on a Symbolic Expression

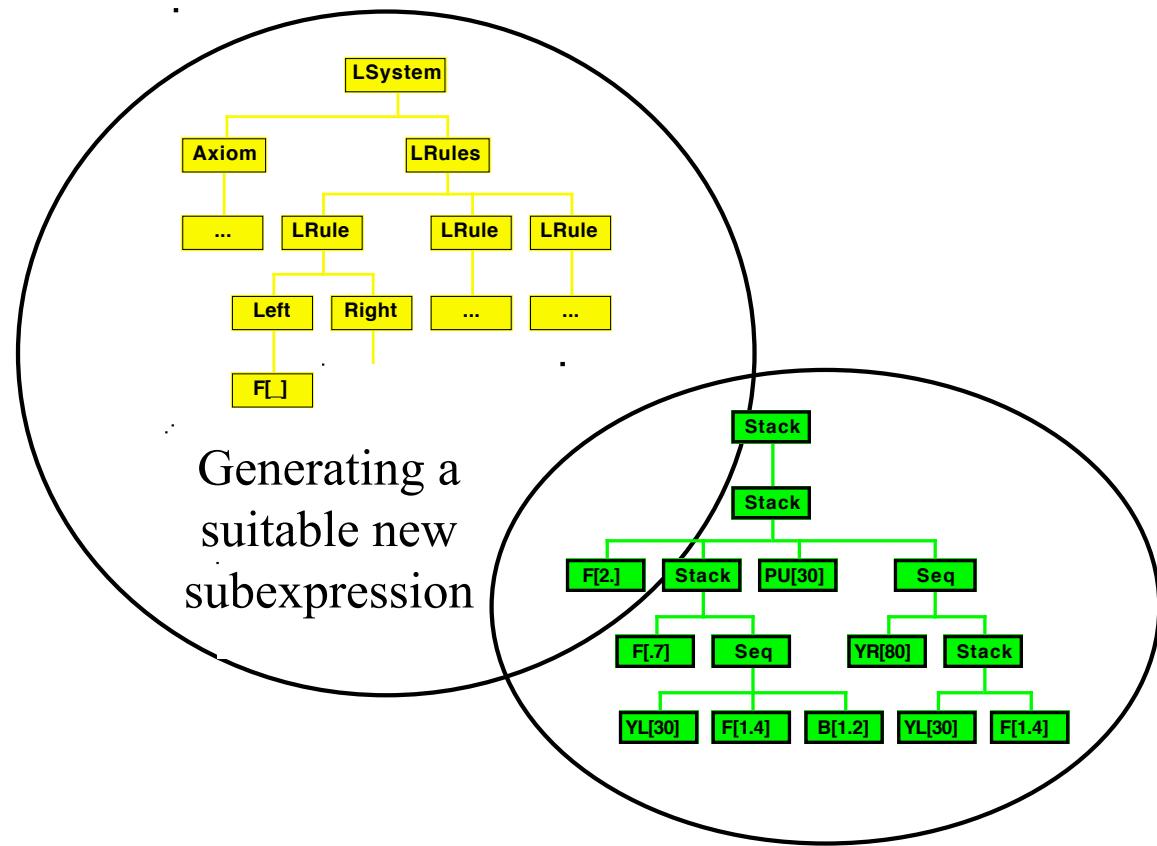
Probabilistic
selection of a
subexpression



MUTATION on a Symbolic Expression

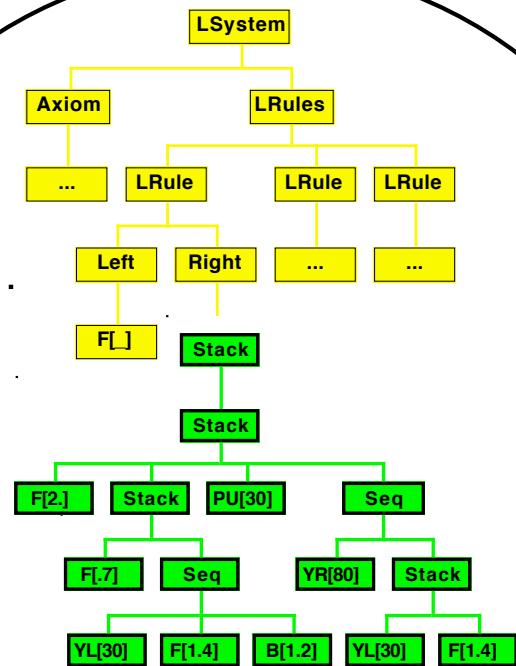


MUTATION on a Symbolic Expression

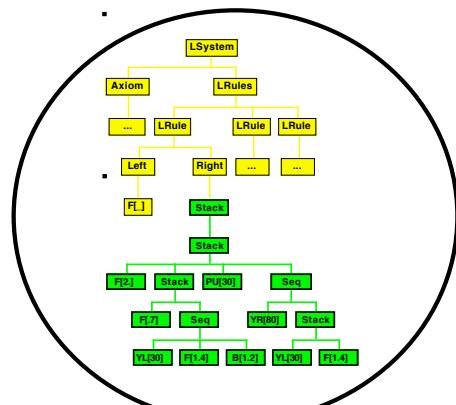


MUTATION on a Symbolic Expression

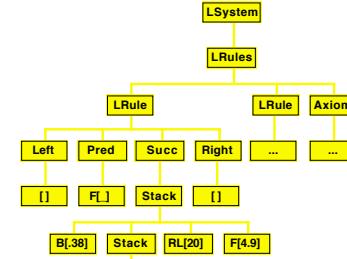
Composing
the mutated
program



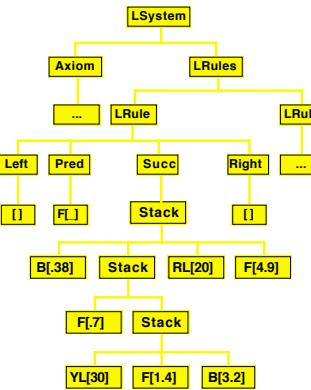
MUTATION on Symbolic Expressions



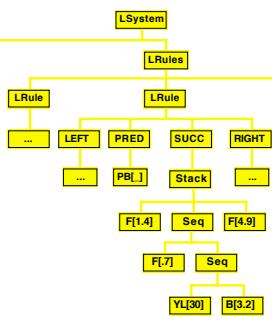
Program 1



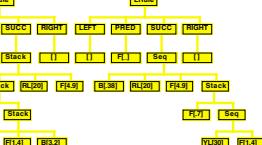
Program 2



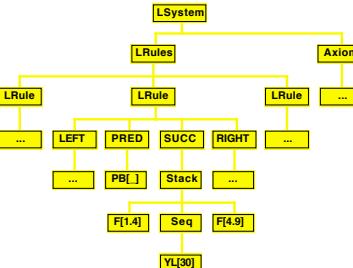
Program 3



Program 4

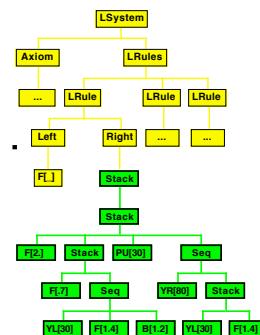


Program 5

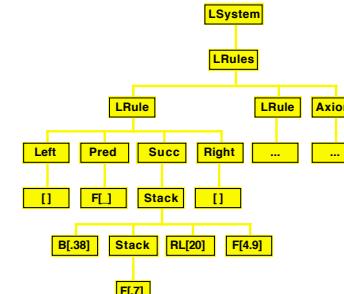


Program 6

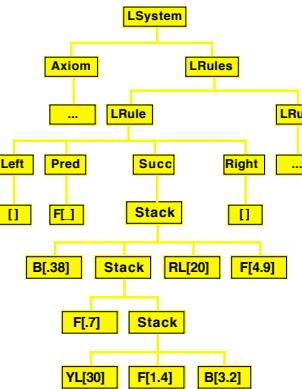
MUTATION on Symbolic Expressions



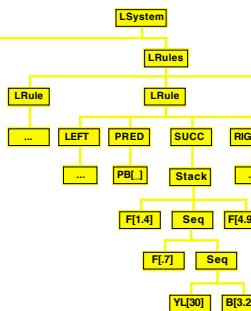
Program 1



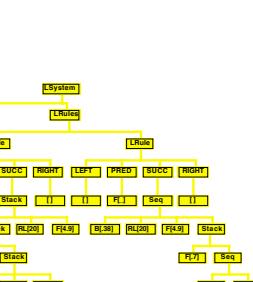
Program 2



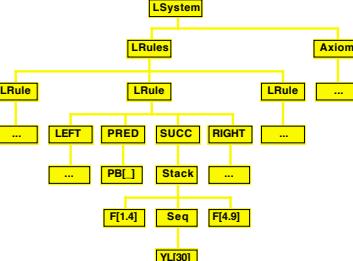
Program 3



Program 4



Program 5

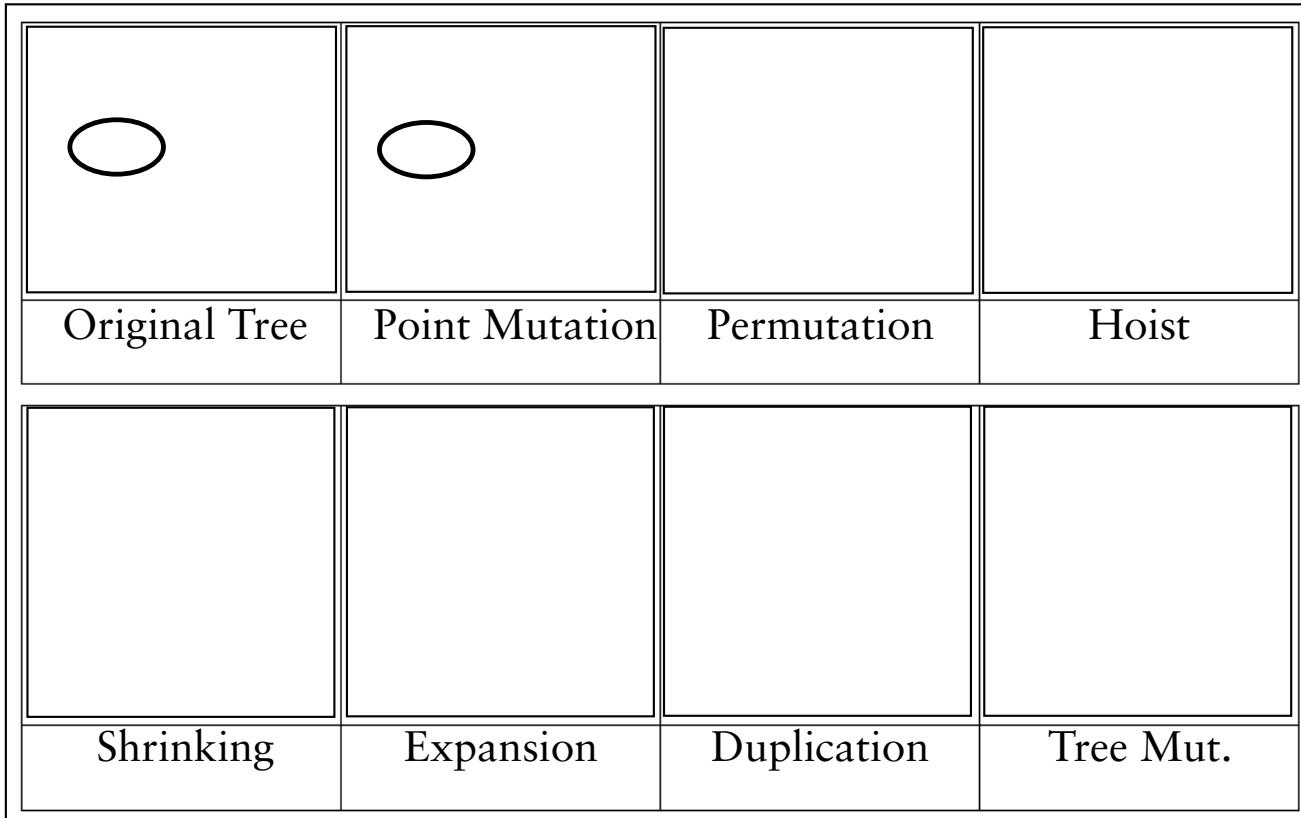


Program 6

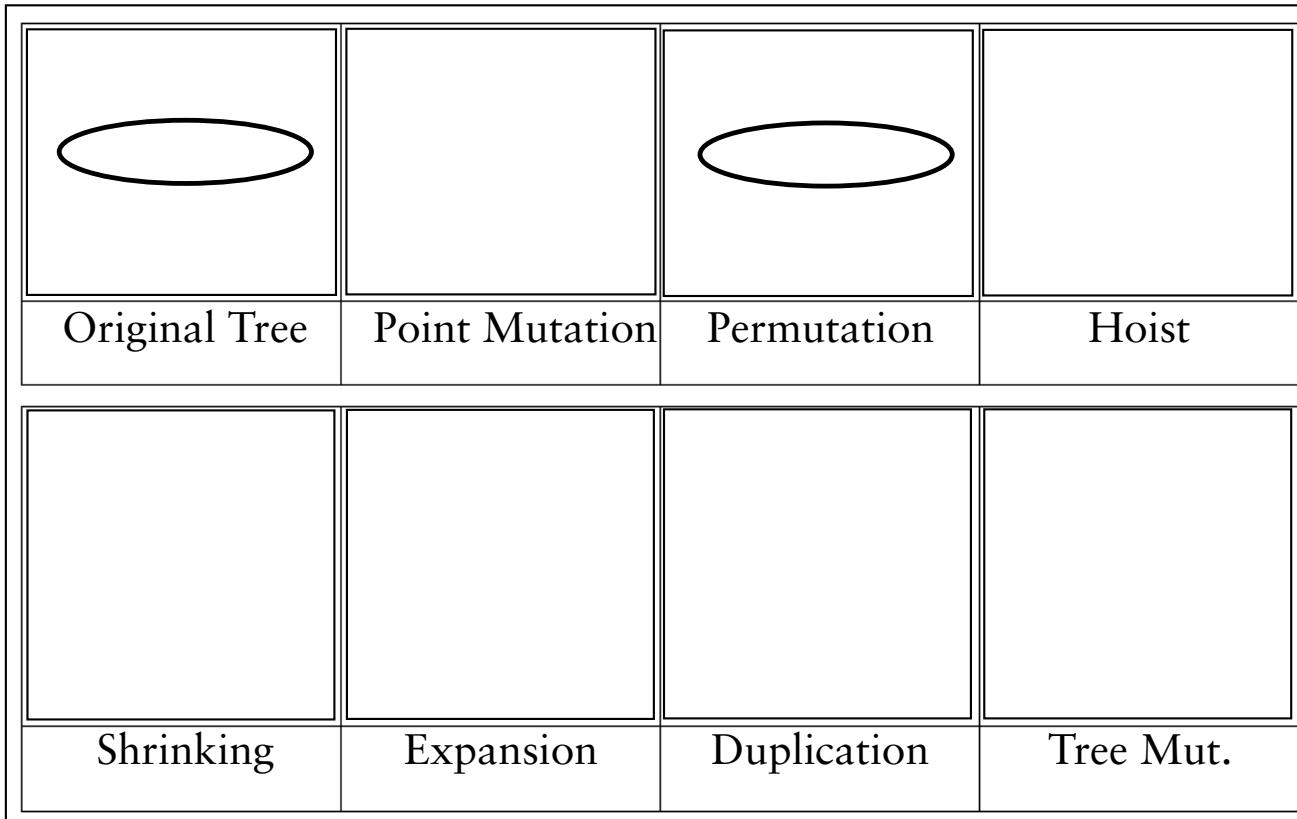
GP Mutation Operators

Original Tree	Point Mutation	Permutation	Hoist
Shrinking	Expansion	Duplication	Tree Mut.

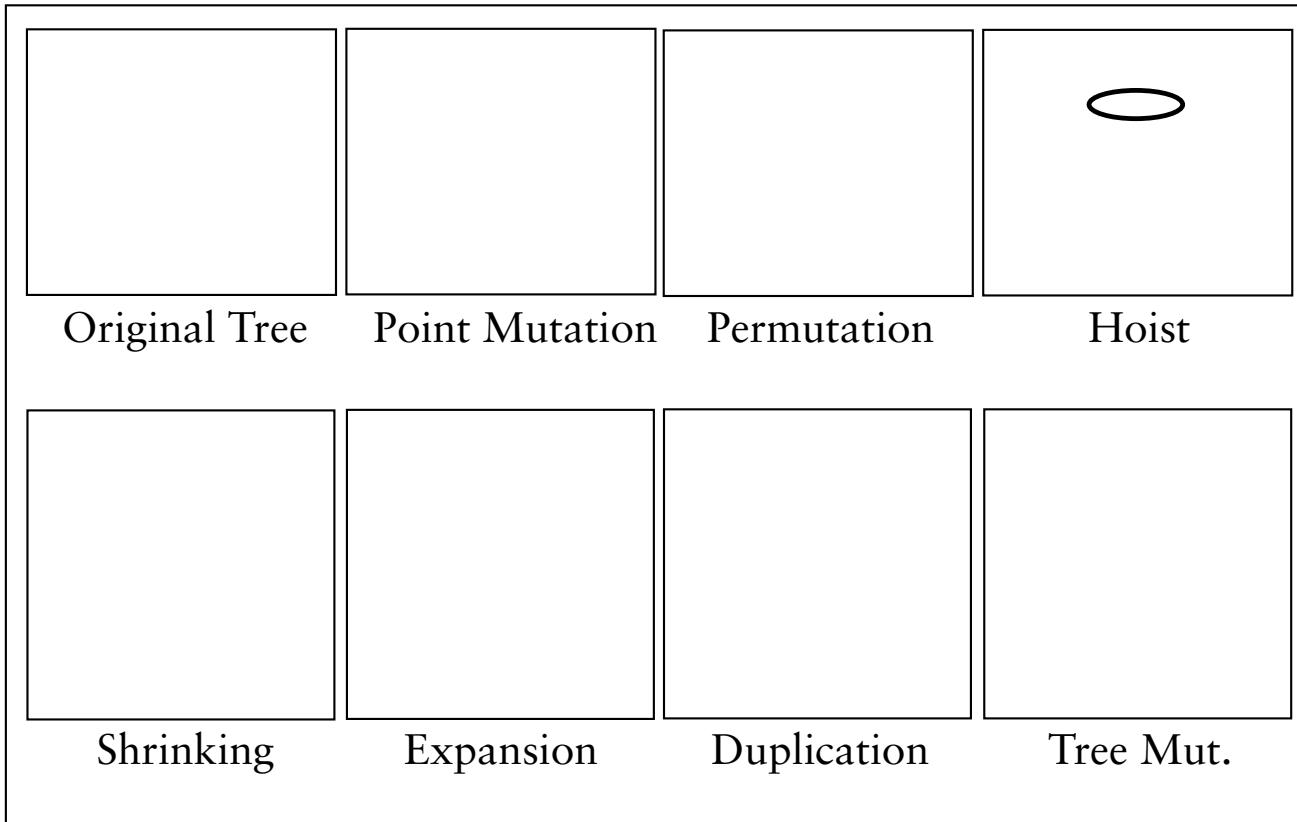
GP Mutation Operators



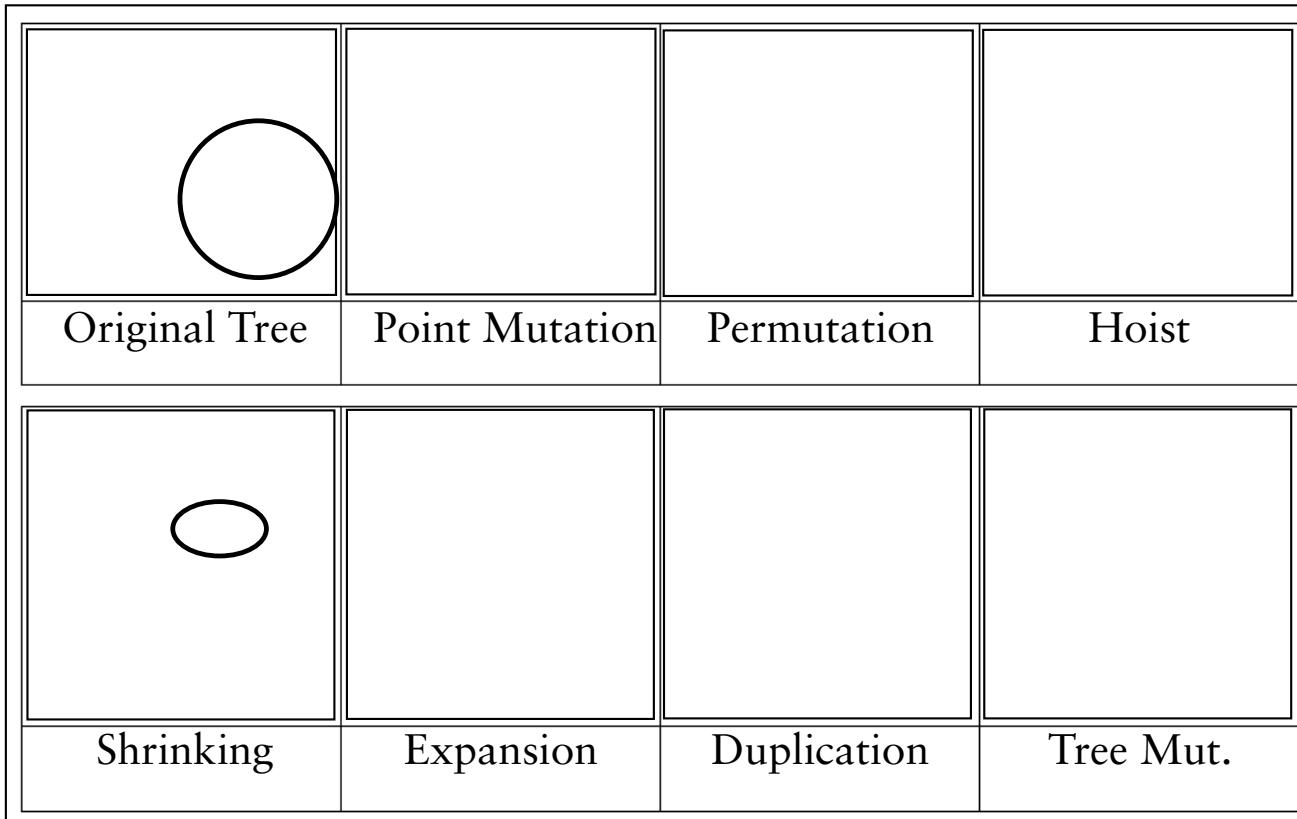
GP Mutation Operators



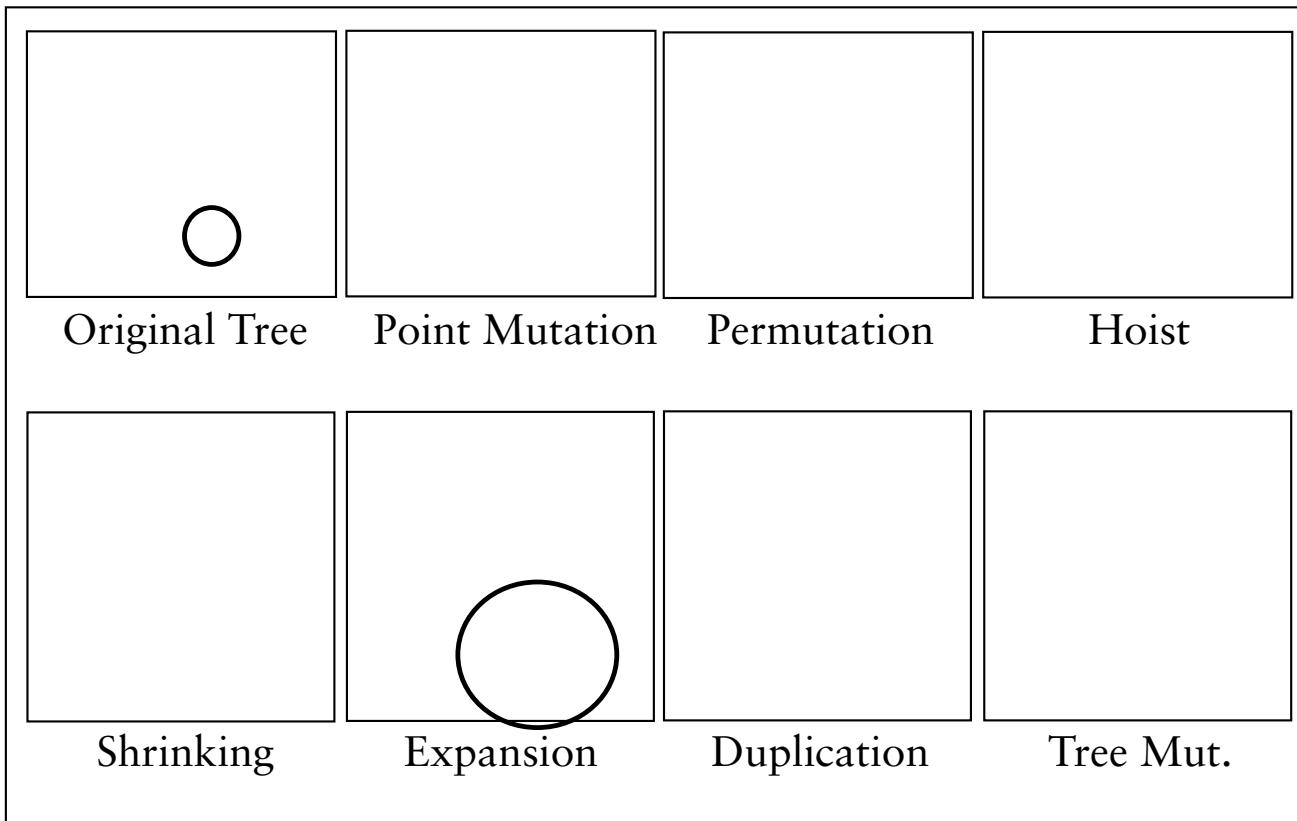
GP Mutation Operators



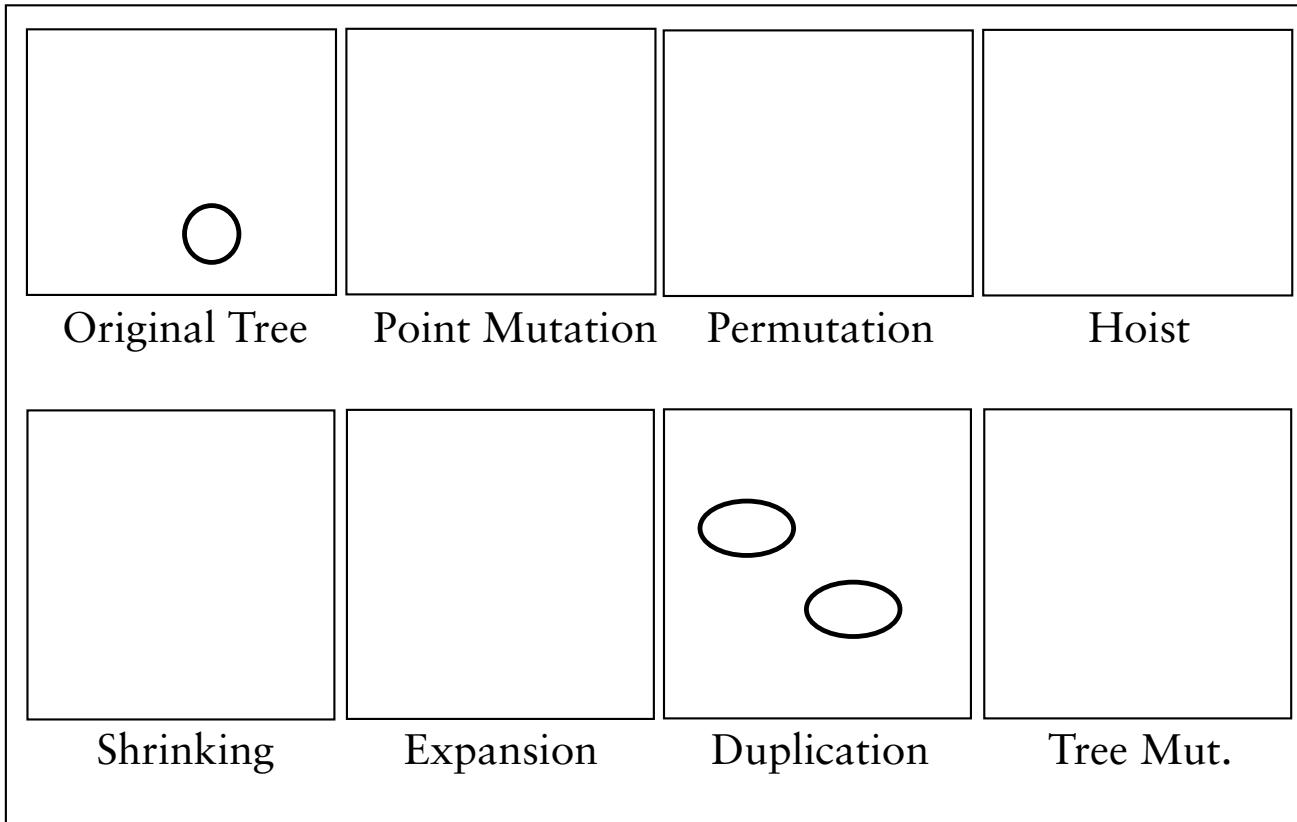
GP Mutation Operators



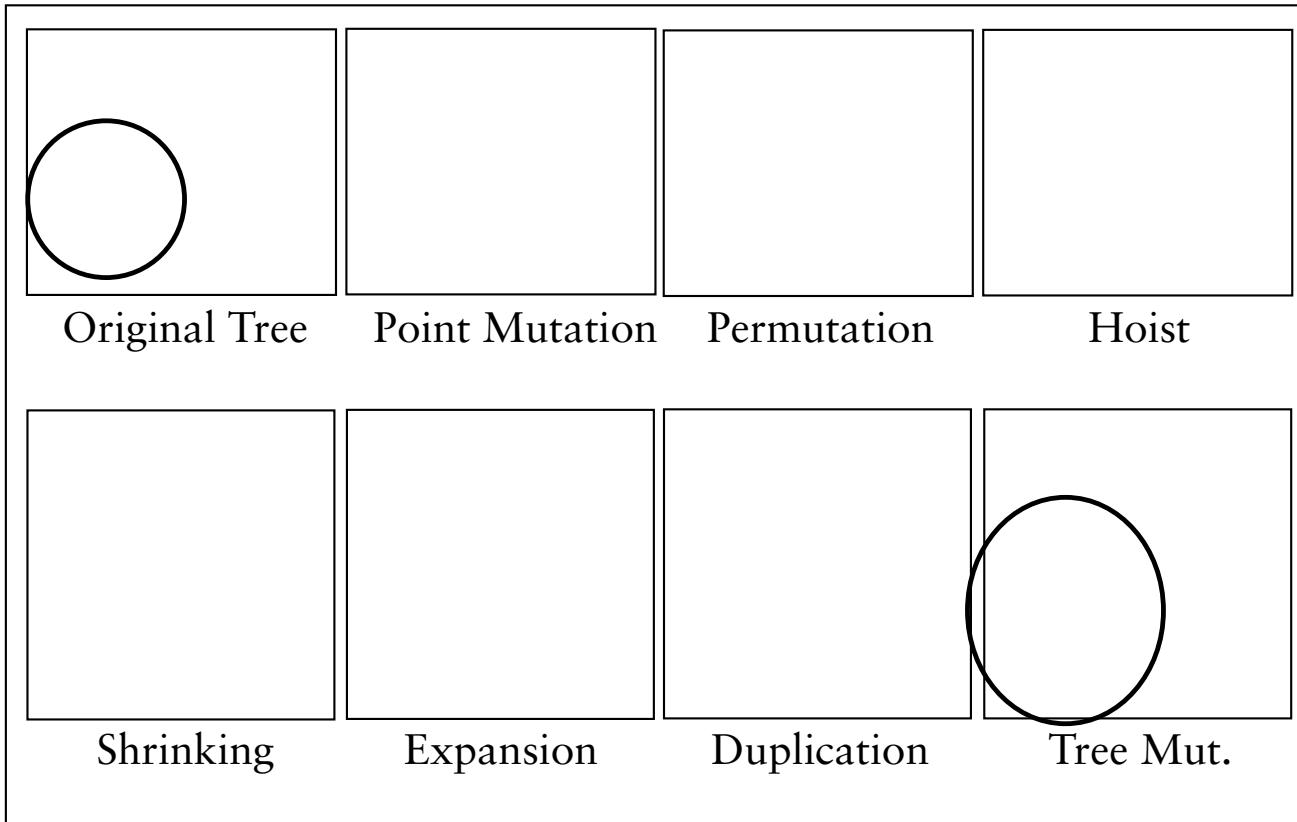
GP Mutation Operators



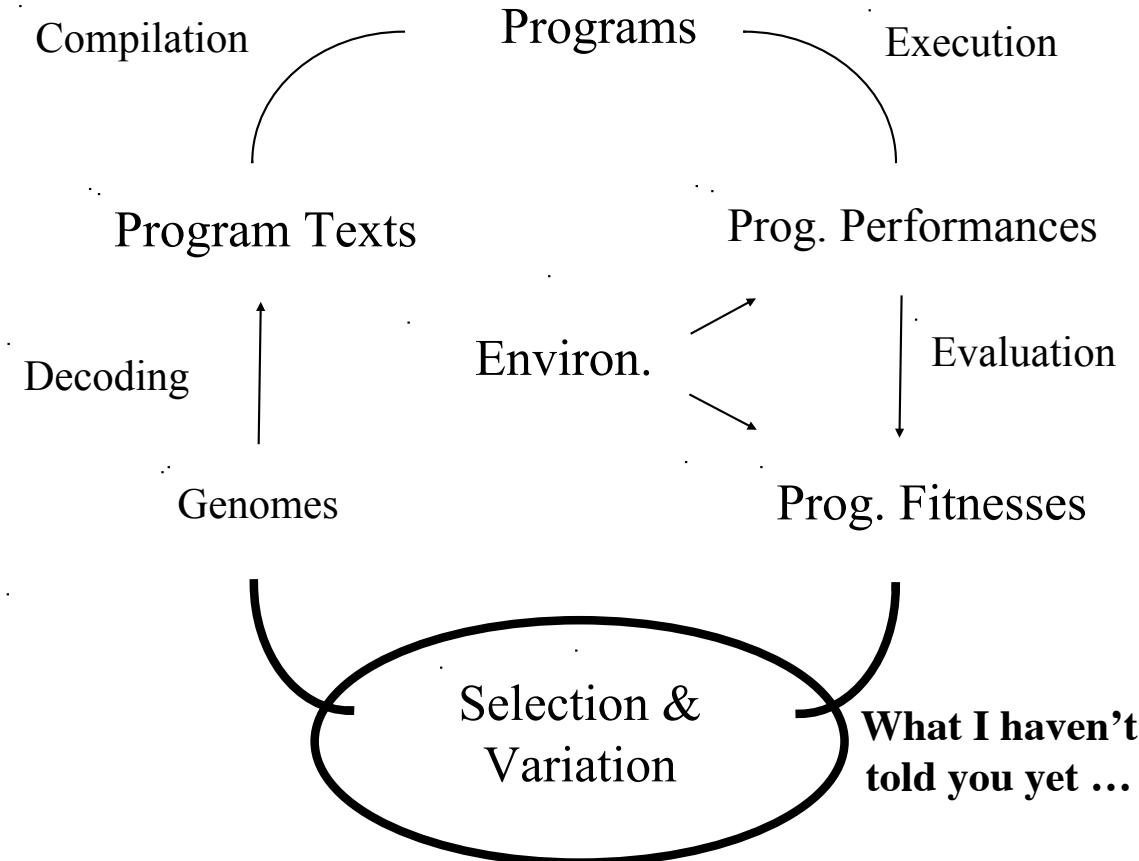
GP Mutation Operators



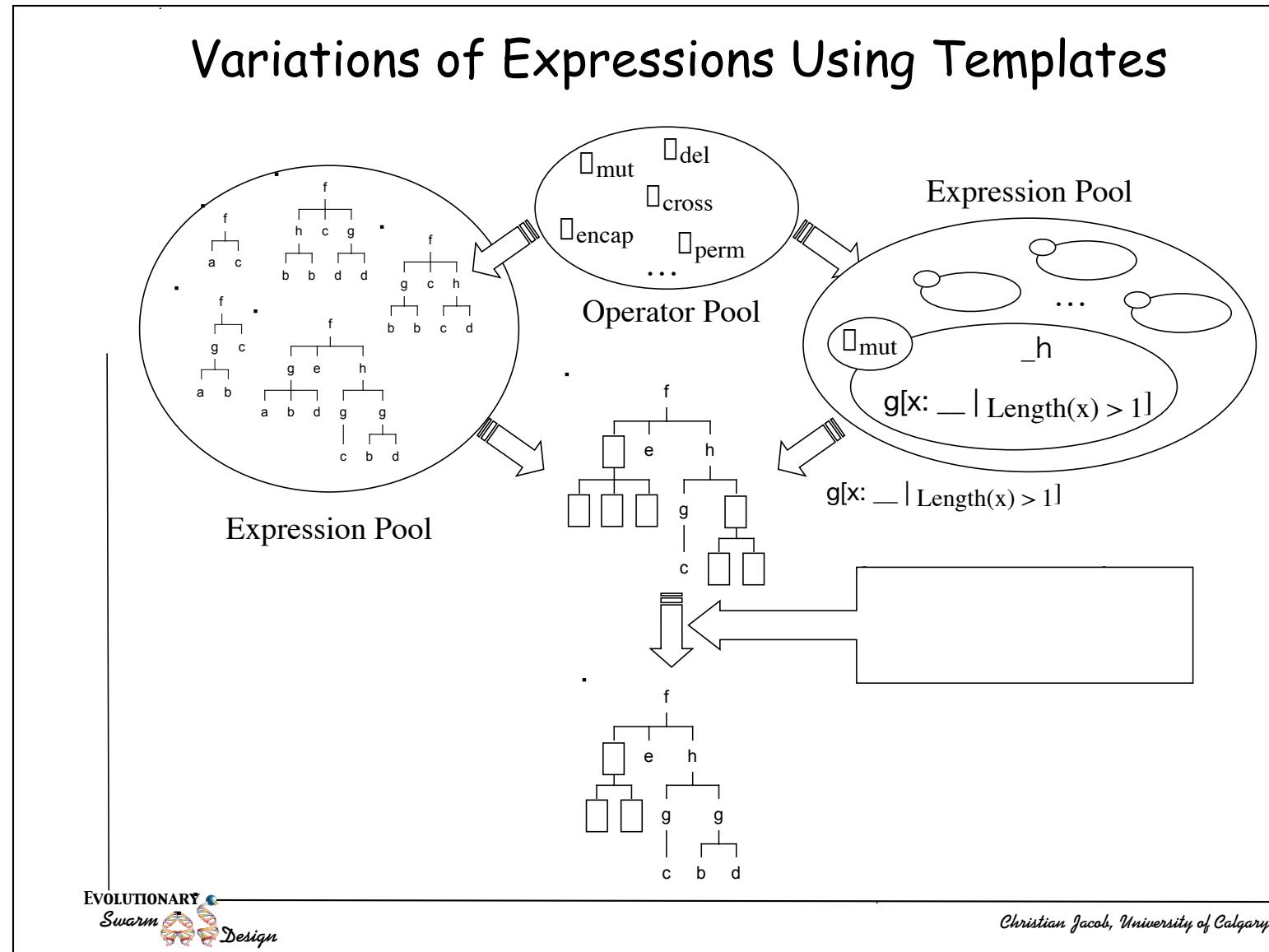
GP Mutation Operators



How to Diversify the Programs ...



Variations of Expressions Using Templates



GP Operators: Selection and History

■ Operator Selection

Probability $\mathcal{P}(\omega)$ of selecting an operator $\omega \in \Omega$ from the operator set Ω :

$$\mathcal{P}(\omega) := \frac{\gamma(\omega)}{\sum_{\omega' \in \Omega} \gamma(\omega')}$$

■ History Function

■ Unary Operator

$$\text{History}(s_i(t)) := (s_k(t-1), \omega)$$

■ Binary Operator

$$\text{History}(s_i(t)) := (s_{k_1}(t-1), s_{k_2}(t-1), s_j(t), \omega_{\text{rec}})$$

GP Operators: Weight Adaptation

■ Weight Adaptation

$\gamma(\omega, t)$ is the weight of operator ω in generation t .

$$\gamma(\omega, t) := \gamma(\omega, t - 1) \cdot \Delta\gamma(\omega, t) \cdot \gamma_{\text{decay}}(\omega)$$

Average fitness difference: $\Delta\gamma(\omega, t)$.

Weight decay constant: $0 \leq \gamma_{\text{decay}}(\omega) \leq 1$.

GP Operators: Weight Adaptation (2)

■ $\Delta\gamma$ for Unary Operators

$$\Delta\gamma(\omega, t) := \frac{1}{|P(\omega, t)|} \cdot \sum_{s \in P(\omega, t)} \frac{\tau(s)}{\tau(\text{History}(s)_1)}$$

$$P(\omega, t) := \{s \mid \text{History}(s)_2 = \omega\} \subseteq P(t)$$

$P(\omega, t)$ is the set of all structures within a population $P(t)$, which are offspring from parents in $P(t - 1)$ using operator ω .

■ $\Delta\gamma$ for Binary Operators

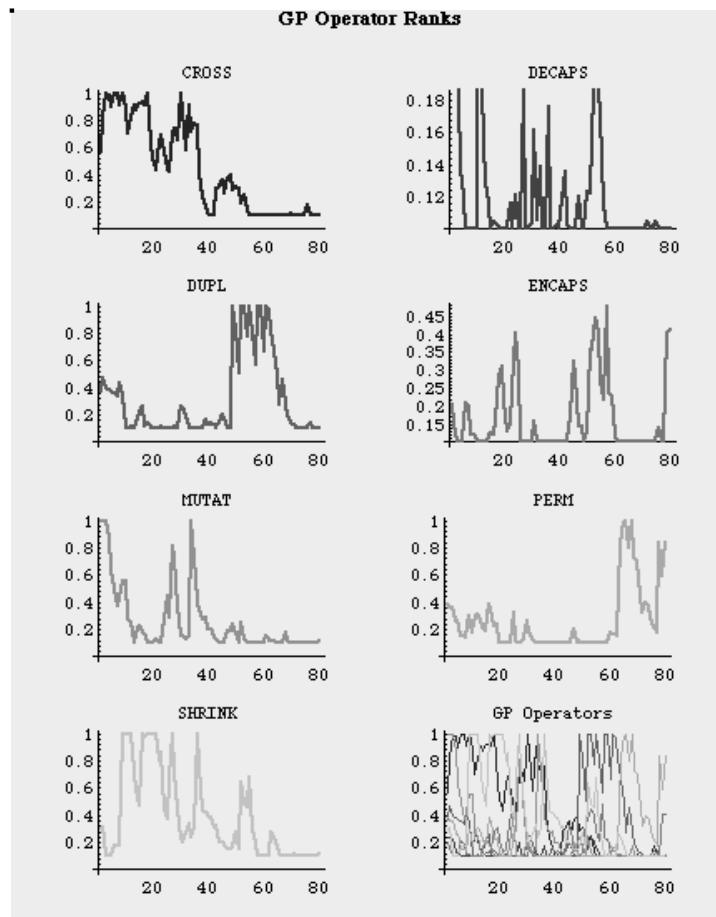
$$\Delta\gamma(\omega, t) := \frac{1}{2 \cdot |P(\omega, t)|} \cdot \sum_{s \in P(\omega, t)} \tau^*(s)$$

$$\tau^*(s) := \text{Max}\left(\frac{\tau(s)}{\tau(p_1(s))}, \frac{\tau(b(s))}{\tau(p_2(s))}\right)$$

Parents: $p_i(s) := \text{History}(s)_i$

Offspring: $b(s) := \text{History}(s)_3$

AntTracker: Adaptive Operator Ranks



[Jacob 2001, Ch. 9]

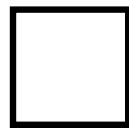
Evolution of Fractals

Towards a better understanding of replacement
systems and their evolution

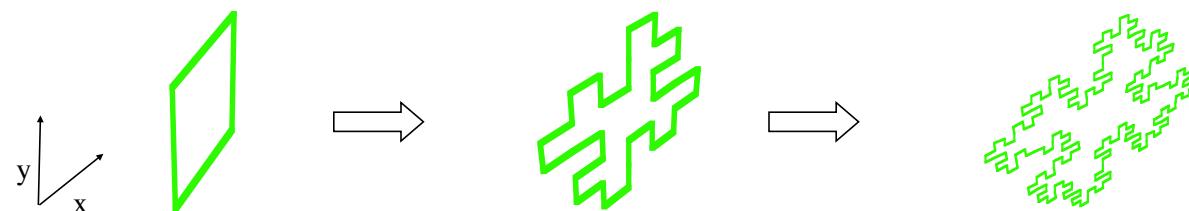
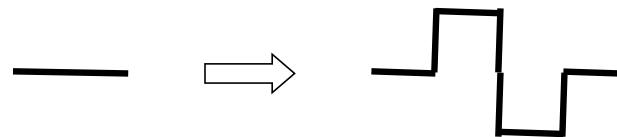
Jing Yu

Fractals and Lindenmayer Systems

Axiom:

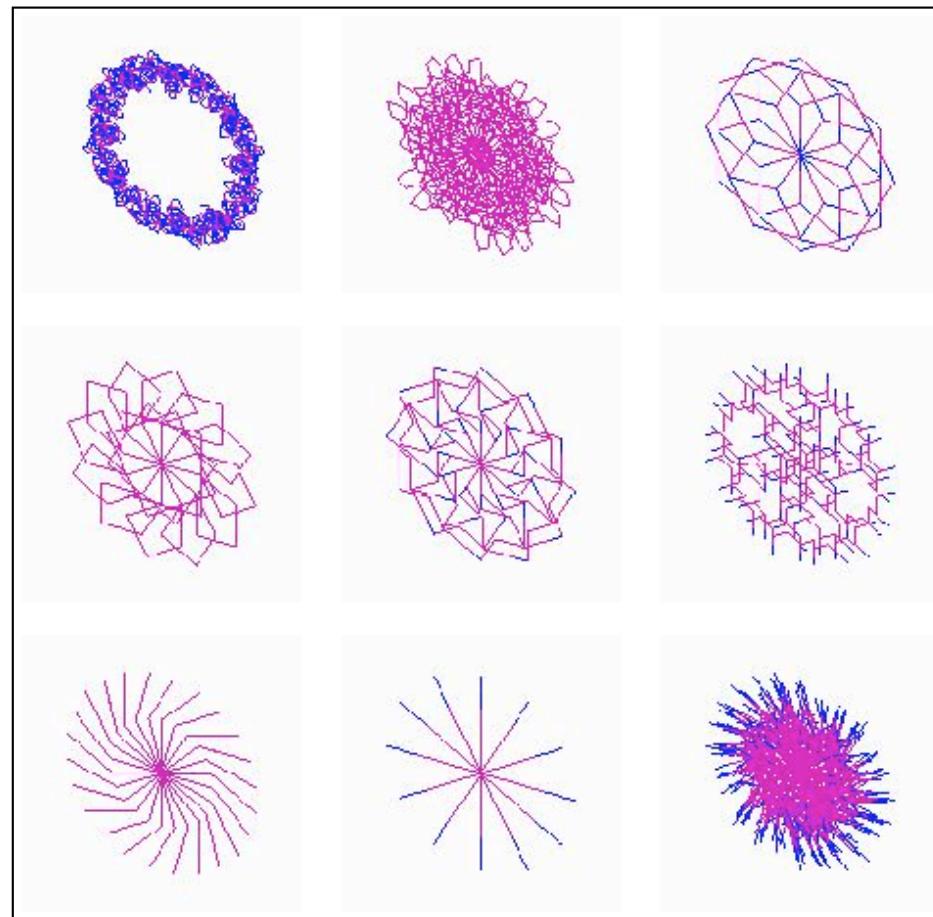


Replacement Rule:

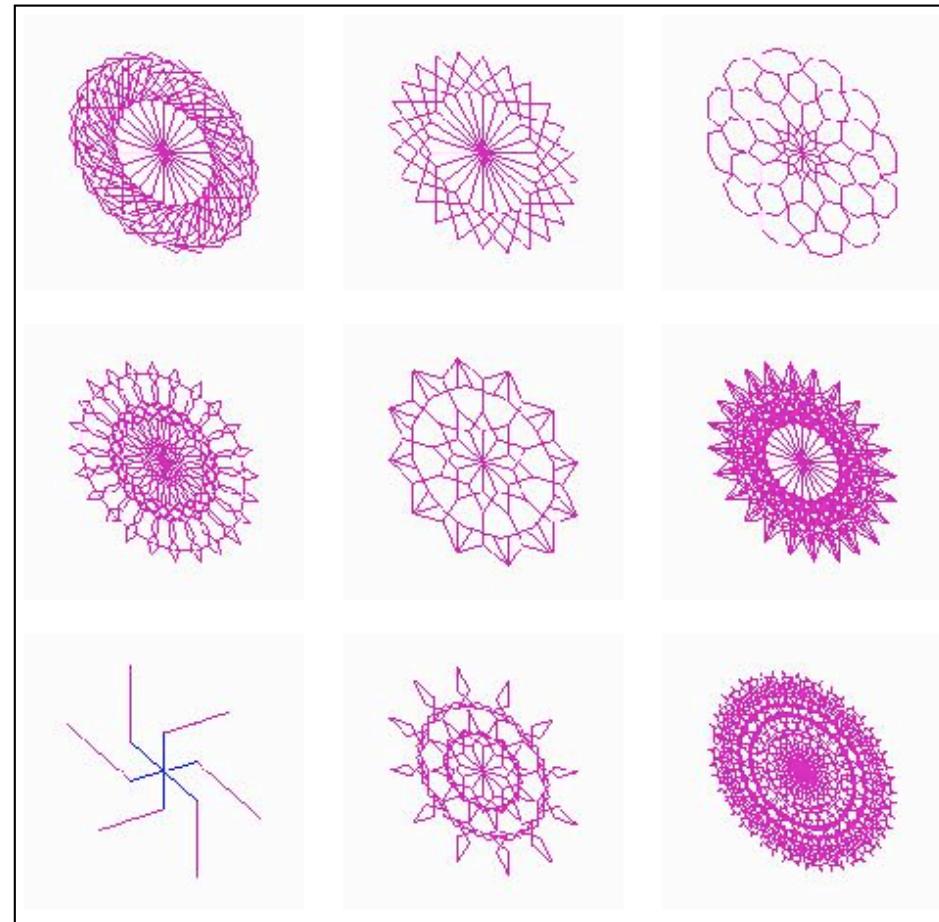


The Quadratic Koch Island

Gallery of Evolved Fractals



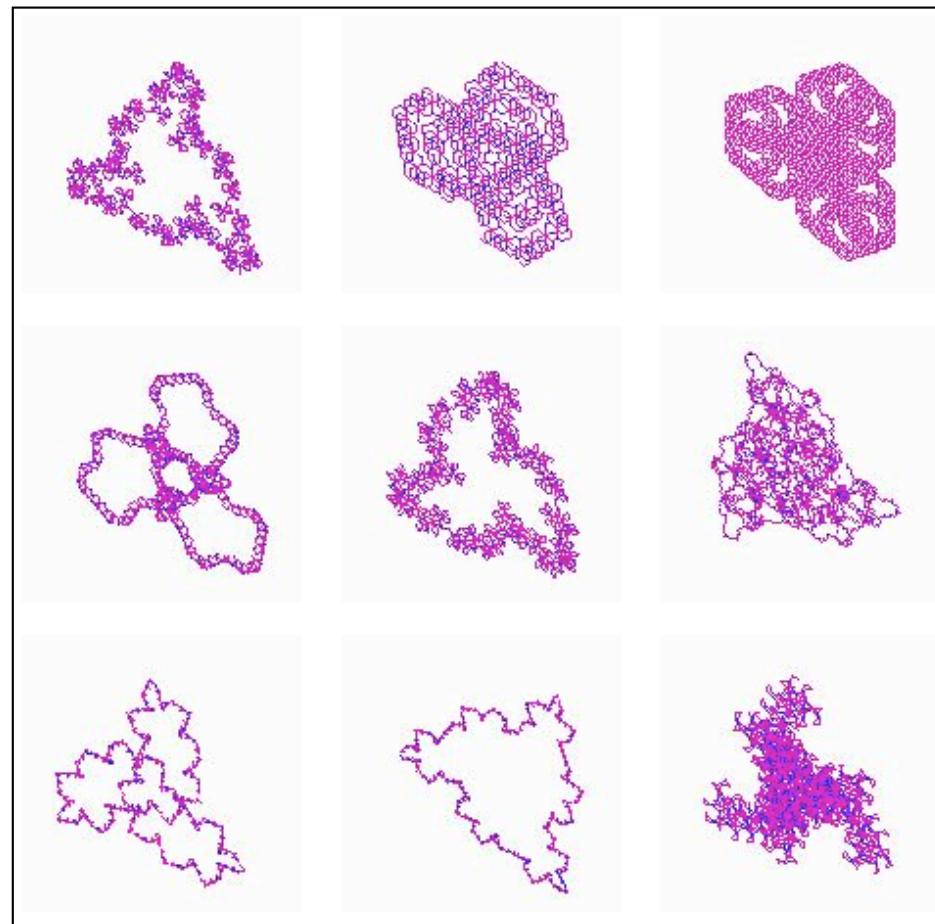
Gallery of Evolved Fractals



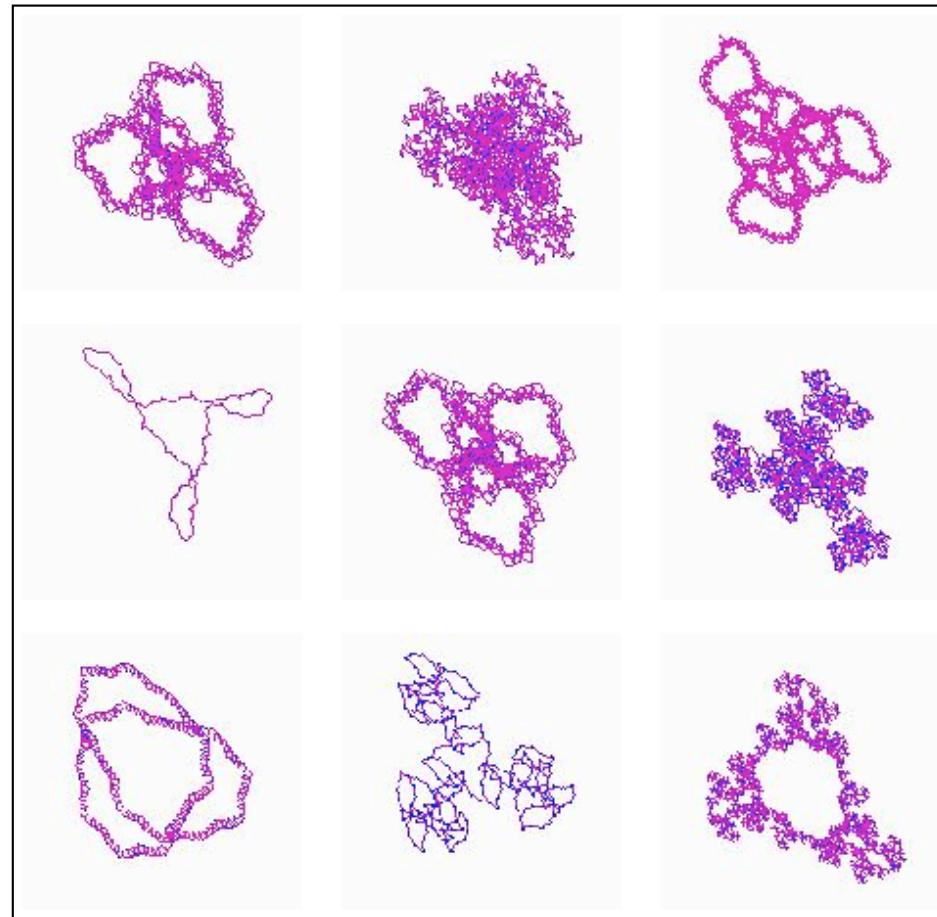
EVOLUTIONARY
Swarm Design

Christian Jacob, University of Calgary

Gallery of Evolved Fractals



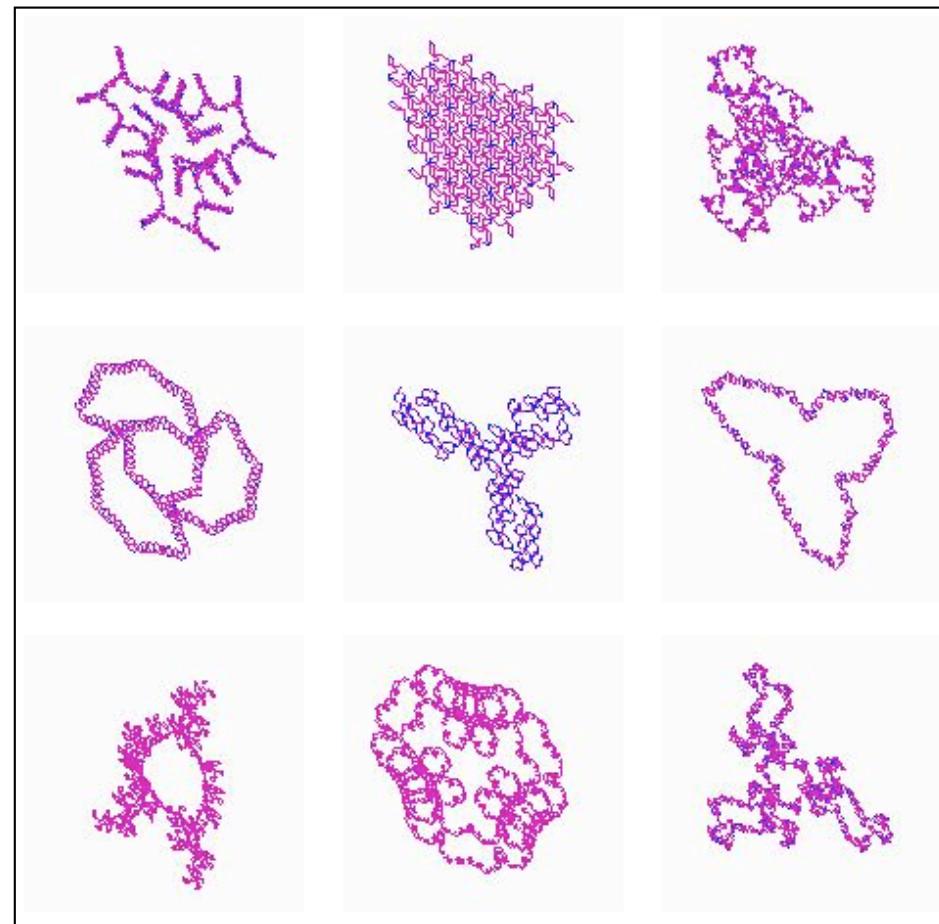
Gallery of Evolved Fractals



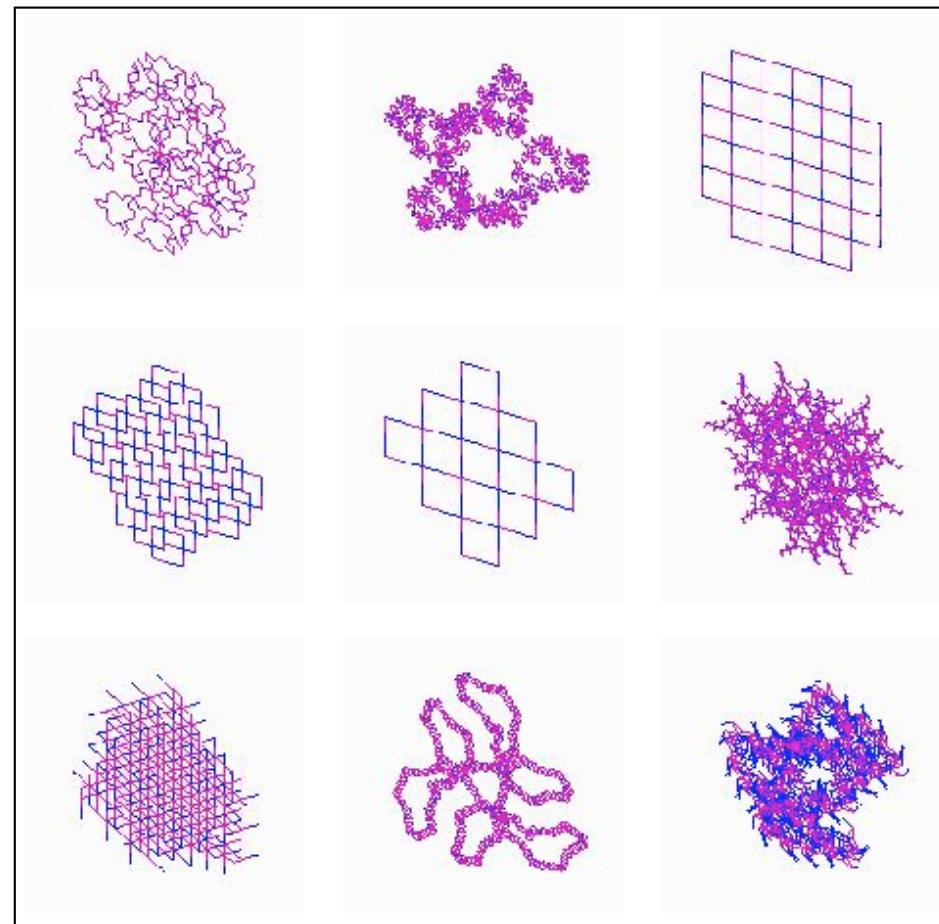
EVOLUTIONARY
Swarm Design

Christian Jacob, University of Calgary

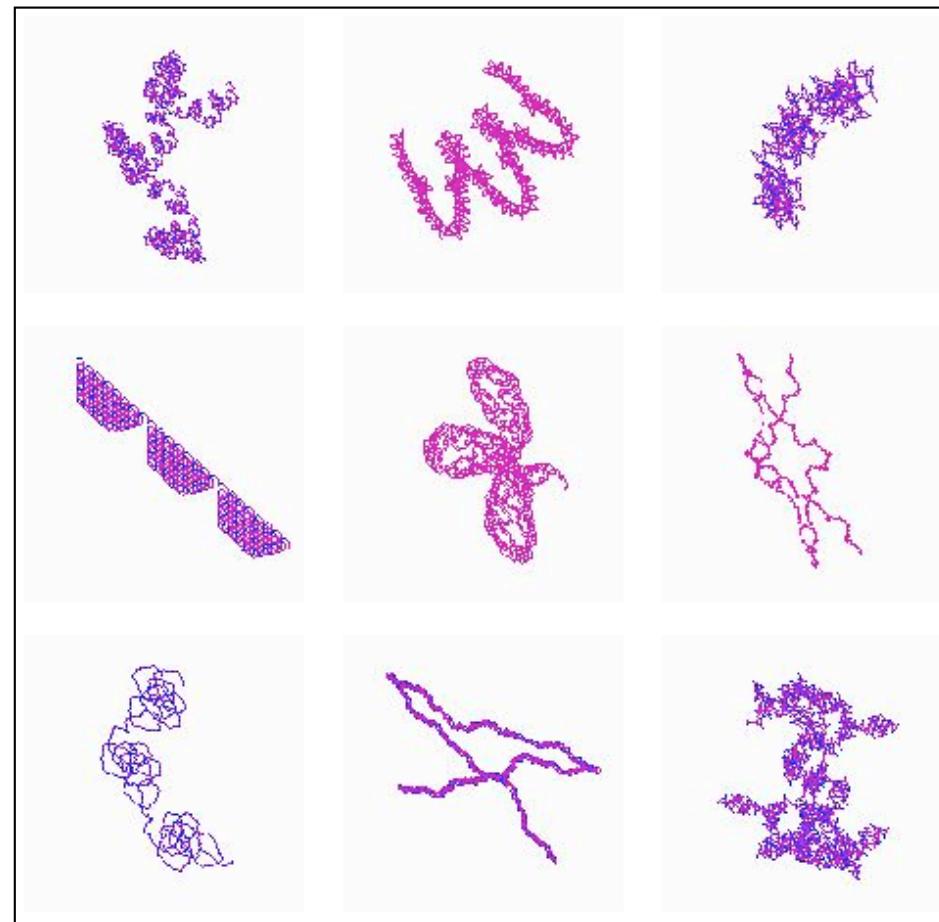
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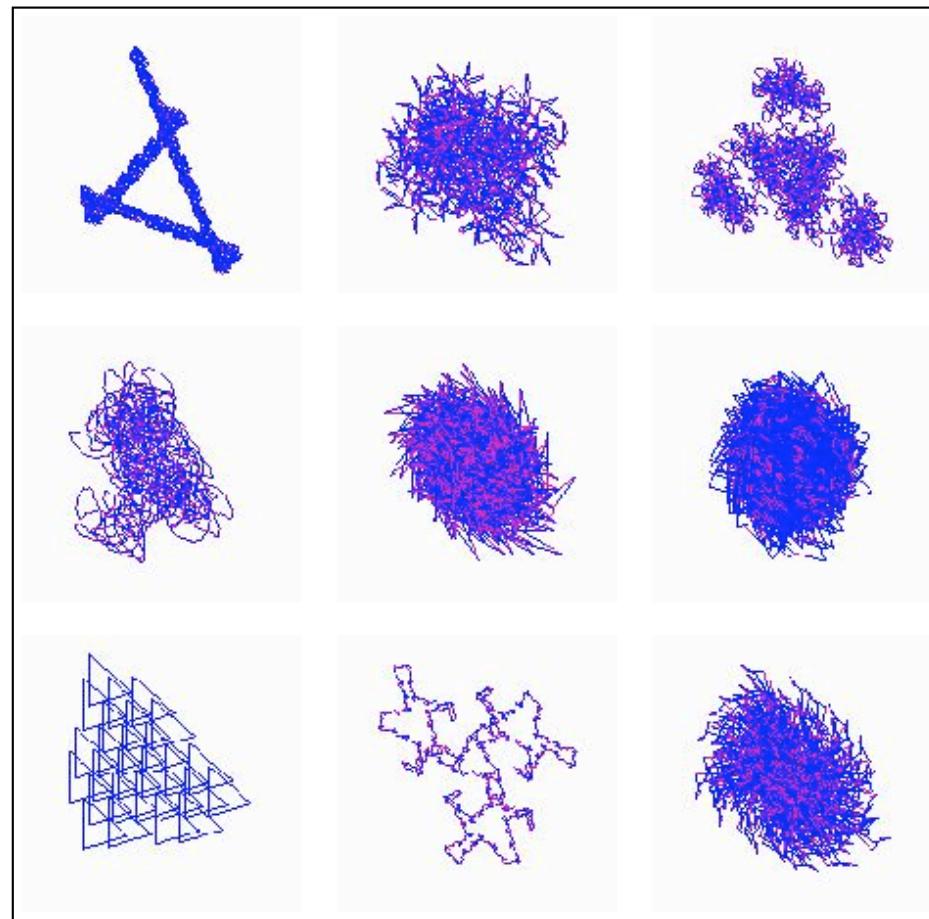
Gallery of Evolved Fractals



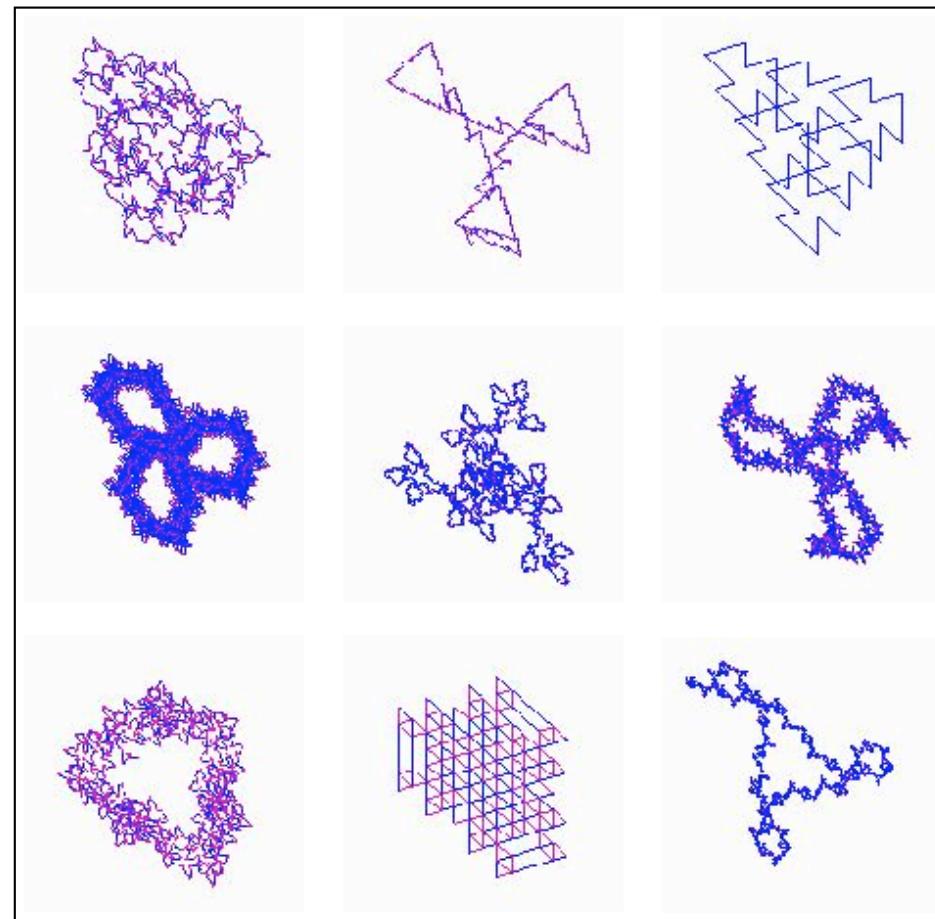
Gallery of Evolved Fractals



Gallery of Evolved Fractals



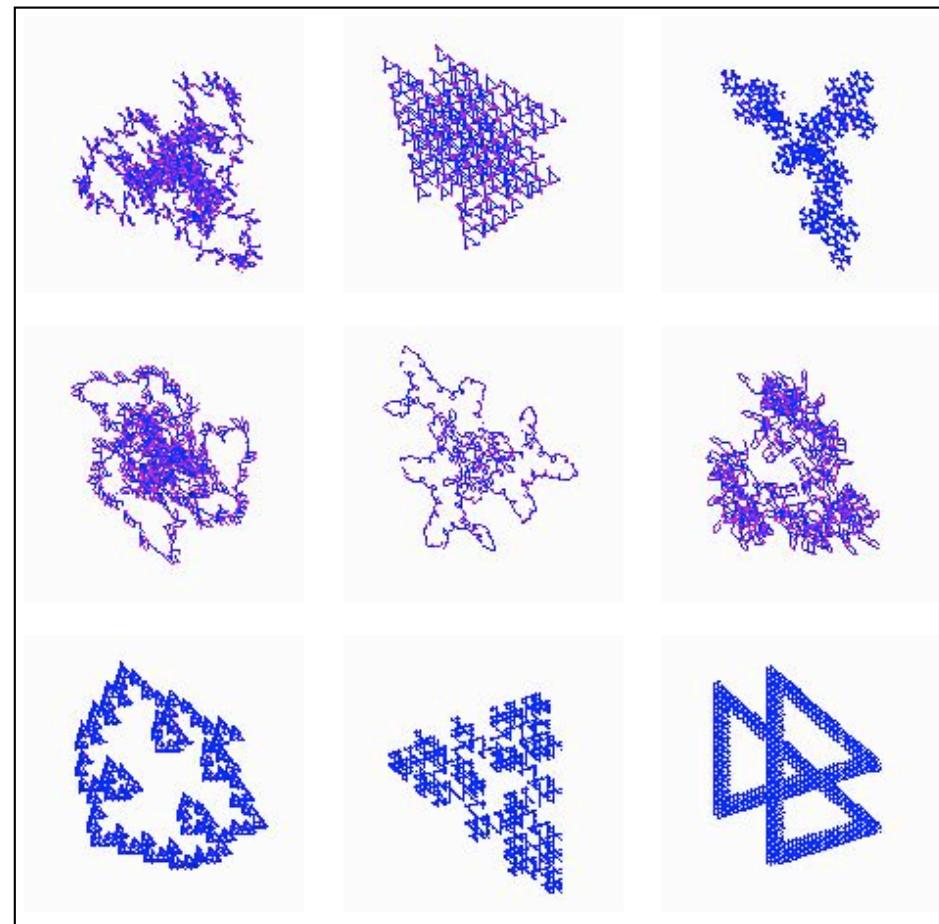
Gallery of Evolved Fractals



EVOLUTIONARY
Swarm Design

Christian Jacob, University of Calgary

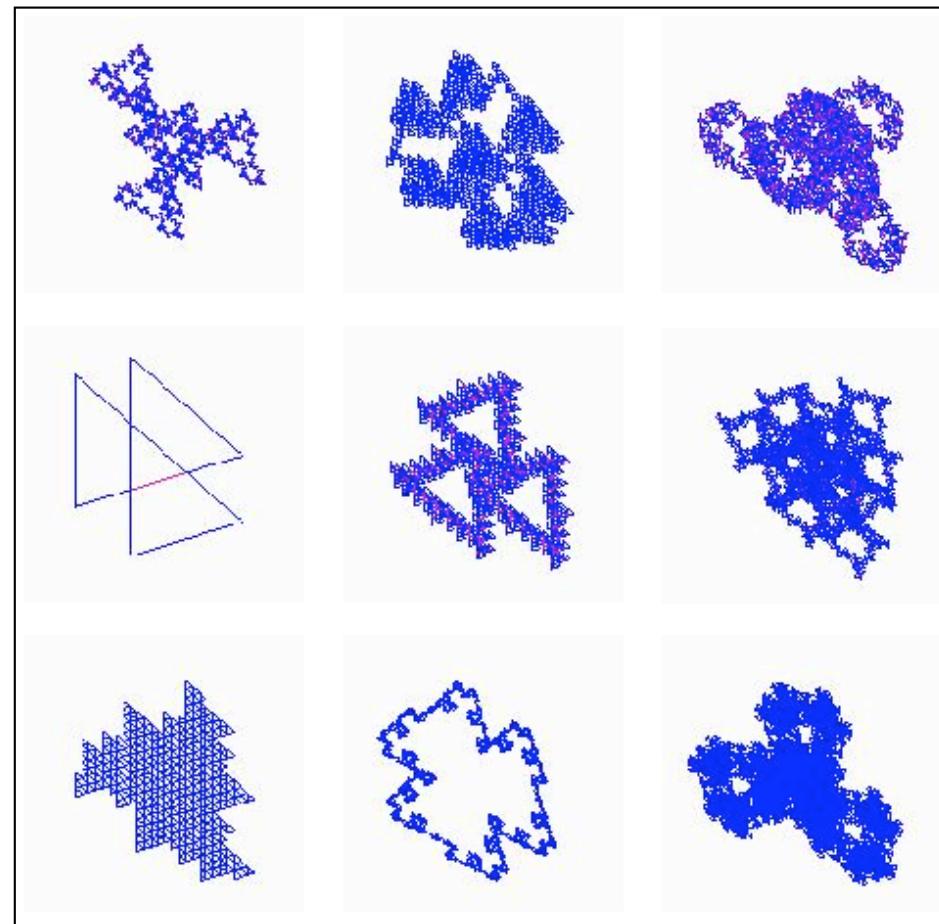
Gallery of Evolved Fractals



EVOLUTIONARY
Swarm Design

Christian Jacob, University of Calgary

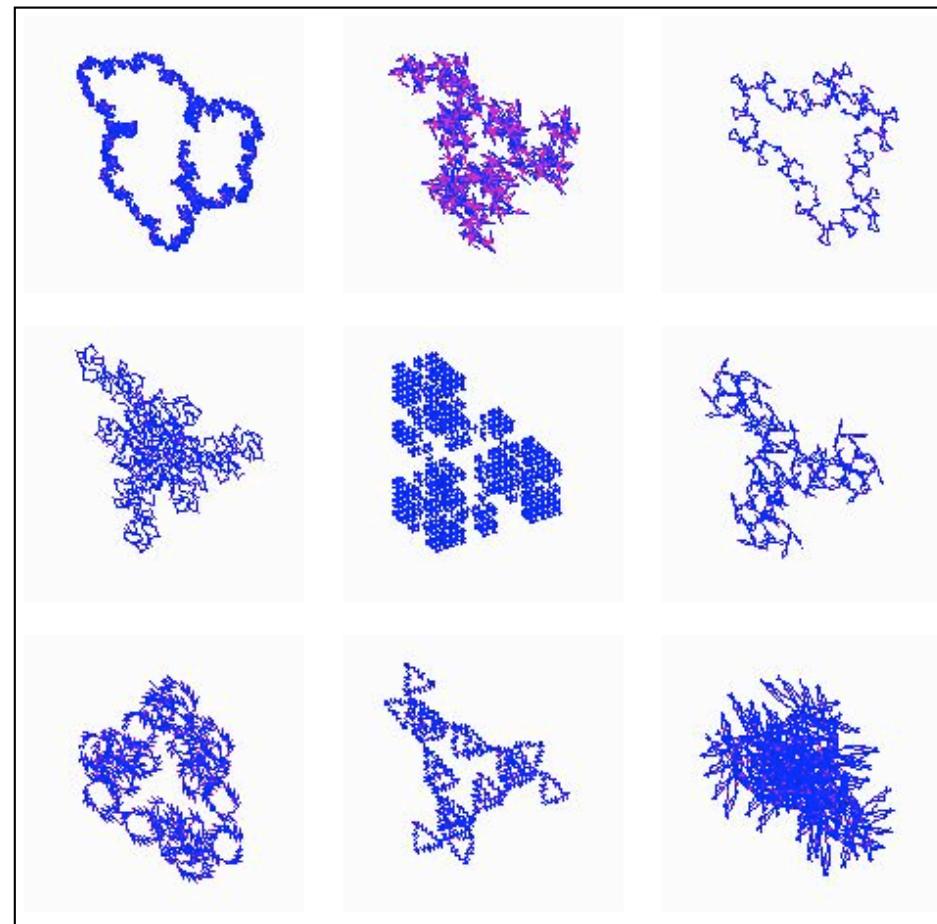
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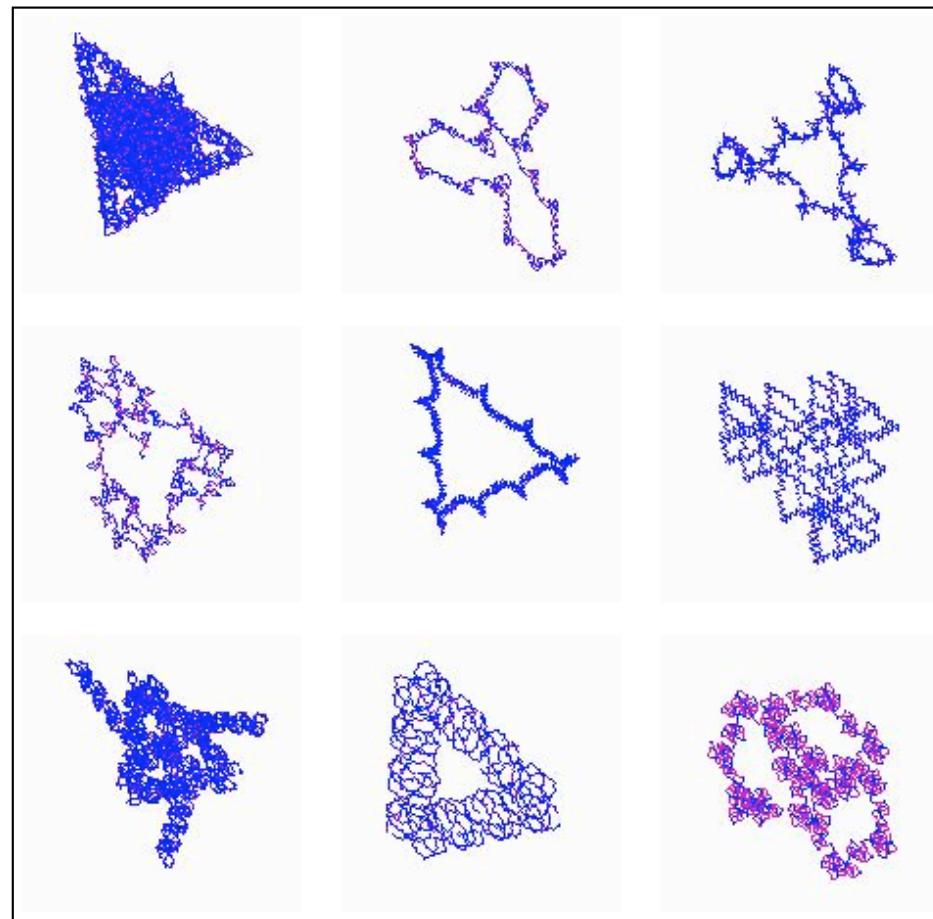
EVOLUTIONARY
Swarm Design

Christian Jacob, University of Calgary

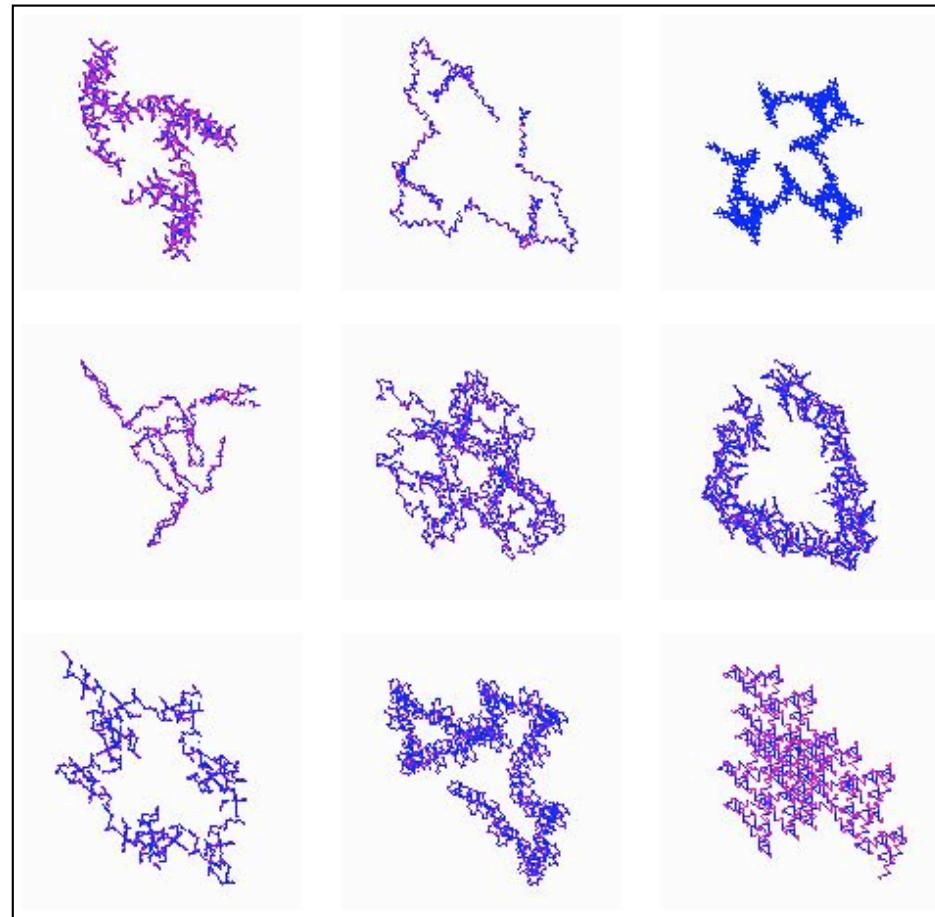
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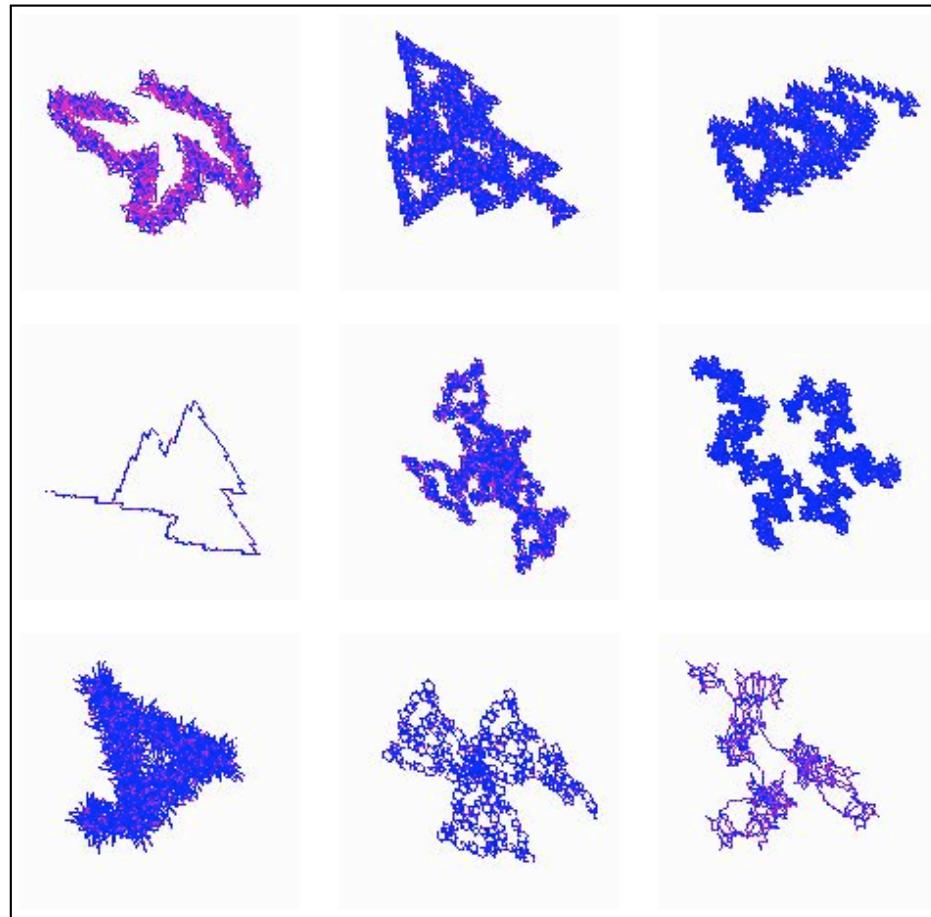
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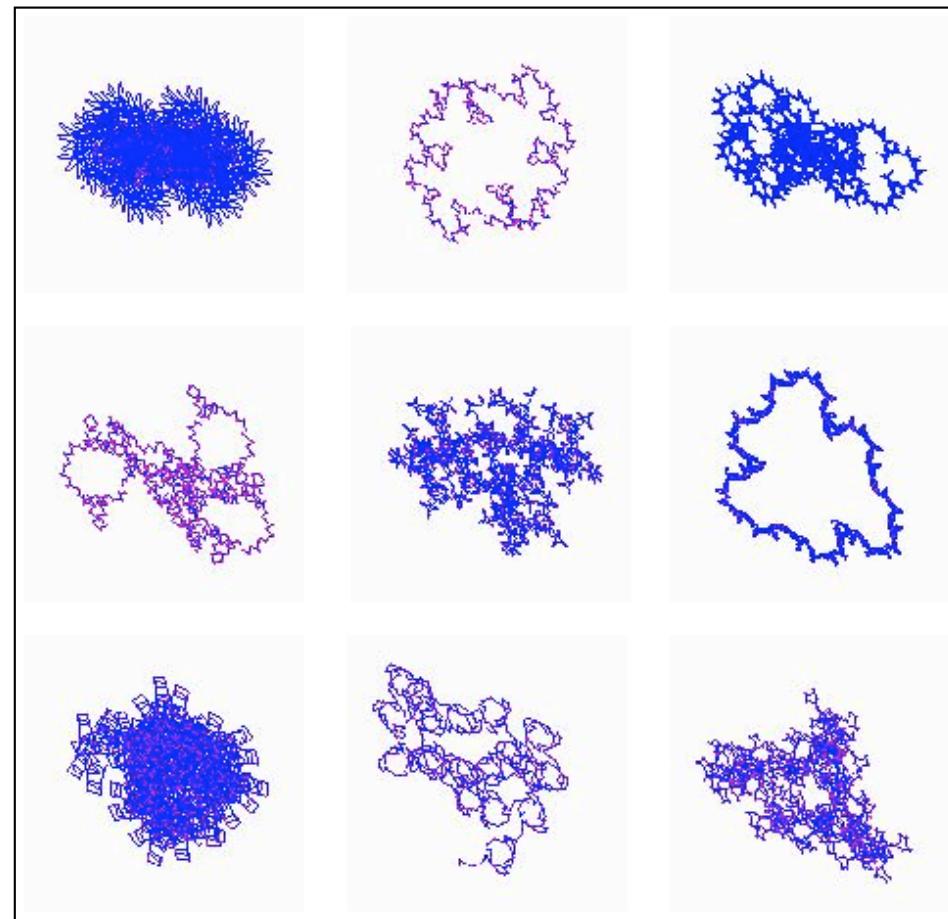
Gallery of Evolved Fractals



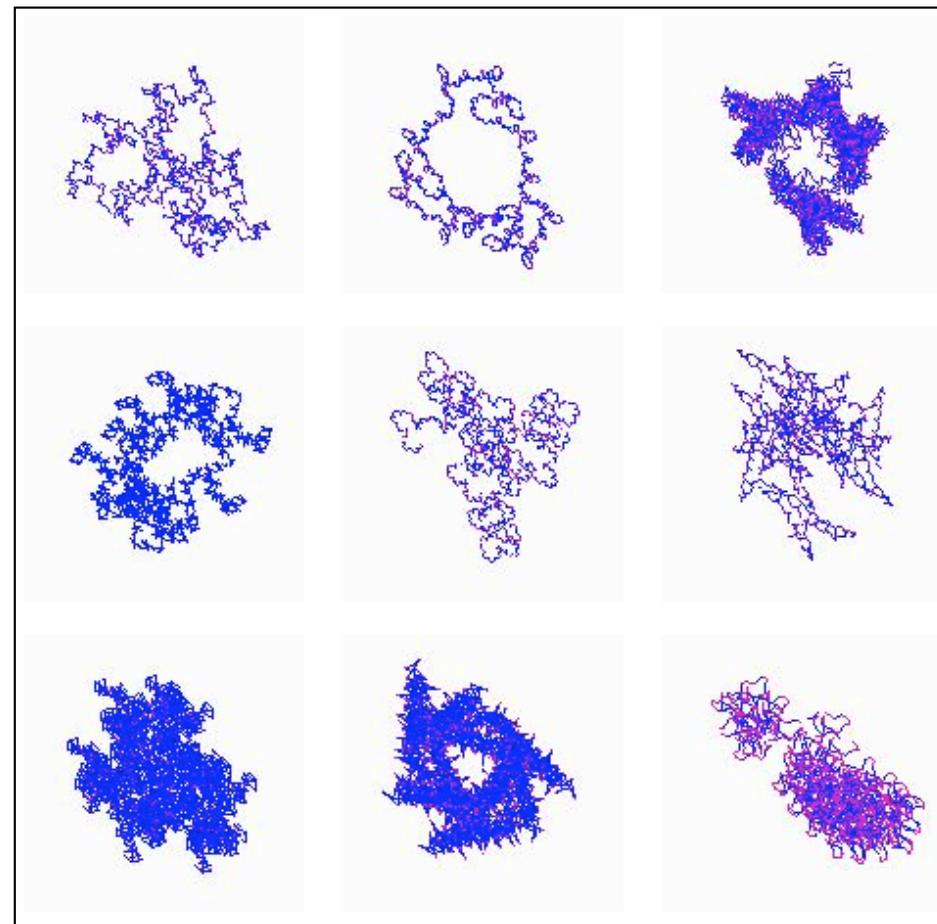
Gallery of Evolved Fractals



Gallery of Evolved Fractals



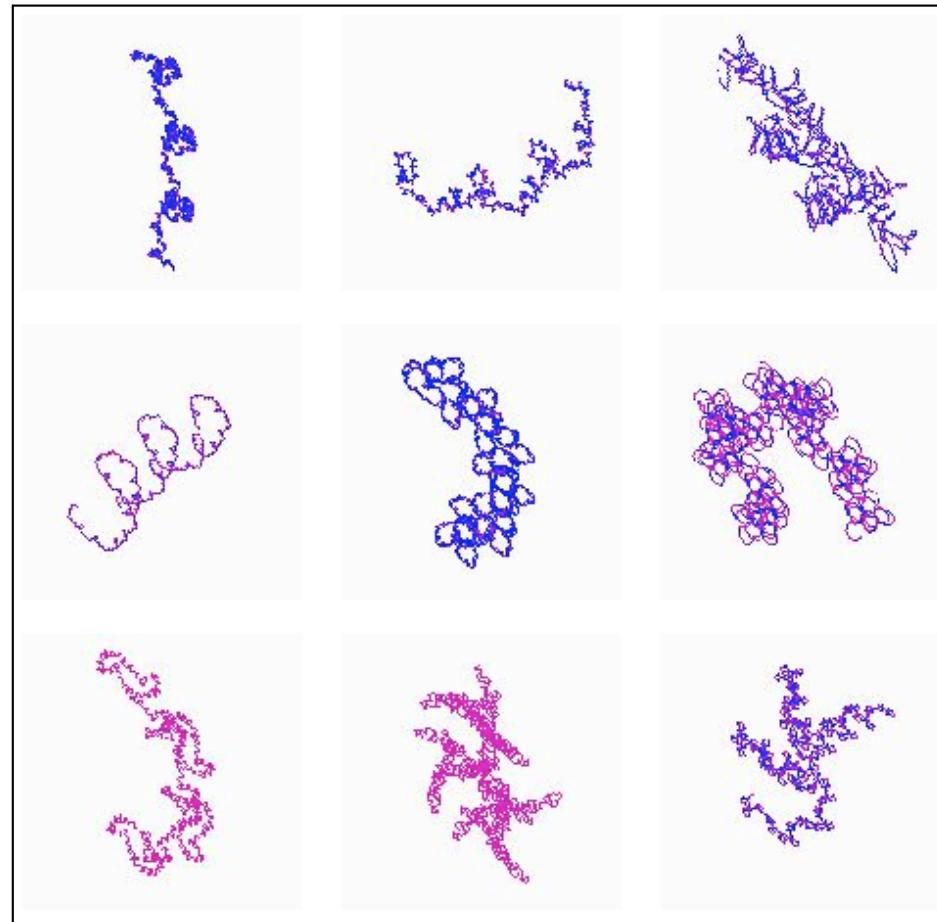
Gallery of Evolved Fractals



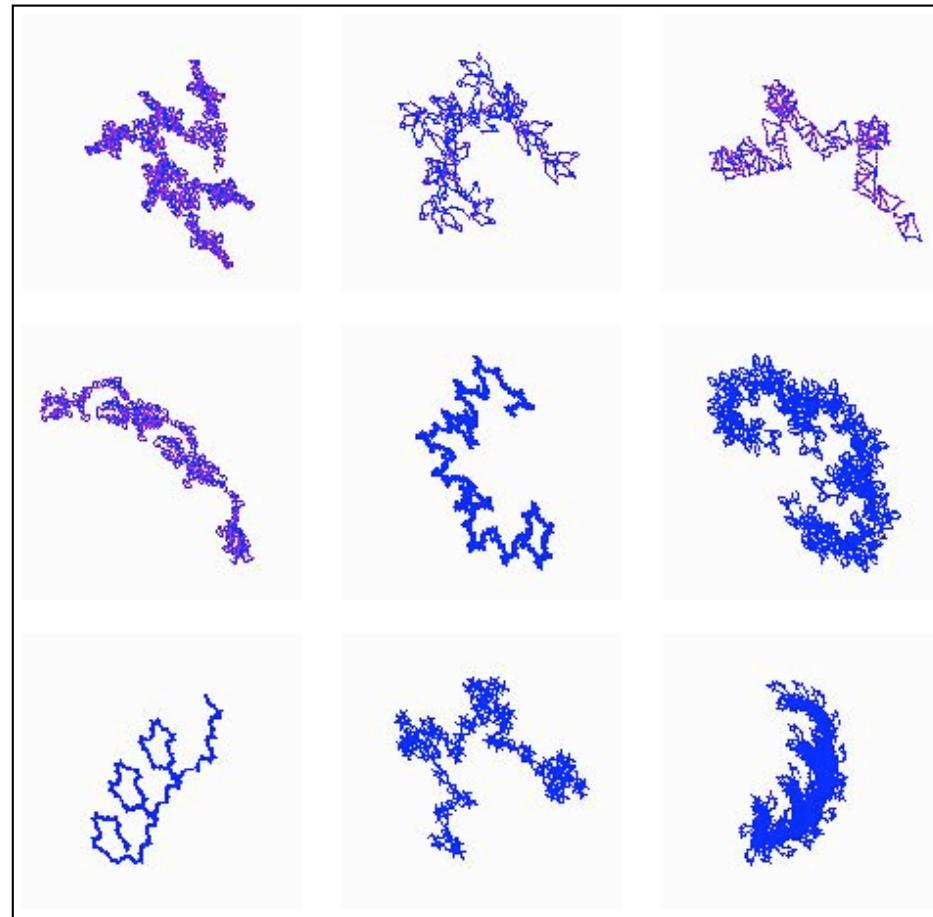
EVOLUTIONARY
Swarm Design

Christian Jacob, University of Calgary

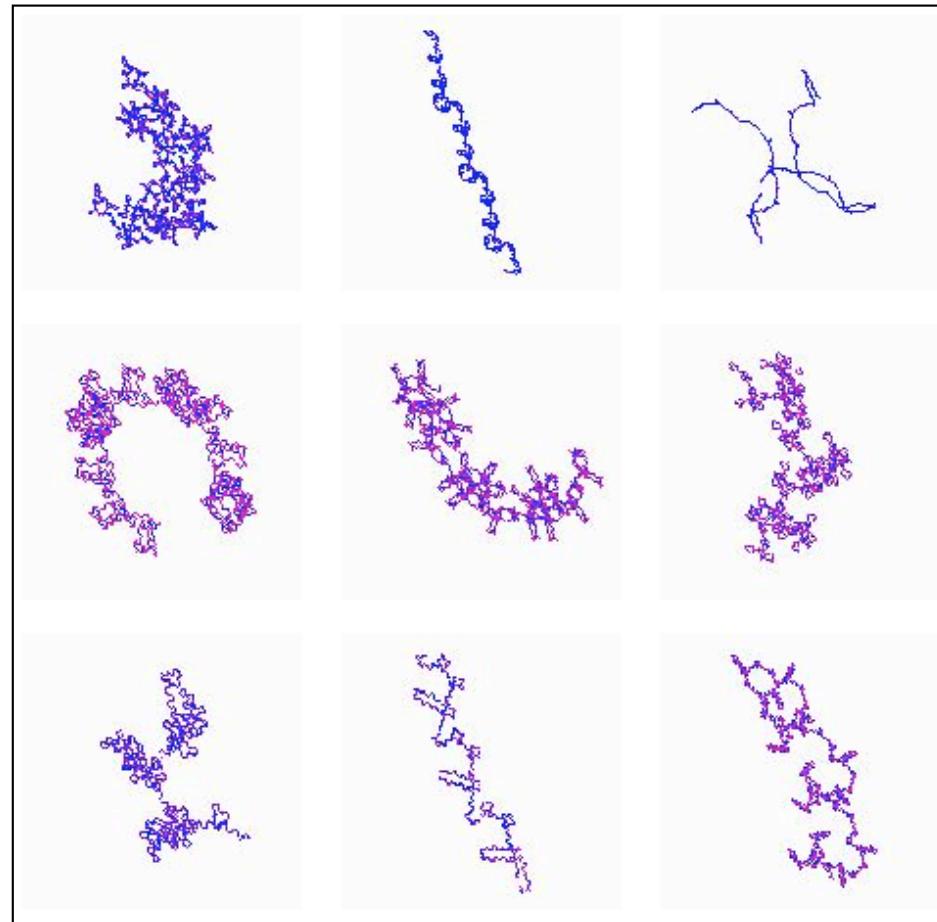
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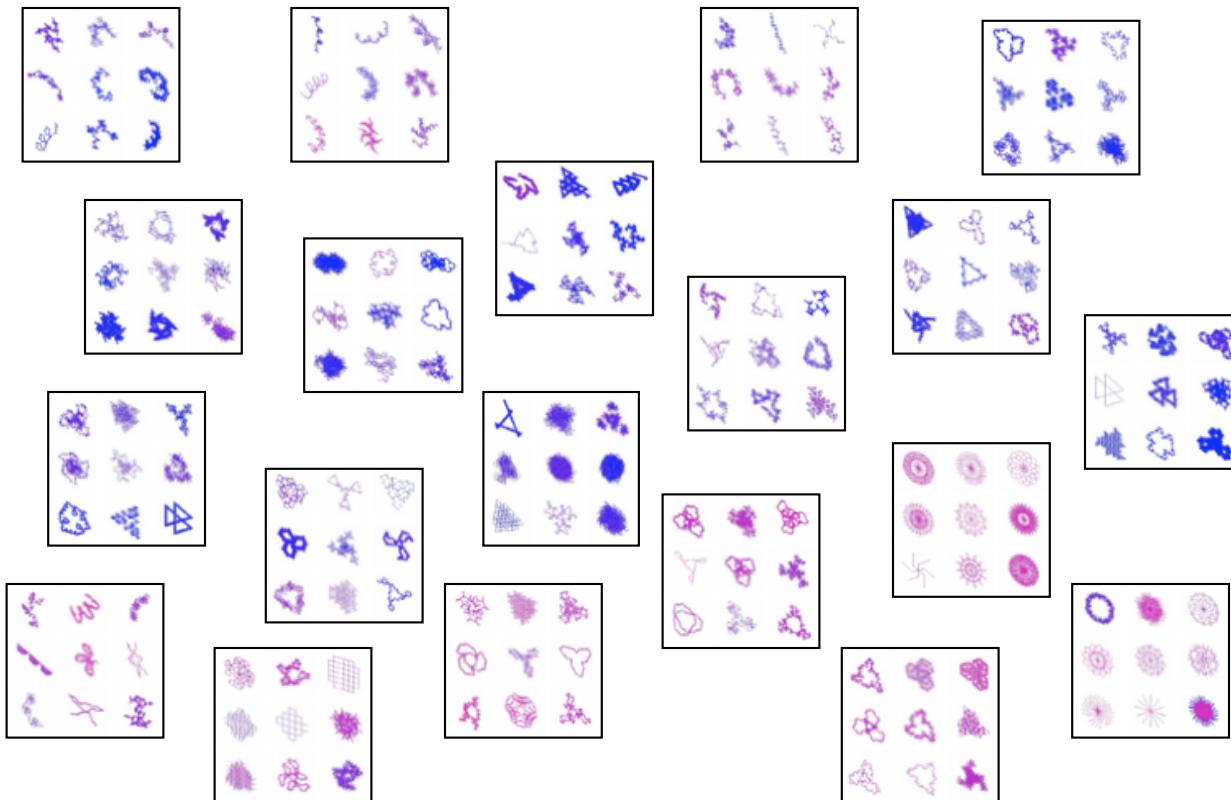
Gallery of Evolved Fractals



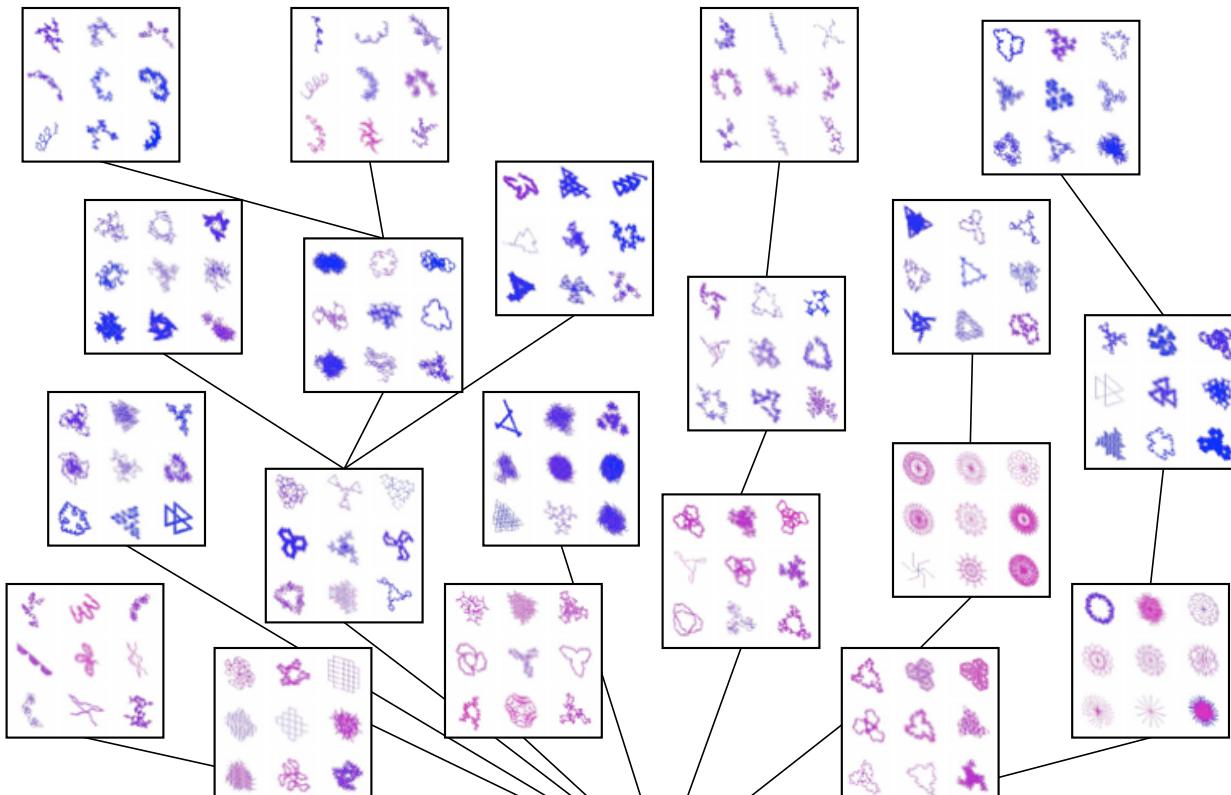
Gallery of Evolved Fractals



Evolutionary Exploration of Fractal Spaces



Evolutionary Exploration of Fractal Spaces



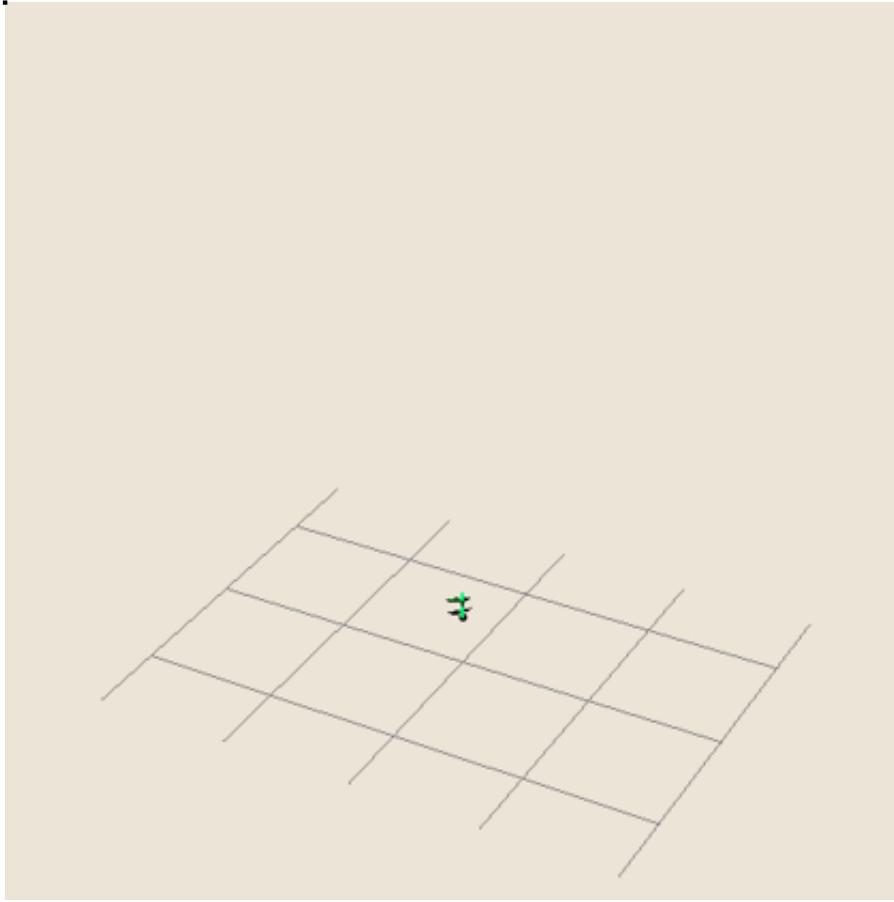
Jing Yu

EVOLUTIONARY
Swarm Design

Christian Jacob, University of Calgary

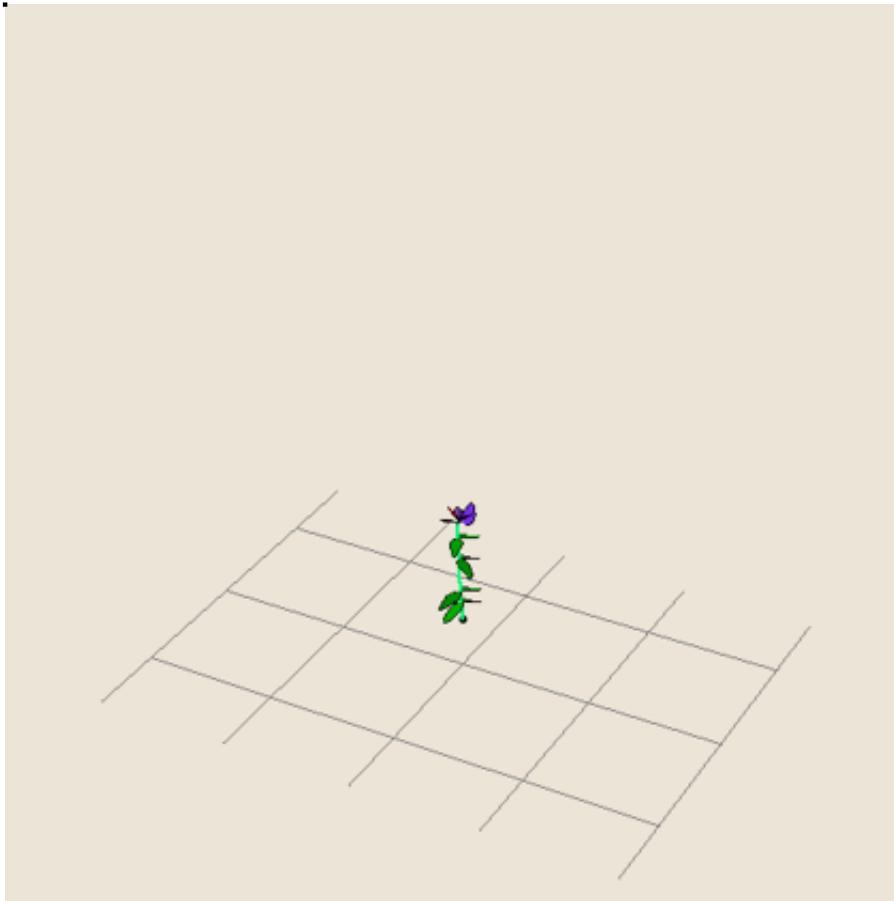
Evolutionary Inference of L-Systems

Developmental Programs



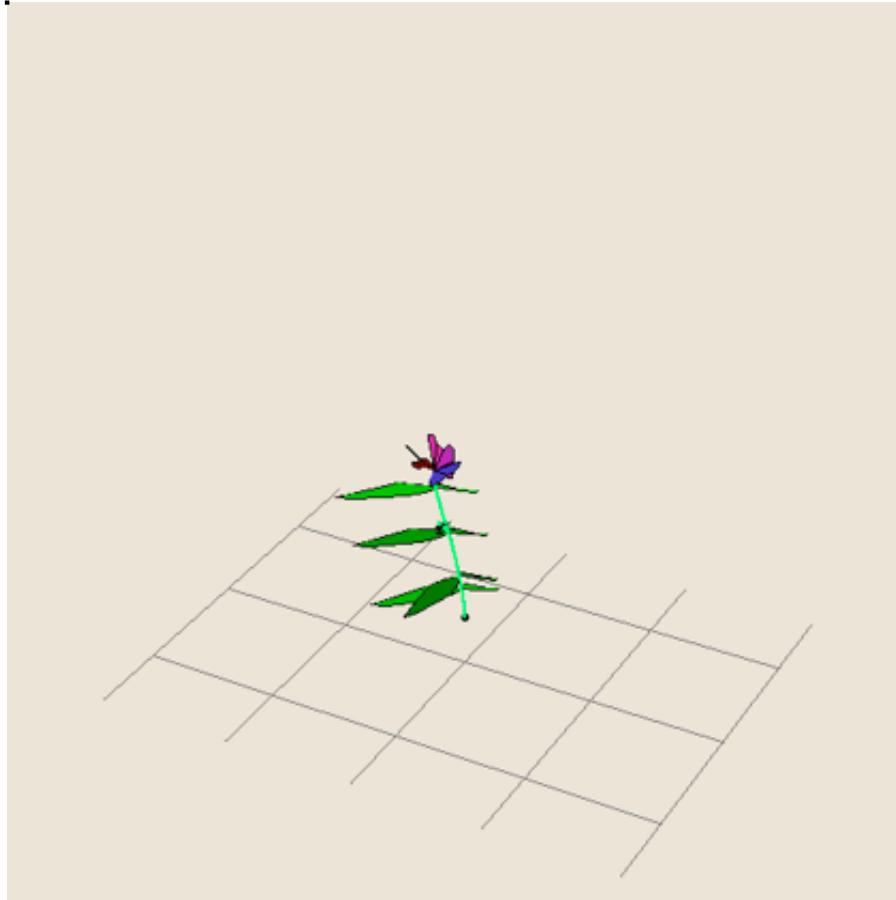
Iteration 1

Developmental Programs



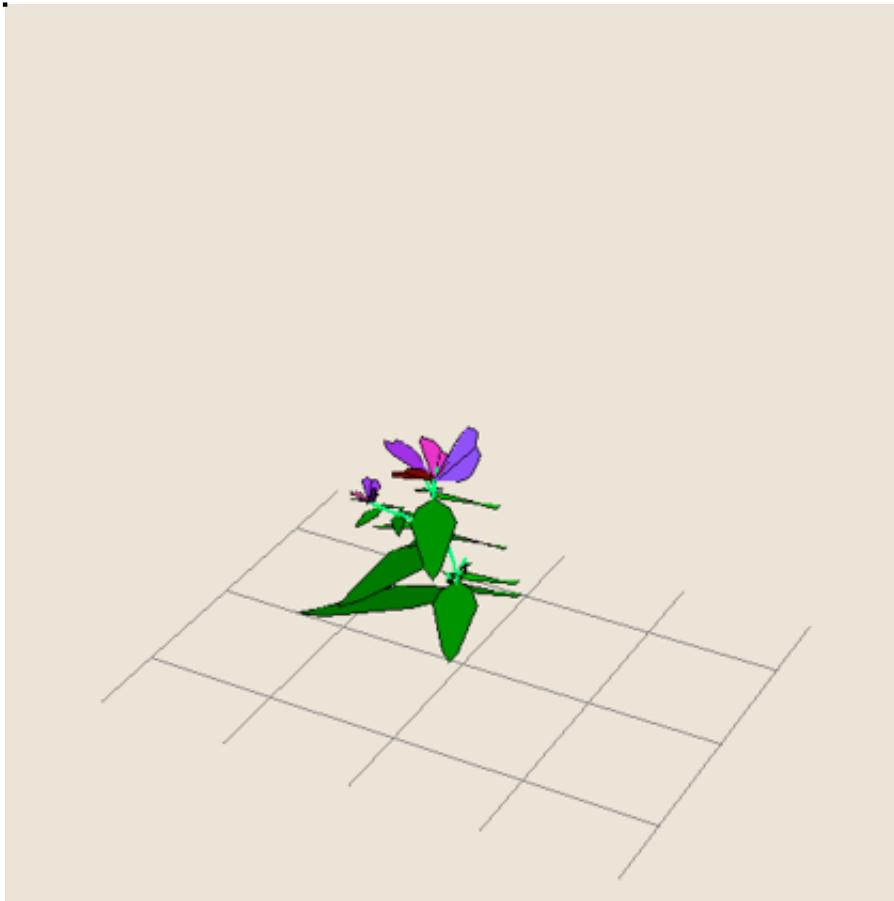
Iteration 2

Developmental Programs



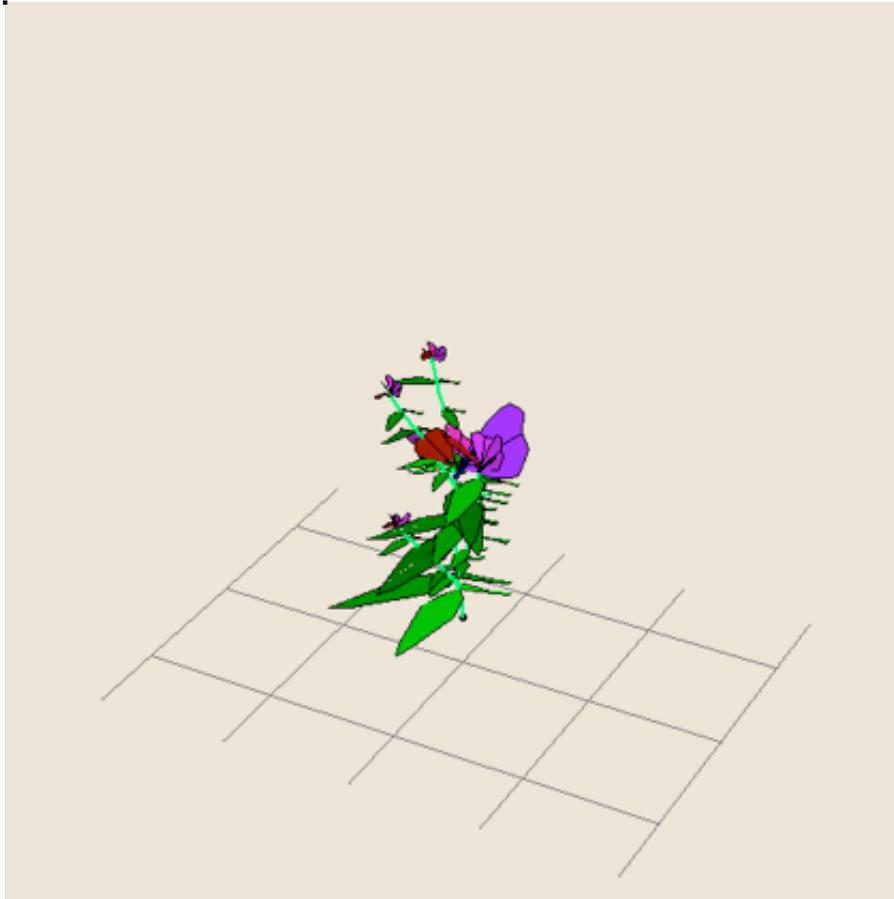
Iteration 3

Developmental Programs



Iteration 4

Developmental Programs



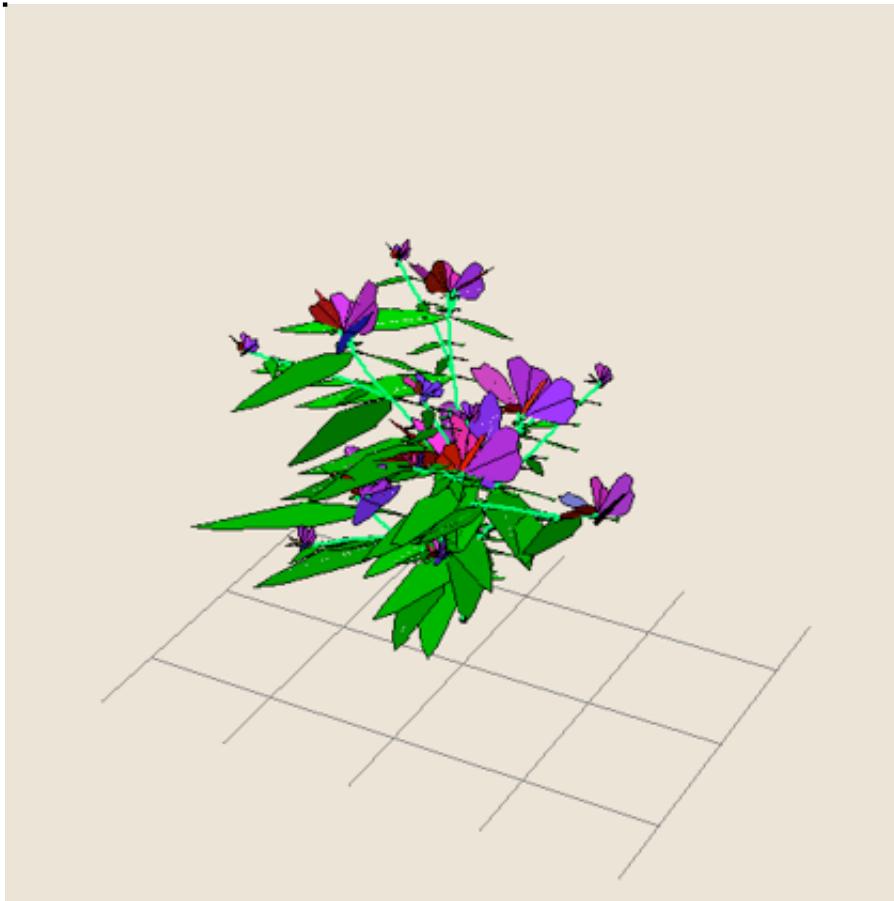
Iteration 5

Developmental Programs



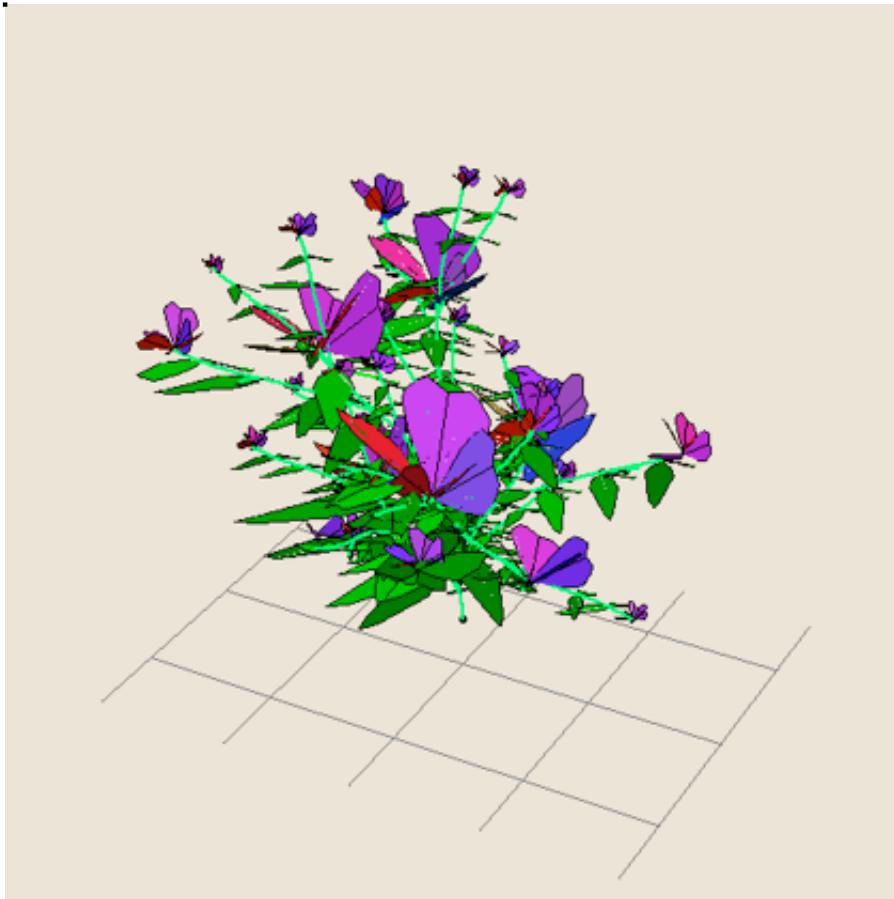
Iteration 6

Developmental Programs



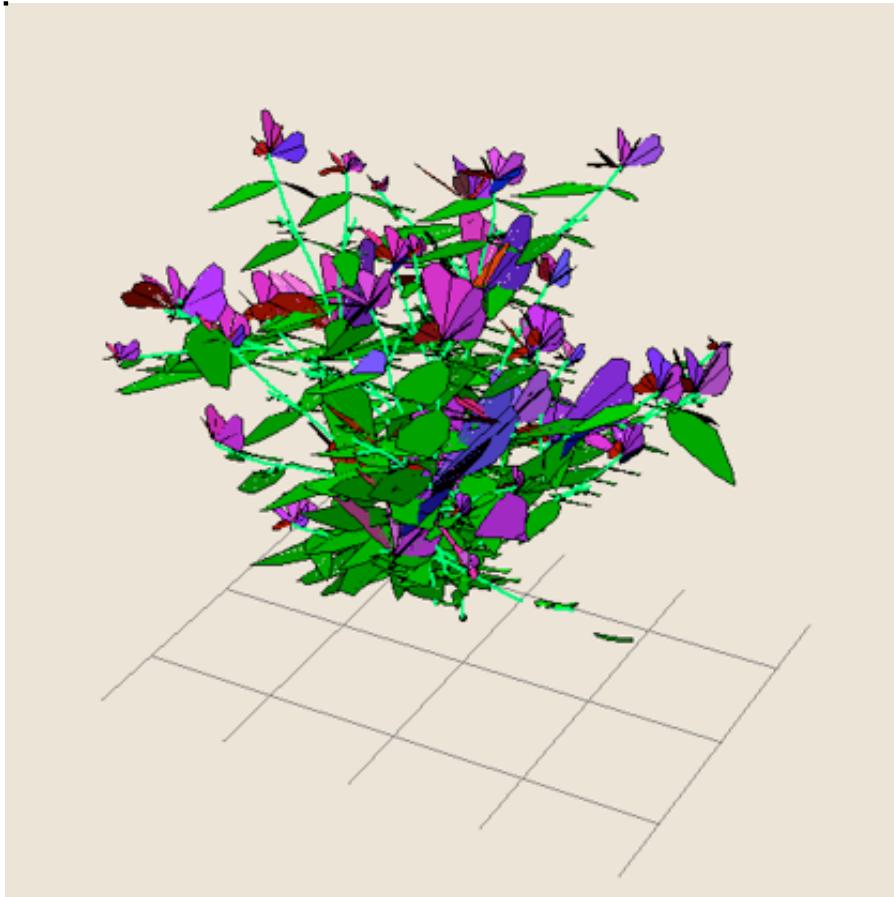
Iteration 7

Developmental Programs



Iteration 8

Developmental Programs



Iteration 9

ArtFlowers Encoded by L-systems

- Axiom: `sprout(4)`

- Sprout:

- $p_1: \text{sprout}(4) \rightarrow f \text{ stalk}(2) [\text{pd}(60) \text{ leaf}(0)] \text{ pu}(20) [\text{pu}(25) \text{ sprout}(0)] [\text{pd}(60) \text{ leaf}(0)] \text{ pd}(29) [\text{pu}(25) \text{ sprout}(2)] f \text{ stalk}(1) \text{ bloom}(0)$

- Sprout ripening:

- $p_2: \text{sprout}(t < 4) \rightarrow \text{sprout}(t+1)$

- Stalk elongation:

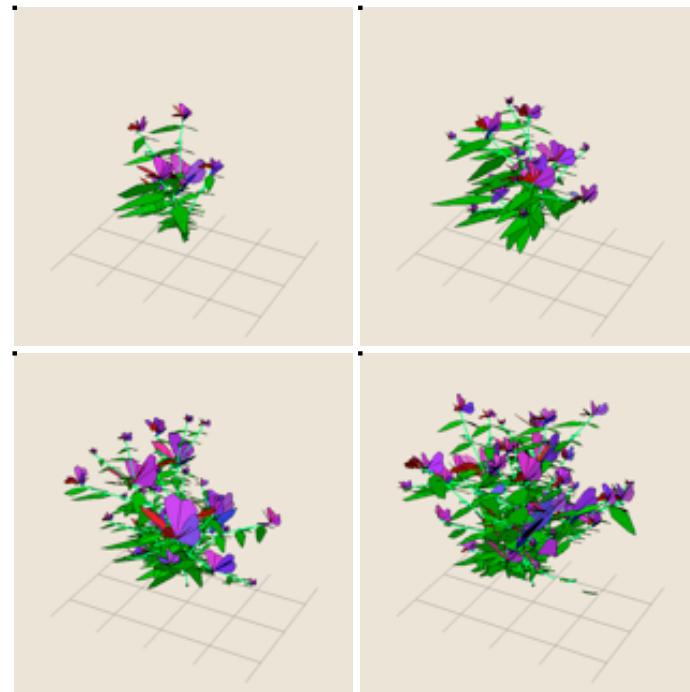
- $p_3: \text{stalk}(t > 0) \rightarrow f f \text{ stalk}(t-1)$

- Bloom growth and decay:

- $p_8: \text{bloom}(t) \rightarrow \text{bloom}(t+1)$
 - $p_9: \text{bloom}(7) \rightarrow \text{bloom}(1)$

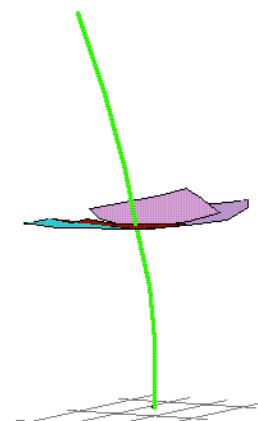
- Changing leaf sizes:

- $p_4: \text{leaf}(t) \rightarrow \text{leaf}(t+1.5)$
 - $p_5: \text{leaf}(t > 7) \rightarrow \text{Leaf}(7)$
 - $p_6: \text{Leaf}(t) \rightarrow \text{Leaf}(t-1.5)$
 - $p_7: \text{Leaf}(t < 2) \rightarrow \text{leaf}(0)$



Lychnis coronaria artificialis

- Axiom: `sprout(a) ; a = 3`
- Sprout with emerging stalk, blooms and leaves
 - `p1: sprout(a) -> f stalk(2) [pd(60) leaf(0)]`
 - `pu(20) [pu(25) sprout(0)]`
 - `[pd(60) leaf(0)] pd(29)`
 - `[pu(25) sprout(2)]`
 - `f stalk(1) bloom(0)`

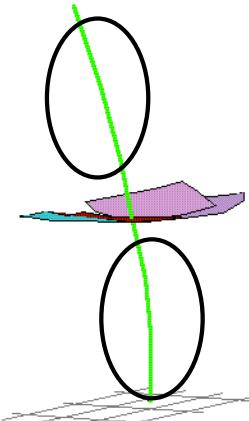


Iteration 1

Lychnis coronaria artificialis

- Axiom: `sprout(a)`
- Sprout with emerging stalk, blooms and leaves

- $p_1: \text{sprout}(a) \rightarrow [\text{stalk}(2) \text{ pd}(60) \text{ leaf}(0)]$
- $\quad \quad \quad \text{pu}(20) [\text{pu}(25) \text{ sprout}(0)]$
- $\quad \quad \quad [\text{pd}(60) \text{ leaf}(0)] \text{ pd}(29)$
- $\quad \quad \quad [\text{pu}(25) \text{ sprout}(2)]$
- $\quad \quad \quad [\text{stalk}(1) \text{ bloom}(0)]$

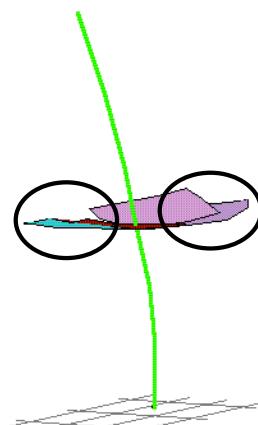


Iteration 1

Lychnis coronaria artificialis

- Axiom: `sprout(a)`
- Sprout with emerging stalk, blooms and leaves

- $p_1: \text{sprout}(a) \rightarrow f \text{ stalk}(2) [\text{pd}(60) \text{ leaf}(0)]$
- $\quad \quad \quad \text{pu}(20) [\text{pu}(25) \text{ sprout}(0)]$
- $\quad \quad \quad [\text{pd}(60) \text{ leaf}(0)] \text{ pd}(29)$
- $\quad \quad \quad [\text{pu}(25) \text{ sprout}(2)]$
- $f \text{ stalk}(1) \text{ bloom}(0)$

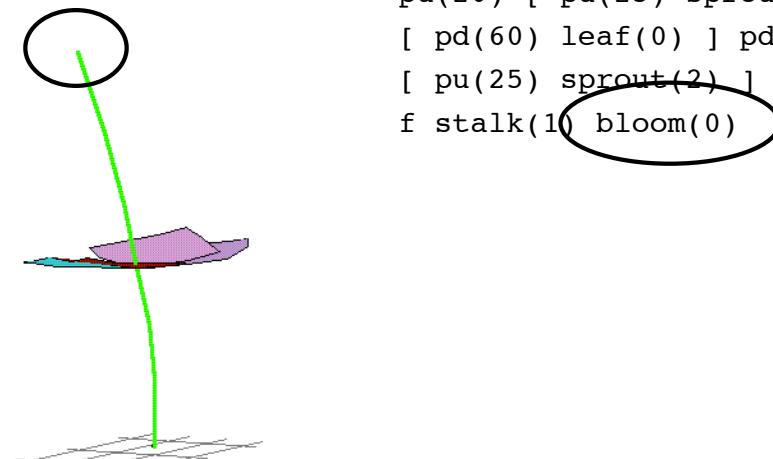


Iteration 1

Lychnis coronaria artificialis

- Axiom: sprout(a)
- Sprout with emerging stalk, blooms and leaves

- p1: sprout(a) -> f stalk(2) [pd(60) leaf(0)]
pu(20) [pu(25) sprout(0)]
[pd(60) leaf(0)] pd(29)
[pu(25) sprout(2)]
-
-
-
-



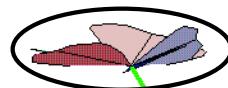
Iteration 1

Lychnis coronaria artificialis

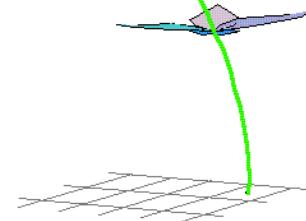
Axiom: `sprout(a)`

Sprout with emerging stalk, blooms and leaves

`p1: sprout(a) ->`



```
f stalk(2) [ pd(60) leaf(0) ]  
pu(20) [ pu(25) sprout(0) ]  
[ pd(60) leaf(0) ] pd(29)  
[ pu(25) sprout(2) ]  
f stalk(1) bloom(1)
```



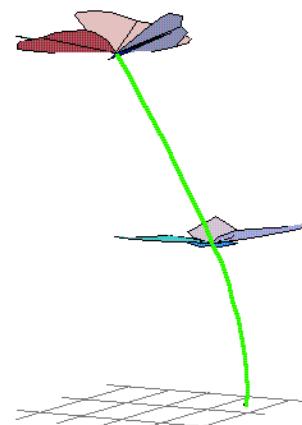
Iteration 2

Lychnis coronaria artificialis

Axiom: sprout(a)

Sprout with emerging stalk, blooms and leaves

p₁: sprout(a) →



```
f stalk(2) [ pd(60) leaf(0) ]  
pu(20) [ pu(85) sprout(0)  
[ pd(60) leaf(0) ] pd(29)  
[ pu(25) sprout(2) ]  
f stalk(1) bloom(1)
```

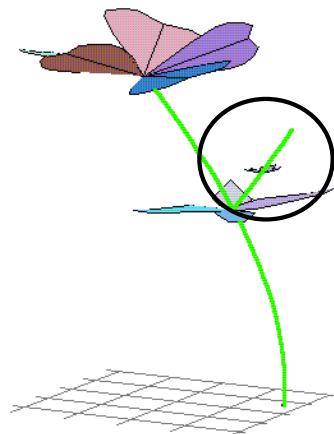
Iteration 2

Lychnis coronaria artificialis

Axiom: sprout(a)

Sprout with emerging stalk, blooms and leaves

p1: sprout(a) ->



```
f stalk(2) [ pd(60) leaf(0) ]
pu(20) [ pu(25) sprout(0) ]
[ pd(60) leaf(0) ] pd(29)
[ pu(25) f stalk(2) [ pd(60) leaf(0) ]
pu(20) [ pu(25) sprout(0) ]
[ pd(60) leaf(0) ] pd(29)
[ pu(25) sprout(2) ] f stalk(1) bloom(0)]
f stalk(1) bloom(1)
```

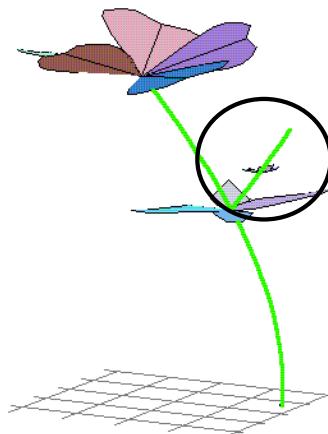
Iteration 3

Lychnis coronaria artificialis

Axiom: sprout(a)

Sprout with emerging stalk, blooms and leaves

p₁: sprout(a) →

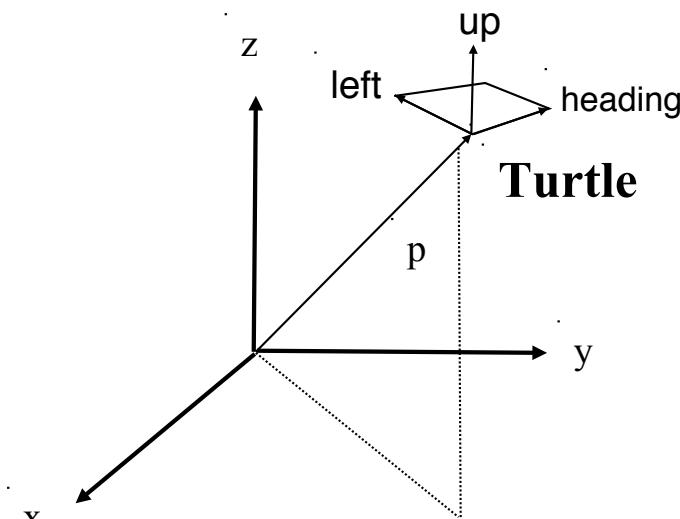


```
f stalk(2) [ pd(60) leaf(0) ]
pu(20) [ pu(25) sprout(0) ]
[ pd(60) leaf(0) ] pd(29)
[ pu(25) f stalk(2) [ pd(60) leaf(0) ]
pu(20) [ pu(25) sprout(0) ]
[ pd(60) leaf(0) ] pd(29)
[ pu(25) sprout(2) ] f stalk(1) bloom(0) ]
f stalk(1) bloom(1)
```

Iteration 3

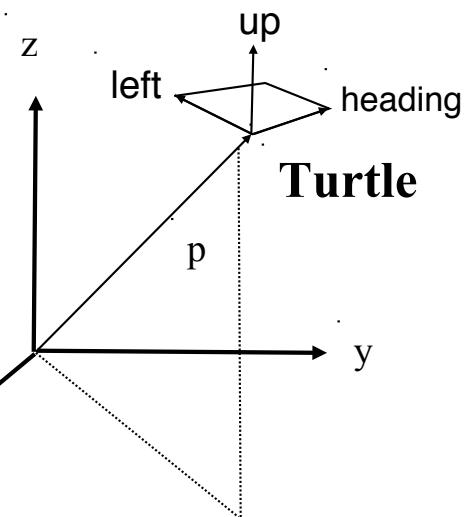
Turtle Interpretation

Position and Orientation

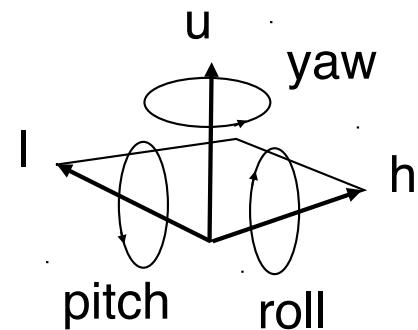


Turtle Interpretation

Position and Orientation



Changing Orientation

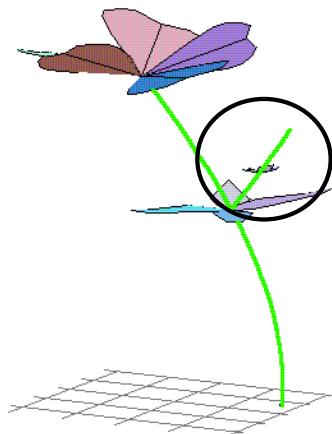


Lychnis coronaria artificialis

Axiom: sprout(a)

Sprout with emerging stalk, blooms and leaves

p₁: sprout(a) →



```
f stalk(2) [ pd(60) leaf(0) ]
pu(20) [ pu(25) sprout(0) ]
[ pd(60) leaf(0) ] pd(29)
[ pu(25) f stalk(2) [ pd(60) leaf(0) ]
pu(20) [ pu(25) sprout(0) ]
[ pd(60) leaf(0) ] pd(29)
[ pu(25) sprout(2) ] f stalk(1) bloom(0) ]
f stalk(1) bloom(1)
```

Iteration 3

ArtFlowers Encoded by L-systems

- Axiom: `sprout(4)`

- Sprout:

- $p_1: \text{sprout}(4) \rightarrow f \text{ stalk}(2) [\text{pd}(60) \text{ leaf}(0)] \text{ pu}(20) [\text{pu}(25) \text{ sprout}(0)] [\text{pd}(60) \text{ leaf}(0)] \text{ pd}(29) [\text{pu}(25) \text{ sprout}(2)] f \text{ stalk}(1) \text{ bloom}(0)$

- Sprout ripening:

- $p_2: \text{sprout}(t < 4) \rightarrow \text{sprout}(t+1)$

- Stalk elongation:

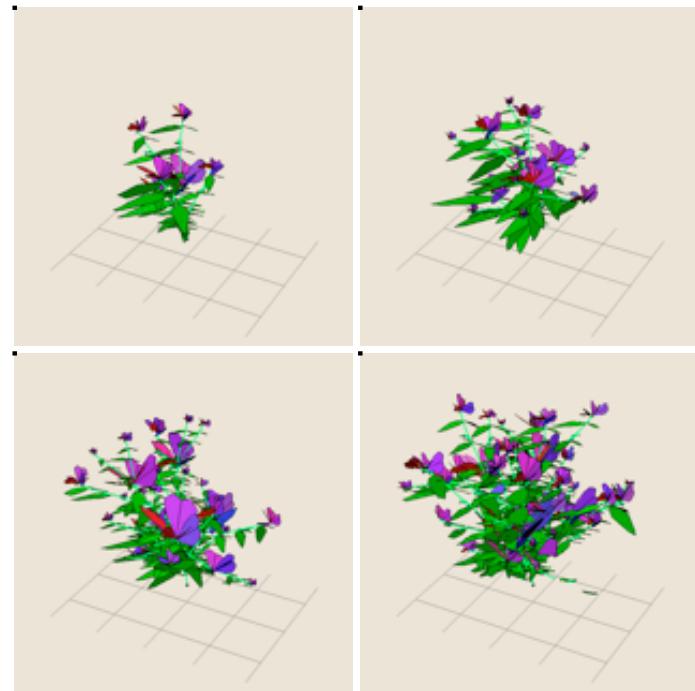
- $p_3: \text{stalk}(t > 0) \rightarrow f f \text{ stalk}(t-1)$

- Bloom growth and decay:

- $p_8: \text{bloom}(t) \rightarrow \text{bloom}(t+1)$
 - $p_9: \text{bloom}(7) \rightarrow \text{bloom}(1)$

- Changing leaf sizes:

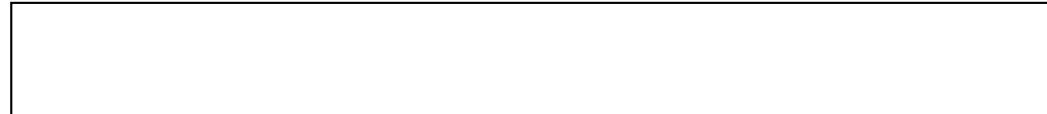
- $p_4: \text{leaf}(t) \rightarrow \text{leaf}(t+1.5)$
 - $p_5: \text{leaf}(t > 7) \rightarrow \text{Leaf}(7)$
 - $p_6: \text{Leaf}(t) \rightarrow \text{Leaf}(t-1.5)$
 - $p_7: \text{Leaf}(t < 2) \rightarrow \text{leaf}(0)$



Encoding L-Systems

- General form of an L-rule:

Left < Predecessor > Right  Successor



Encoding L-Systems

- General form of an L-rule:

Left < Predecessor > Right \rightarrow Successor

•

•

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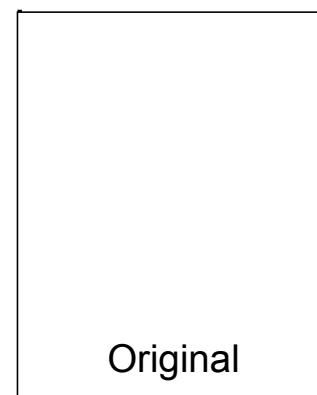
- Encoding by a symbolic expression:

```
LRule[  
    LEFT[Left], PRED[Predecessor],RIGHT[Right],  
    SUCC[Successor]  
]
```

Encoding L-Systems

- LSystem[
 - Axiom[...],
 - LRules[
 - LRule[...],
 - LRule[LEFT[*Left*],PRED[*Pred*],RIGHT[*Right*],SUCC[*Succ*]],
 - LRule[...], ...

ArtFlowers Gallery



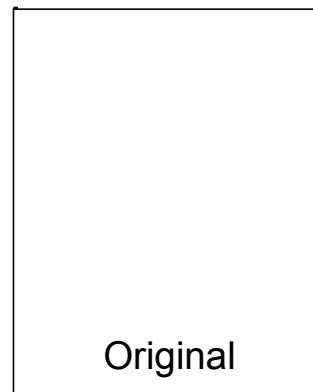
Original



Mutants



ArtFlowers Gallery

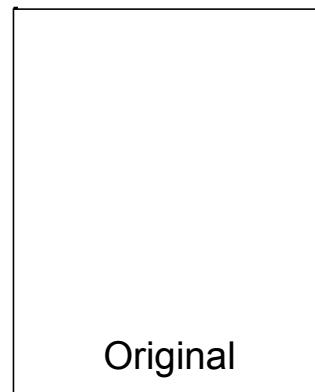


Original

Mutants



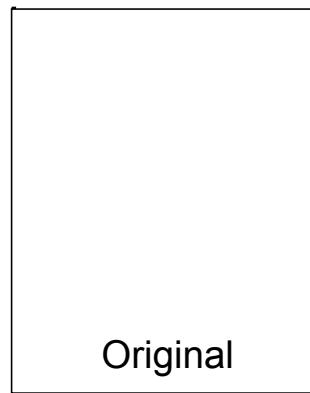
ArtFlowers Gallery



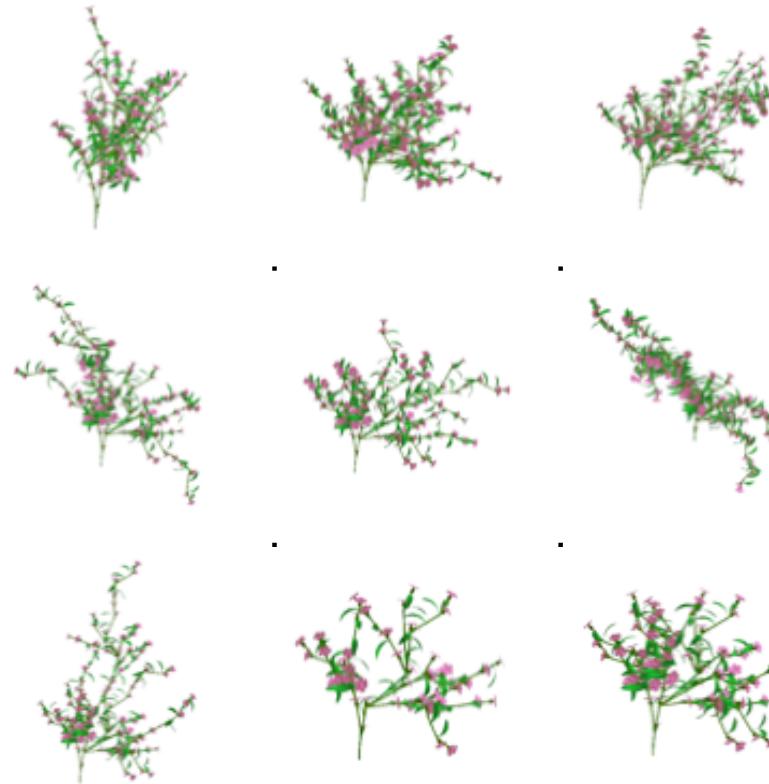
Original

Mutants

ArtFlowers Gallery



Original

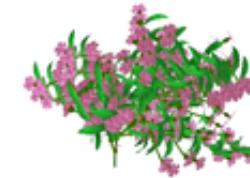
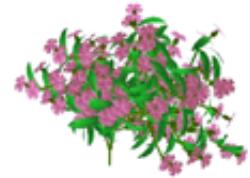


Mutants

ArtFlowers Gallery



Original

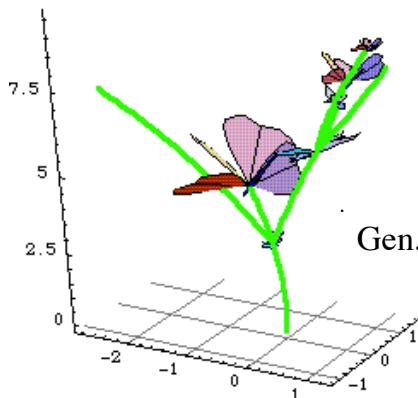


Mutants

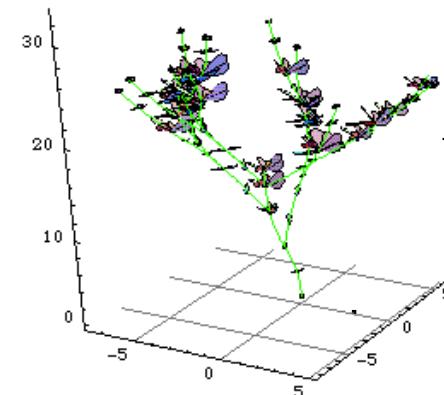
Visualizing Evolution and Ontogeny

Effects of Genetic Operators

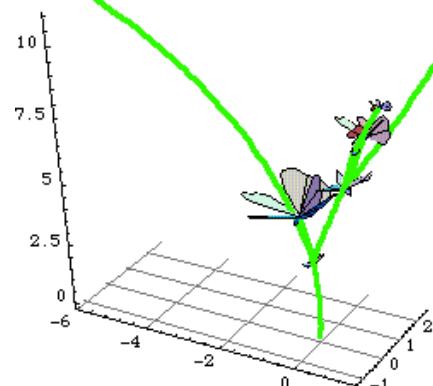
Effects of Genetic Operators



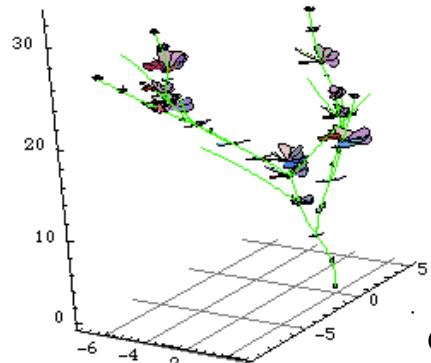
Gen. 1



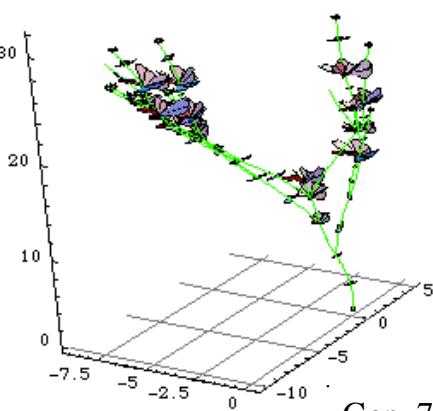
Gen. 8



Gen. 4



Gen. 6



Gen. 7

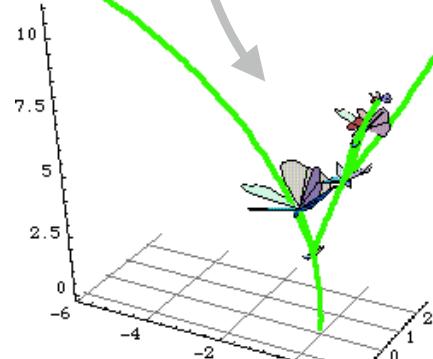
Effects of Genetic Operators

```

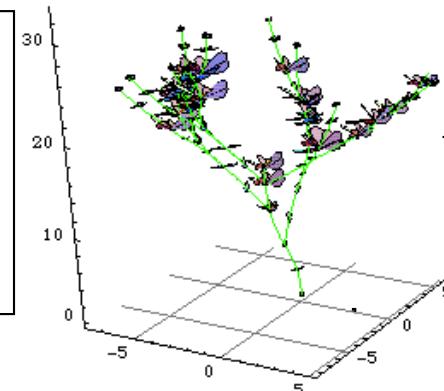
LSystem[AXiom[a4]
LRULES{
LRule[LEFT], PRED[a4], RIGHT],
SUCC[SEQ[SEQ[], SEQ[]]],
STACK[pd[60], 0], SEQ[0, 0],
STACK[pd[20], a3], SEQ[m[90]],
SEQ[], RR[17], [2],
STACK[pd[60], 0], SEQ[0, 0],
STACK[pd[20], a2], SEQ[],
SEQ[1], m[0],
LRule[LEFT], PRED[a1/x4], RIGHT], SUCC[a1+]],
LRule[LEFT], PRED[m[0], RIGHT], SUCC[m[1]],
LRule[LEFT], PRED[a2], RIGHT], SUCC[STACK[a4], YR[34]],
LRule[LEFT], PRED[0], RIGHT], SUCC[STACK[YR[18], YR[18]]]
}

```

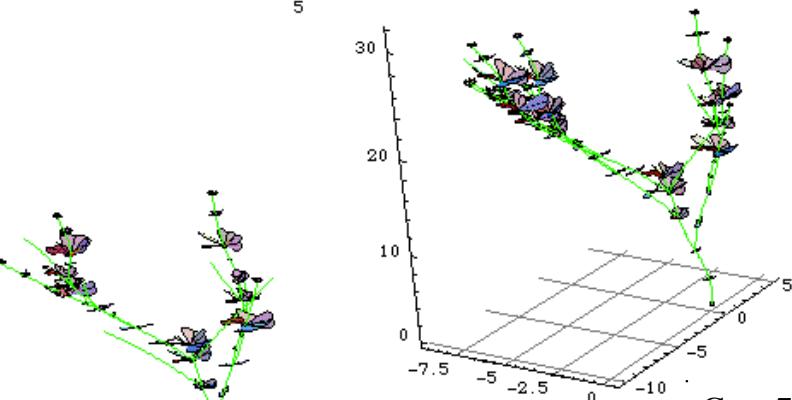
Duplication



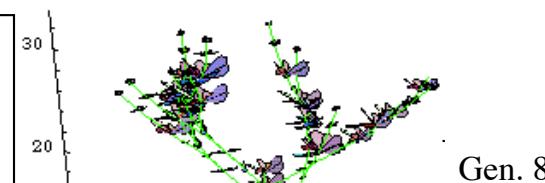
Gen. 4



Gen. 6



Gen. 7



Gen. 8

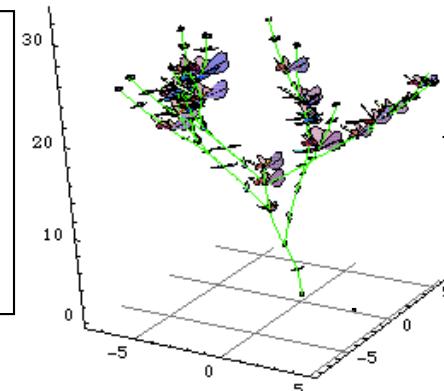
Effects of Genetic Operators

```
LSystem[AXIOM[a4]
LRULES[
LRule[LEFT], PRED[a4], RIGHT],
SUCC[SEQ[SEQ[], SEQ[2]],
STACK[pd[60], 0], SEQ[90]],
STACK[pd[20], a3], SEQ[90],
SEQ[], RR[17], [2],
STACK[pd[60], 0], SEQ[90],
STACK[pd[20], a2], SEQ[],
SEQ[1], m[0]],
LRule[LEFT], PRED[a4], RIGHT], SUCC[a1+]],
LRule[LEFT], PRED[m[0], RIGHT], SUCC[m[1]],
LRule[LEFT], PRED[a2], RIGHT], SUCC[STACK[a4], YR[34]],
LRule[LEFT], PRED[a0], RIGHT], SUCC[STACK[YR[18], YR[18]]]]
```

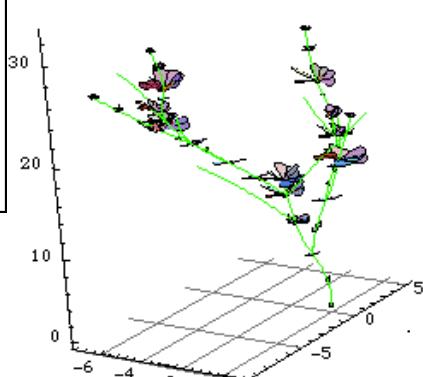
Duplication

```
LSystem[AXIOM[a4]
LRULES[
LRule[LEFT], PRED[a4], RIGHT],
SUCC[SEQ[SEQ[], SEQ[2]],
STACK[pd[60], 0], SEQ[90]],
STACK[pd[20], a3], SEQ[90],
SEQ[], RR[17], RR[17], [2],
STACK[pd[60], 0], SEQ[90],
STACK[pd[20], a2], SEQ[],
SEQ[1], m[0]],
LRule[LEFT], PRED[a4], RIGHT], SUCC[a1+]],
LRule[LEFT], PRED[m[0], RIGHT], SUCC[m[1]],
LRule[LEFT], PRED[a2], RIGHT], SUCC[STACK[a4][4], YR[34]],
LRule[LEFT], PRED[a0], RIGHT], SUCC[STACK[YR[18], YR[18]]]]
```

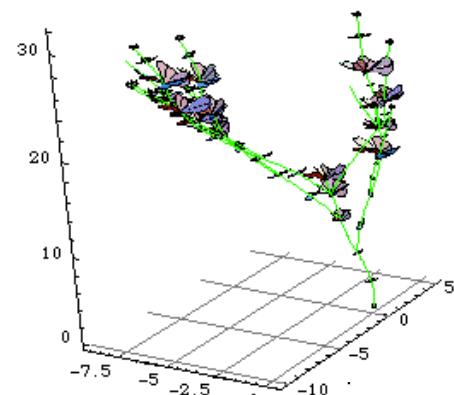
Gen. 4



Gen. 8



Gen. 6



Gen. 7

**EVOLUTIONARY
Swarm Design**

Christian Jacob, University of Calgary

Effects of Genetic Operators

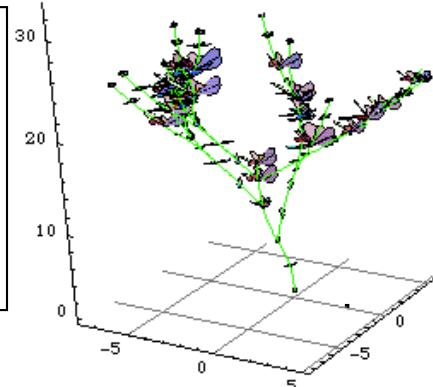
```

LSystem[AXIOM[a4]]
LRULES[
    LRule[LEFT], PRED[a4], RIGHT],
    SUCC[SEQ[SEQ[], SEQ[]]],
    STACK[pd[60], 0], SEQ[r90],
    STACK[pd[20], a3], SEQ[r90],
    SEQ[], RR[17], [2],
    STACK[pd[60], 0], SEQ[r90],
    STACK[pd[20], a2], SEQ[],
    SEQ[], m[]],
    LRule[LEFT], PRED[a1/a4], RIGHT], SUCC[a1+[]]
]

LRule[LEFT], PRED[m6], RIGHT], SUCC[m1],
LRule[LEFT], PRED[a2], RIGHT], SUCC[STACK[a4], YR[34]],
LRule[LEFT], PRED[a0], RIGHT], SUCC[STACK[YR[18], YR[18]]]

```

Duplication



Gen. 8

```

LSystem[AXIOM[a4]]
LRULES[
    LRule[LEFT], PRED[a4], RIGHT],
    SUCC[SEQ[SEQ[], SEQ[]]],
    STACK[pd[60], 0], SEQ[r90],
    STACK[pd[20], a3], SEQ[r90],
    SEQ[], RR[17], RR[17], [2],
    STACK[pd[60], 0], SEQ[r90],
    STACK[pd[20], a2], SEQ[],
    SEQ[], m[]],
    LRule[LEFT], PRED[a1/a4], RIGHT], SUCC[a1+[]]
]

LRule[LEFT], PRED[m6], RIGHT], SUCC[m1],
LRule[LEFT], PRED[a2], RIGHT], SUCC[STACK[a4], YR[34]],
LRule[LEFT], PRED[a0], RIGHT], SUCC[STACK[YR[18], YR[18]]]

```

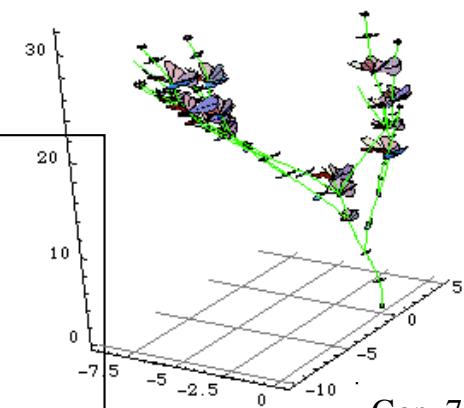
Duplication
Mutation

```

LSystem[AXIOM[a4]]
LRULES[
    LRule[LEFT], PRED[a4], RIGHT],
    SUCC[SEQ[SEQ[], SEQ[]]],
    STACK[pd[60], 0],
    SEQ[SEQ[], SEQ[]],
    STACK[pd[60], 0], SEQ[r90],
    STACK[pd[20], a3], SEQ[r90],
    SEQ[r3/a4], RL[30],
    STACK[pd[60], 0], SEQ[r90],
    STACK[pd[20], a2], SEQ[],
    SEQ[a1/a1], m[]],
    STACK[pd[20], a3], SEQ[r90],
    SEQ[r0], RR[17], RR[17], [2],
    STACK[pd[60], 0], SEQ[r90],
    STACK[pd[20], a2], SEQ[],
    SEQ[a1/a1], m[]],
    LRule[LEFT], PRED[a1/a4], RIGHT], SUCC[a1+[]]
]

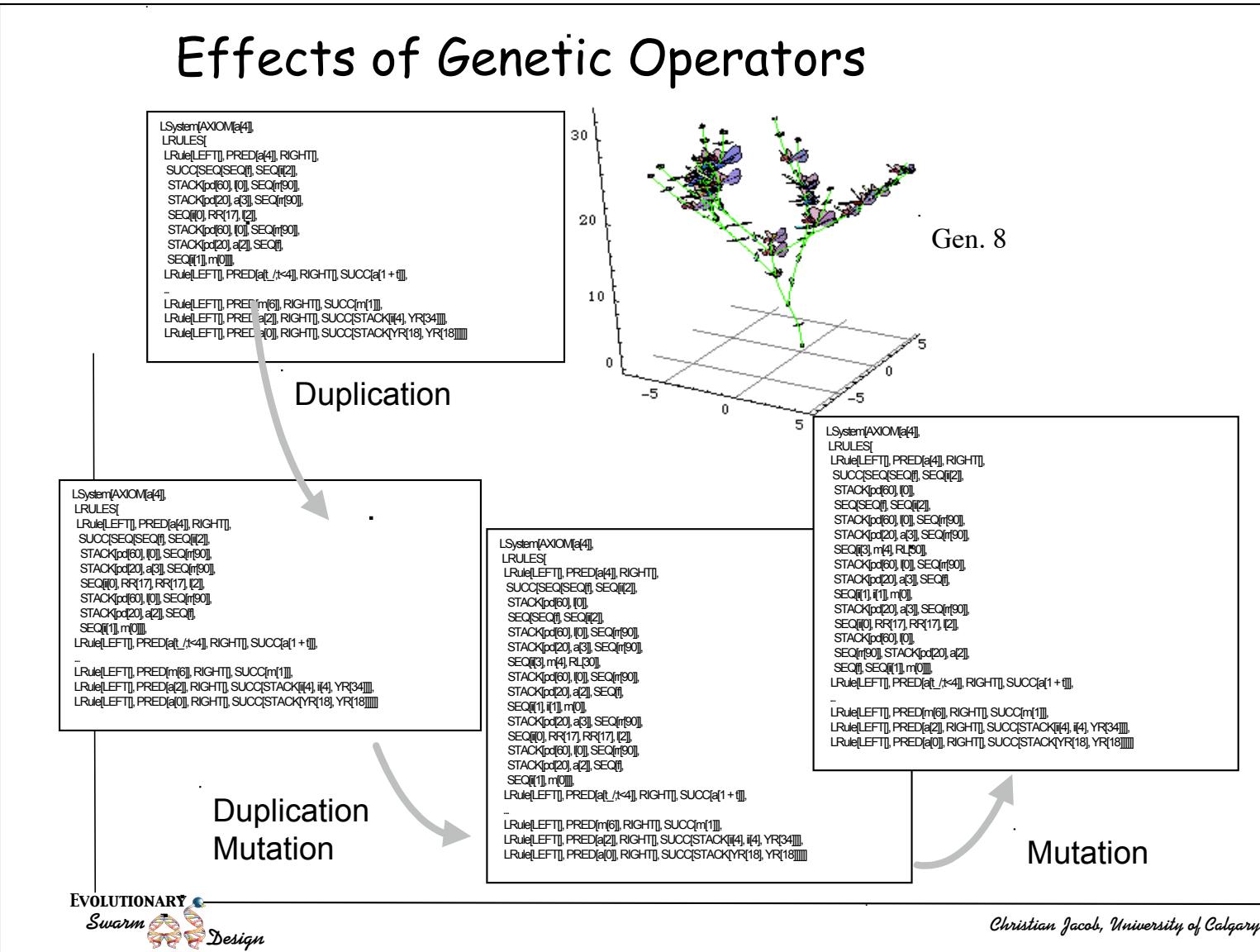
LRule[LEFT], PRED[m6], RIGHT], SUCC[m1],
LRule[LEFT], PRED[a2], RIGHT], SUCC[STACK[a4], YR[34]],
LRule[LEFT], PRED[a0], RIGHT], SUCC[STACK[YR[18], YR[18]]]

```

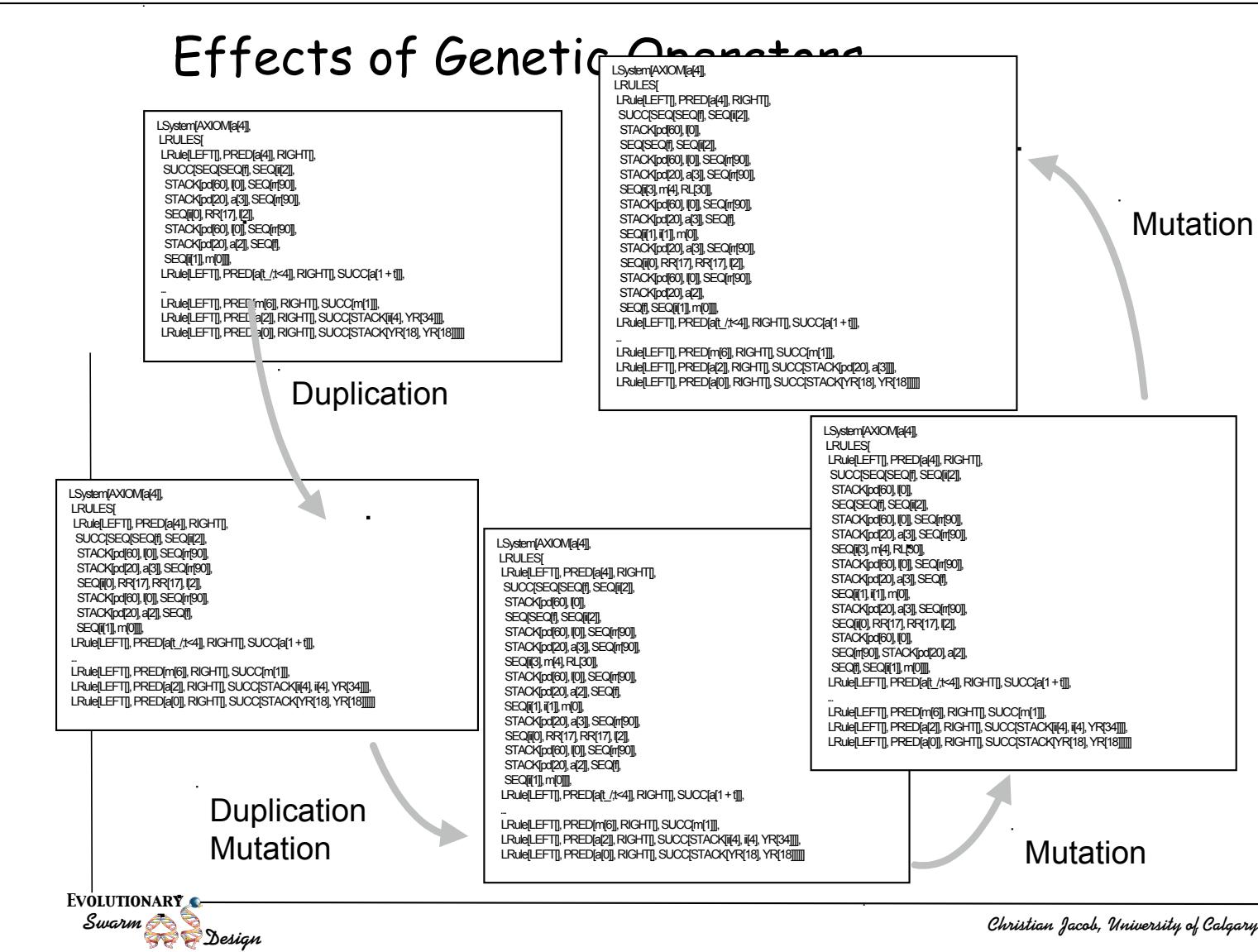


Gen. 7

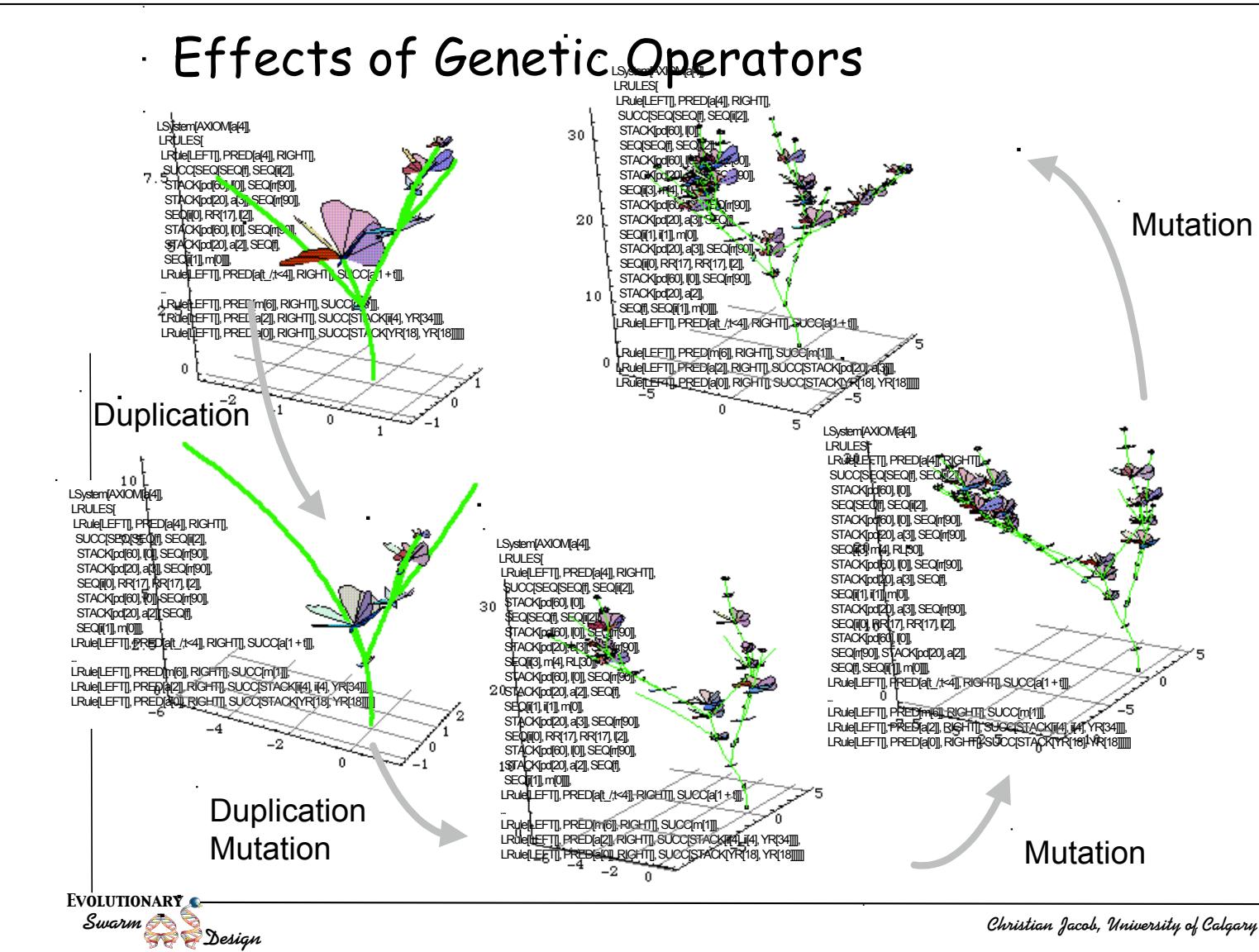
Effects of Genetic Operators



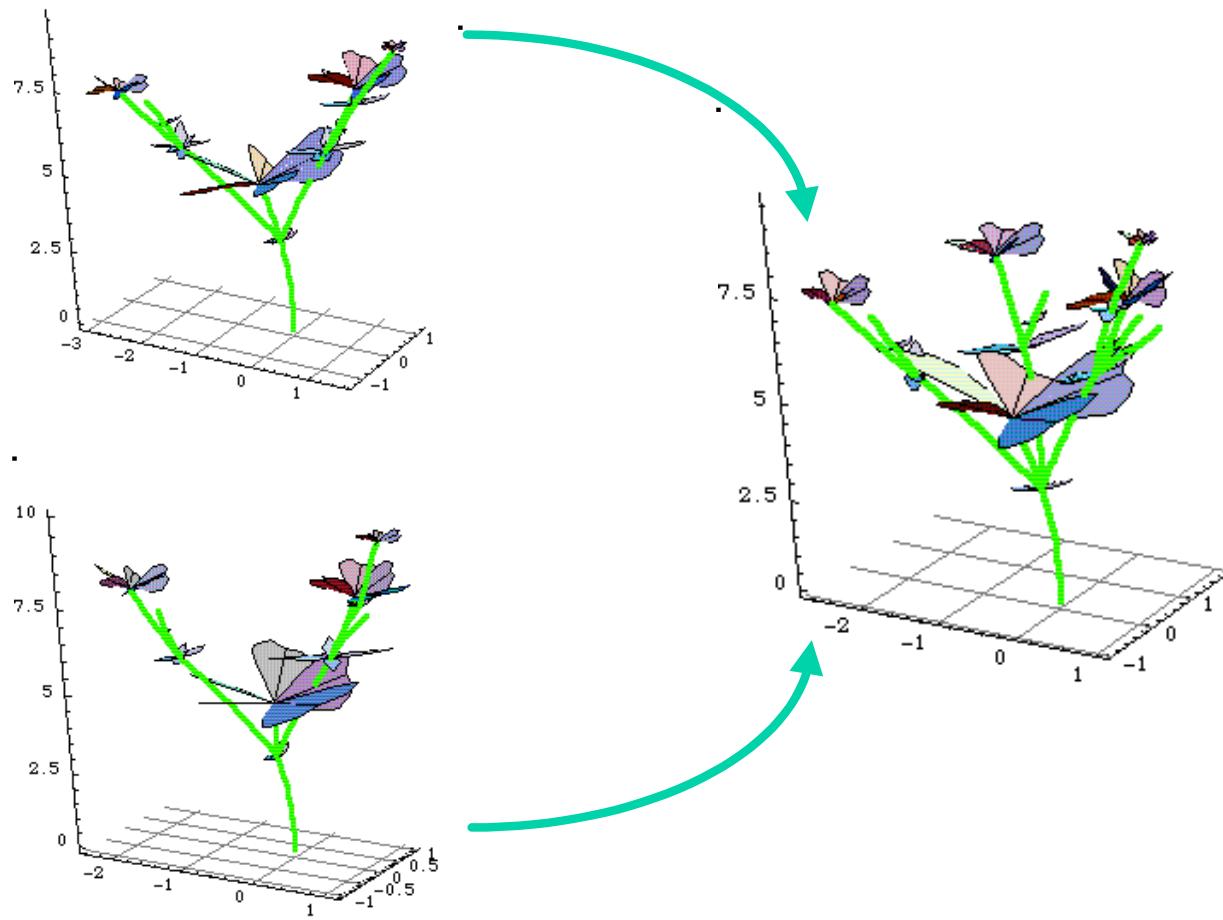
Effects of Genetic Operators



Effects of Genetic Operators

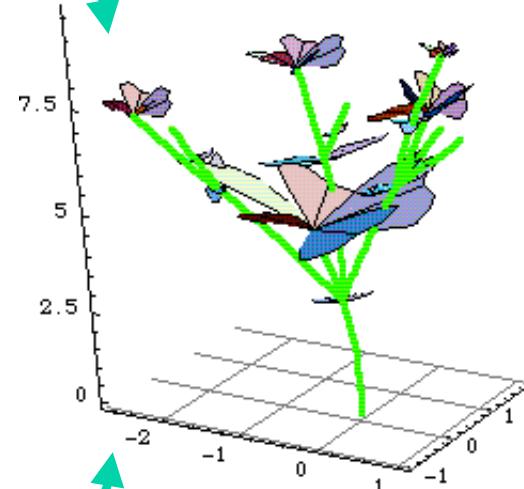
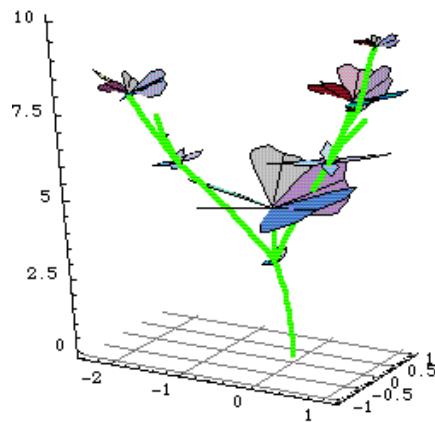


Effects of Recombination



Effects of Recombination

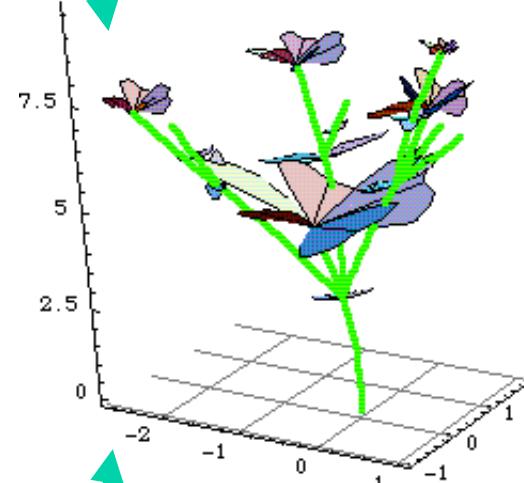
```
LSystem[AXIOM[a[4]],  
LRULES[  
LRule[LEFT[], PRED[a[4]], RIGHT[],  
SUCC[SEQ[SEQ[f], SEQ[ii[2]]],  
STACK[pd[20], a[2]], SEQ[rr[90]]],  
STACK[pd[20], a[3]], SEQ[rr[90]],  
SEQ[i[2]], STACK[pd[60], i[0]],  
SEQ[rr[90]], STACK[pd[20], a[2]],  
SEQ[f], SEQ[ii[1]], m[0]]],  
...]
```



Effects of Recombination

```
LSystem[AXIOM[a[4]],  
LRULES[  
LRule[LEFT[], PRED[a[4]], RIGHT[],  
SUCC[SEQ[SEQ[f], SEQ[ii[2]]],  
STACK[pd[20], a[2]], SEQ[rr[90]]],  
STACK[pd[20], a[3]], SEQ[rr[90]],  
SEQ[i[2]], STACK[pd[60], I[0]],  
SEQ[rr[90]], STACK[pd[20], a[2]],  
SEQ[f], SEQ[ii[1]], m[0]]],  
...]
```

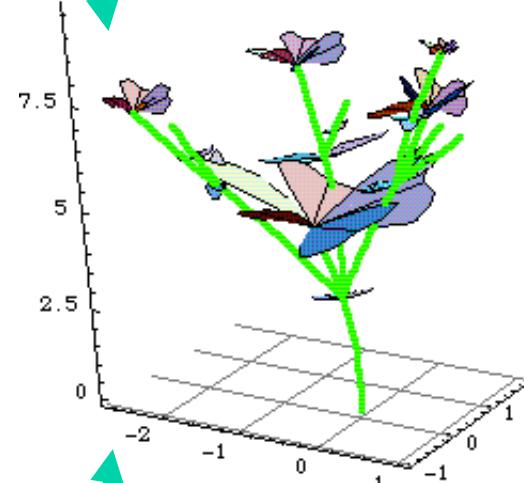
```
LSystem[AXIOM[a[4]],  
LRULES[  
LRule[LEFT[], PRED[a[4]], RIGHT[],  
SUCC[SEQ[SEQ[f], SEQ[ii[2]]],  
STACK[pd[60], I[0]], SEQ[rr[90]]],  
STACK[pd[20], a[3]], SEQ[rr[90]],  
SEQ[YR[10]], STACK[pd[60], I[0]],  
SEQ[rr[90]], STACK[pd[60], I[0]],  
SEQ[f], SEQ[ii[1]], m[0]]],  
...]
```



Effects of Recombination

```
LSystem[AXIOM[a[4]],  
LRULES[  
LRule[LEFT[], PRED[a[4]], RIGHT[],  
SUCC[SEQ[SEQ[f], SEQ[ii[2]]],  
STACK[pd[20], a[2]], SEQ[rr[90]]],  
STACK[pd[20], a[3]], SEQ[rr[90]],  
SEQ[i[2]], STACK[pd[60], I[0]],  
SEQ[rr[90]], STACK[pd[20], a[2]],  
SEQ[f], SEQ[ii[1]], m[0]]],  
...]
```

```
LSystem[AXIOM[a[4]],  
LRULES[  
LRule[LEFT[], PRED[a[4]], RIGHT[],  
SUCC[SEQ[SEQ[f], SEQ[ii[2]]],  
STACK[pd[60], I[0]], SEQ[rr[90]]],  
STACK[pd[20], a[3]], SEQ[rr[90]],  
SEQ[YR[10]], STACK[pd[60], I[0]],  
SEQ[rr[90]], STACK[pd[60], I[0]],  
SEQ[f], SEQ[ii[1]], m[0]]],  
...]
```



Effects of Recombination

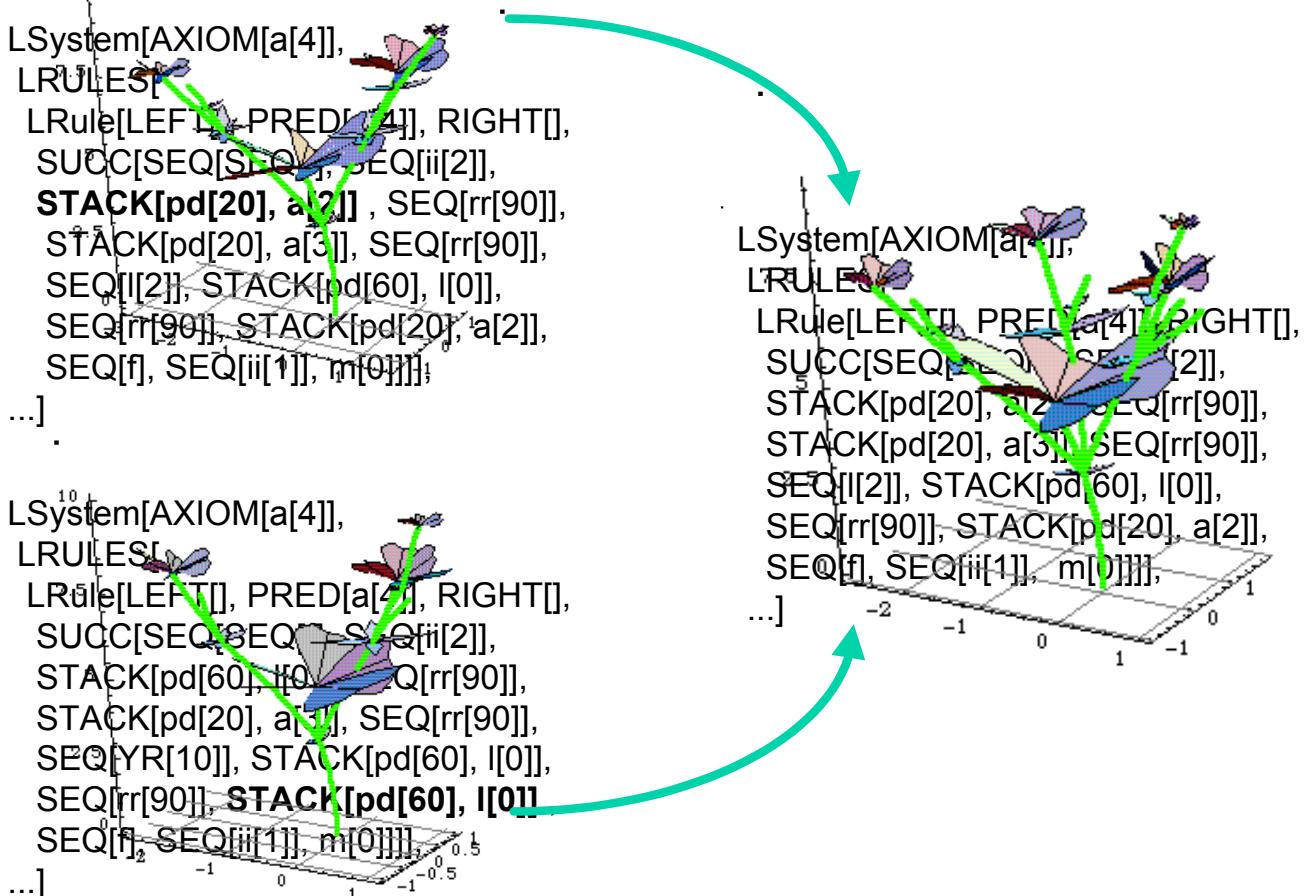
```
LSystem[AXIOM[a[4]],  
LRULES[  
LRule[LEFT[], PRED[a[4]], RIGHT[],  
SUCC[SEQ[SEQ[f], SEQ[ii[2]]],  
STACK[pd[20], a[2]] , SEQ[rr[90]],  
STACK[pd[20], a[3]], SEQ[rr[90]],  
SEQ[ii[2]], STACK[pd[60], l[0]],  
SEQ[rr[90]], STACK[pd[20], a[2]],  
SEQ[f], SEQ[ii[1]], m[0]]],  
...]
```

```
LSystem[AXIOM[a[4]],  
LRULES[  
LRule[LEFT[], PRED[a[4]], RIGHT[],  
SUCC[SEQ[SEQ[f], SEQ[ii[2]]],  
STACK[pd[60], l[0]], SEQ[rr[90]],  
STACK[pd[20], a[3]], SEQ[rr[90]],  
SEQ[YR[10]], STACK[pd[60], l[0]],  
SEQ[rr[90]], STACK[pd[60], l[0]],  
SEQ[f], SEQ[ii[1]], m[0]]],  
...]
```

```
LSystem[AXIOM[a[4]],  
LRULES[  
LRule[LEFT[], PRED[a[4]], RIGHT[],  
SUCC[SEQ[SEQ[f], SEQ[ii[2]]],  
STACK[pd[20], a[2]], SEQ[rr[90]],  
STACK[pd[20], a[3]], SEQ[rr[90]],  
SEQ[ii[2]], STACK[pd[60], l[0]],  
SEQ[rr[90]], STACK[pd[20], a[2]],  
SEQ[f], SEQ[ii[1]], m[0]]],  
...]
```

0 -1
1

Effects of Recombination



References

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- Koza, J. R. (1992). Genetic Programming: On the Programming of Computers by Means of Natural Selection. Cambridge, MA, MIT Press.
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- Jacob, C. (2001). Illustrating Evolutionary Computation with Mathematica. San Francisco, CA, Morgan Kaufmann Publishers (Chapters 7 and 8).
- Prusinkiewicz, P. and A. Lindenmayer (1990). The Algorithmic Beauty of Plants. New York, Springer.